



## **Sorting on GPUs**

**Revisiting some algorithms from lecture 6:**

**Some not-so-good sorting approaches**

**Bitonic sort**

**QuickSort**

**Concurrent kernels and recursion**



## **Adapt to parallel algorithms**

**Many sorting algorithms are highly sequential**

**Suitable for parallel implementation?**

- **Data driven execution**
- **Data independent execution**



## **Data driven execution**

**Computing pattern depends on data**

**Usually harder to parallelize!**

**Example: QuickSort.**



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## **Data independent execution**

**Known computing pattern**

**Easier to parallelize - always the same plan**

**Example: Bitonic sort**



## **Bubble sort**

**Loop through data, compare neighbors**

**Extremely sequential**

**Inefficient**

**Parallel version: Bubble sort with odd-even transposition method**

**Compare all items pairwise**

**Two phases, "odd phase" and "even phase" (shifted one step"**

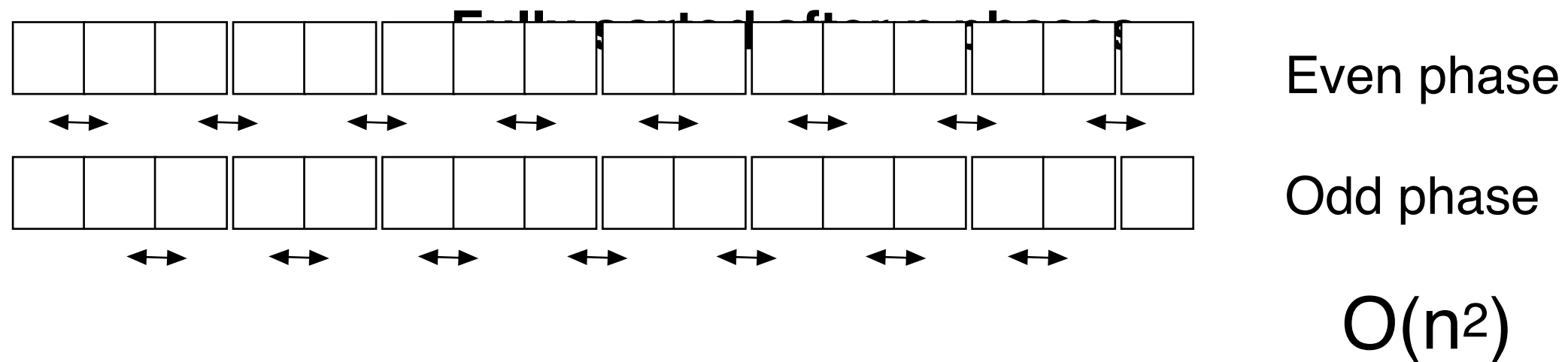


## Bubble sort, parallel version

Bubble sort with odd-even transposition method

Compare all items pairwise

Two phases, "odd phase" and "even phase" (shifted one step")





## **Suitable for GPU?**

**Not as bad as it seems at first look:**

- **Data independent**
  - **Excellent locality**
  - **Pretty good possibilities to use shared memory (but with some costly transfers at edges between blocks). Thus close to optimal in global memory transfers.**
  - **But certainly not optimal at very large sizes**
- ”Better” algorithms don’t necessary beat this all that easily!**



## **Rank sort**

**Count number of items that are smaller**

**Easy to parallelize:**

- **One thread per item**
- **Loop through entire data**
- **Store in index decided from count of number of smaller items.**





## **Suitable for GPU?**

**Again, not as bad as it seems at first look:**

- **Data independent**
- **Excellent locality - especially good for broadcasting (e.g. constant memory). Also suitable for shared memory.**
  - **Again,  $O(n^2)$ : Will grow at very large sizes**

**Two bad ones that are not quite as bad as they seem.**

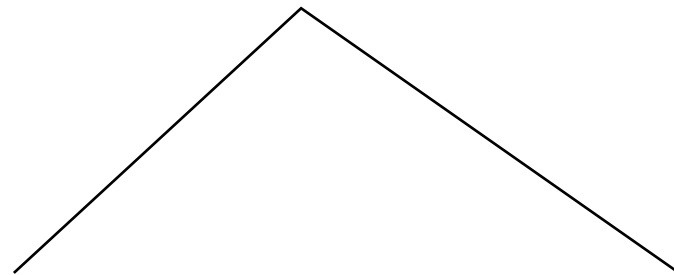
**$N$  parallel iterations may beat  $N \log N$  sequential ones!**



## **Bitonic sort**

**(As described in lecture 6)**

**Bitonic set: Two monotonic parts in different direction.**





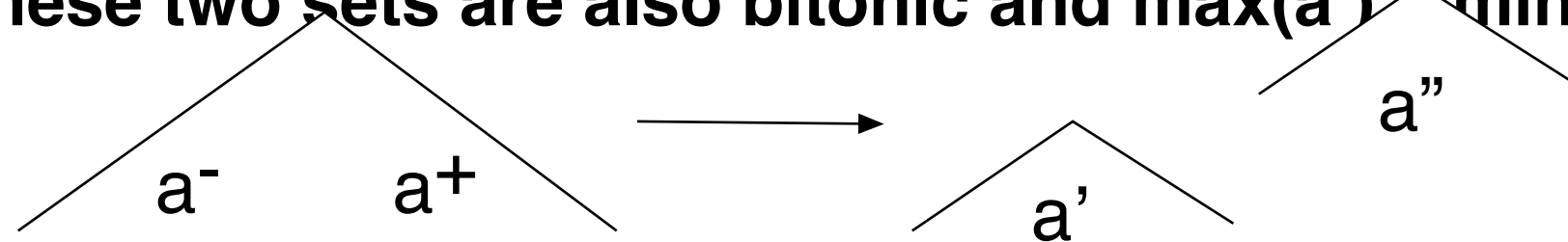
## Bitonic sort

**(According to Batcher:) Let  $a$  be a bitonic set with a maximum at  $k$ , consisting of two monotonic parts, one increasing,  $a^-$  (from item 1 to  $k$ ) and one decreasing,  $a^+$  ( $k+1$  to  $n$ )**

**Then two new sets can be constructed as**

$$a' = \min(a_1, a_{k+1}), \min(a_2, a_{k+2}) \dots$$
$$a'' = \max(a_1, a_{k+1}), \max(a_2, a_{k+2}) \dots$$

**These two sets are also bitonic and  $\max(a') \leq \min(a'')$ !**





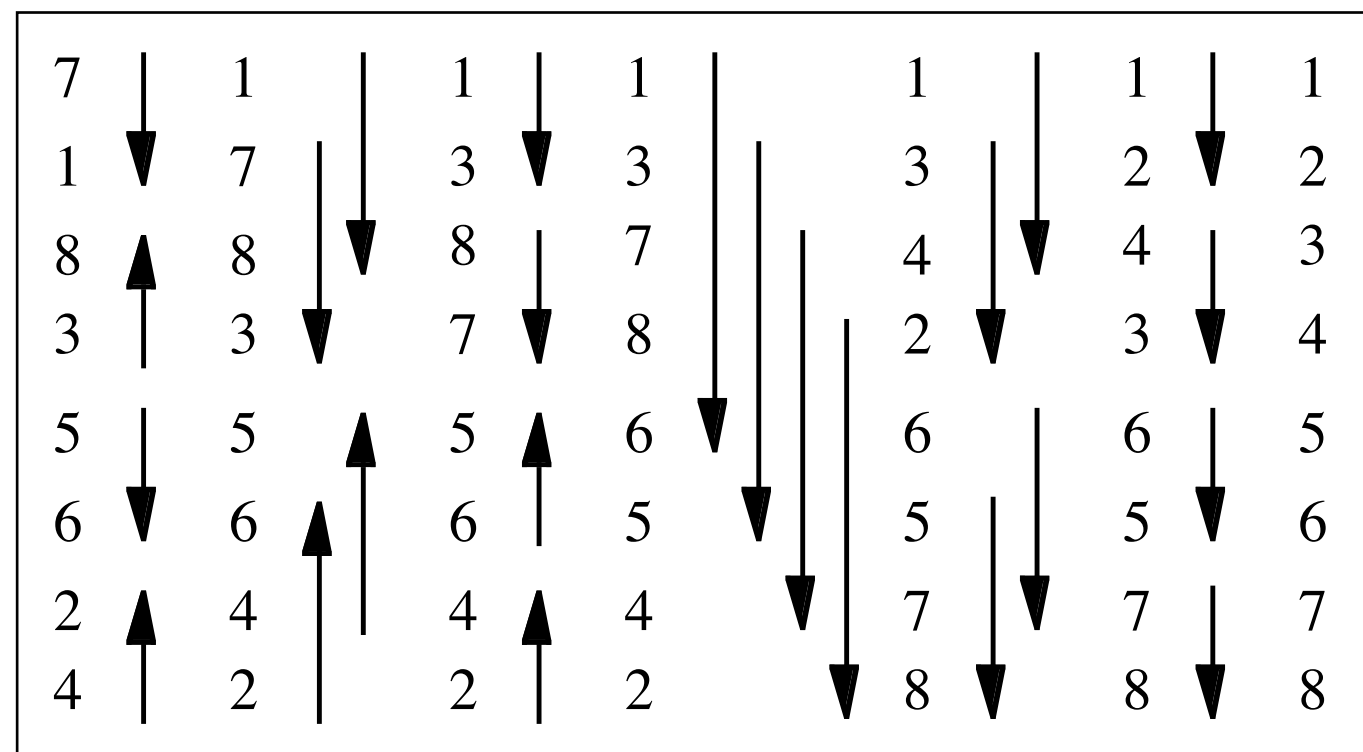
## **Bitonic sort by divide-and-conquer**

**Bitonic sort works on a bitonic sequence:  
partially sorted**

**The parts must be sorted. Sort them by  
bitonic sort!**



## Bitonic sort example



Bitonic sort of smaller part

Reverse parts (bitonic merge)

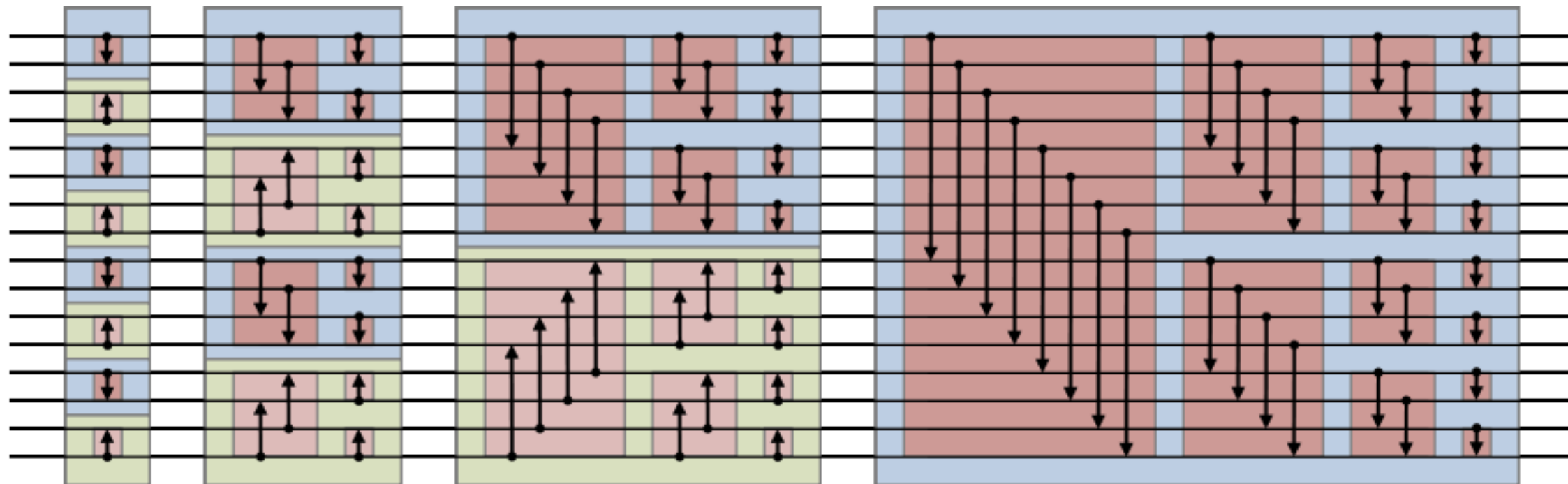
Bitonic sort of main part

Reverse parts (bitonic merge)



# Bigger example

The problem scales nicely, uniformly



More stages gives longer stages

(Image from Wikipedia)



# **Get those steps right**

**Step length**

**Step direction**

**Comparison direction**

**Calculated from stage number and stage  
length**



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# **Code examples**

**Sequential**

**Recursive example**

**Iterative example**





## **Bitonic sort**

- **Data independent, no worst case**
  - **Fast:  $O(n \cdot \log^2 n)$  (Why?)**
  - **Good locality in some parts**
- but**
- **Big leaps in addressing for some parts**



## **What about those big leaps?**

**Small leaps: Can be computed within one block.  
Shared memory friendly.**

**Big leaps (>number of threads/block): No  
synchronization possible between blocks!**

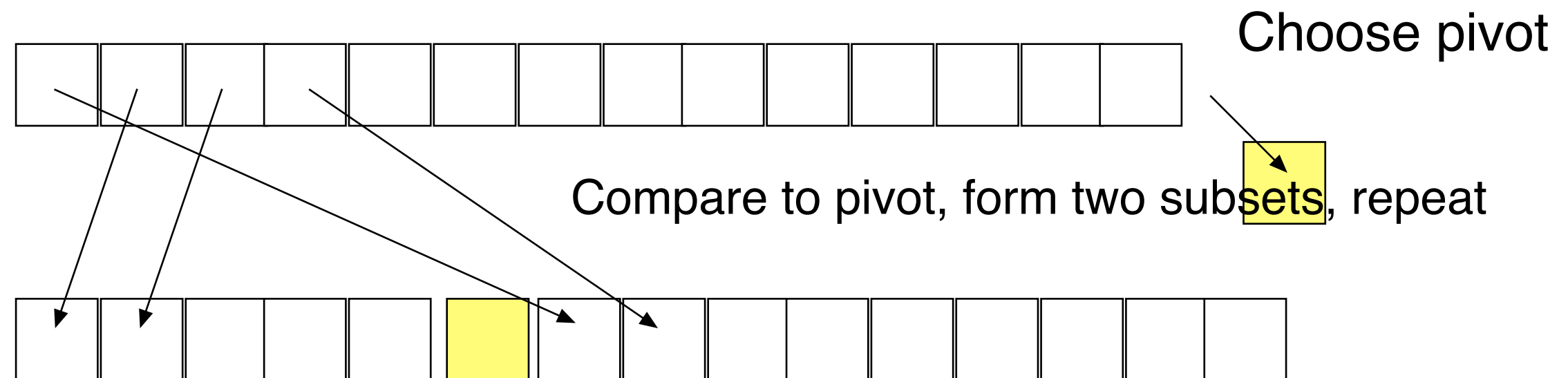
**But we *must* synchronize!**

**-> multiple kernel runs!**



# QuickSort

**Very popular algorithm for sequential implementation**



Data driven, data dependent reorganization, non-uniform

Fancy name - nobody expect QuickSort to be nothing but optimal



# QuickSort is

**Fast:  $O(n \cdot \log n)$  in typical cases**

**$O(n^2)$  in the worst case**

**Data driven, data dependent reorganization, non-uniform**

**Fancy name - nobody expects QuickSort to be nothing  
but optimal**



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# **QuickSort on GPU**

**Initially ignored as impractical**

**CUDA implementations exist**

**Data driven approaches increasingly suitable as  
GPUs become more flexible**



# Parallel QuickSort

Several stages to consider:

- **Pivot selection. Usually just grab one.**
  - **Comparisons**
  - **Partitioning**
- **Concatenate result**



## Pivot selection

**If we could always pick a pivot that splits the data in half...**





**but you can't do that without sorting! But how about a random one?**



**There is a worst case caused by bad pivots. Live with it!**





# Comparisons

**Easy to parallelize**

**One thread per comparison not unreasonable!  
(GPUs don't have a problem with many threads!)**

**No problem!**



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# Partitioning

**The big problem!**

**Sequential partitioning: Bad!**

**Parallel partitioning 1: Atomic fetch & increment.  
(GPUs have atomics!)**

**Parallel partitioning 2: Divide and conquer**



# Recursion

**GPUs can't do recursion efficiently... or can they?**

**New in Kepler: *Concurrent kernels***

**Not only a matter of launching kernels from CPU!**

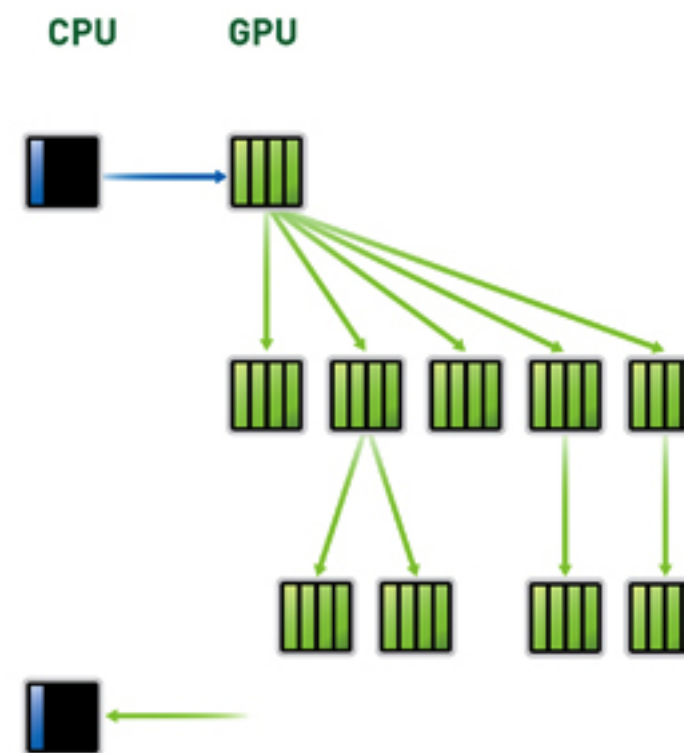
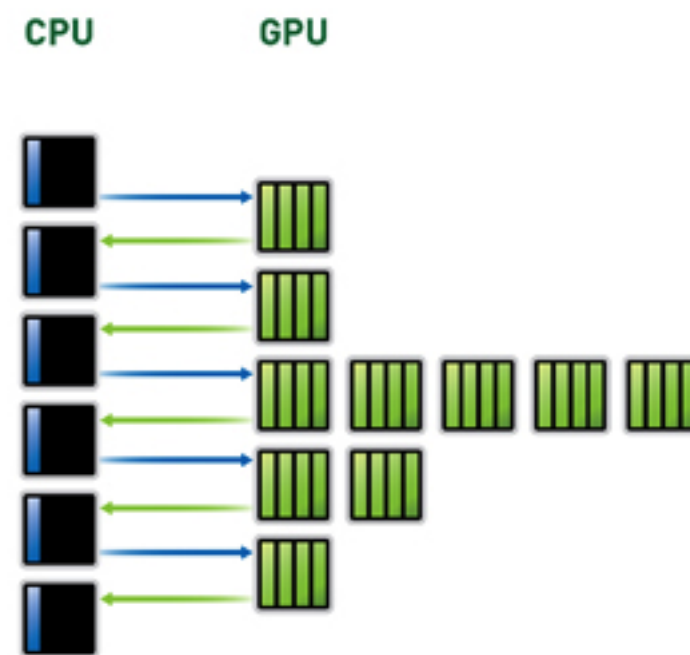
**A kernel can spawn new kernels!**

**Do recursion by spawning new kernels!**



## Concurrent kernels, Dynamic Parallelism

Less work for the CPU to manage the computation.





## Recursion can look like this:

```
__global__ void quicksort(int *data, int left, int right)
{
    int nleft, nright;
    cudaStream_t s1, s2;

    // Partitions data based on pivot of first element.
    // Returns counts in nleft & nright
    partition(data+left, data+right, data[left], nleft, nright);

    // If a sub-array needs sorting, launch a new grid for it.
    // Note use of streams to get concurrency between sub-sorts
    if(left < nright) {
        cudaStreamCreateWithFlags(&s1, cudaStreamNonBlocking);
        quicksort<<< ..., s1 >>>(data, left, nright);
    }
    if(nleft < right) {
        cudaStreamCreateWithFlags(&s2, cudaStreamNonBlocking);
        quicksort<<< ..., s2 >>>(data, nleft, right);
    }
}

__host__ void launch_quicksort(int *data, int count)
{
    quicksort<<< ... >>>(data, 0, count-1);
}
```

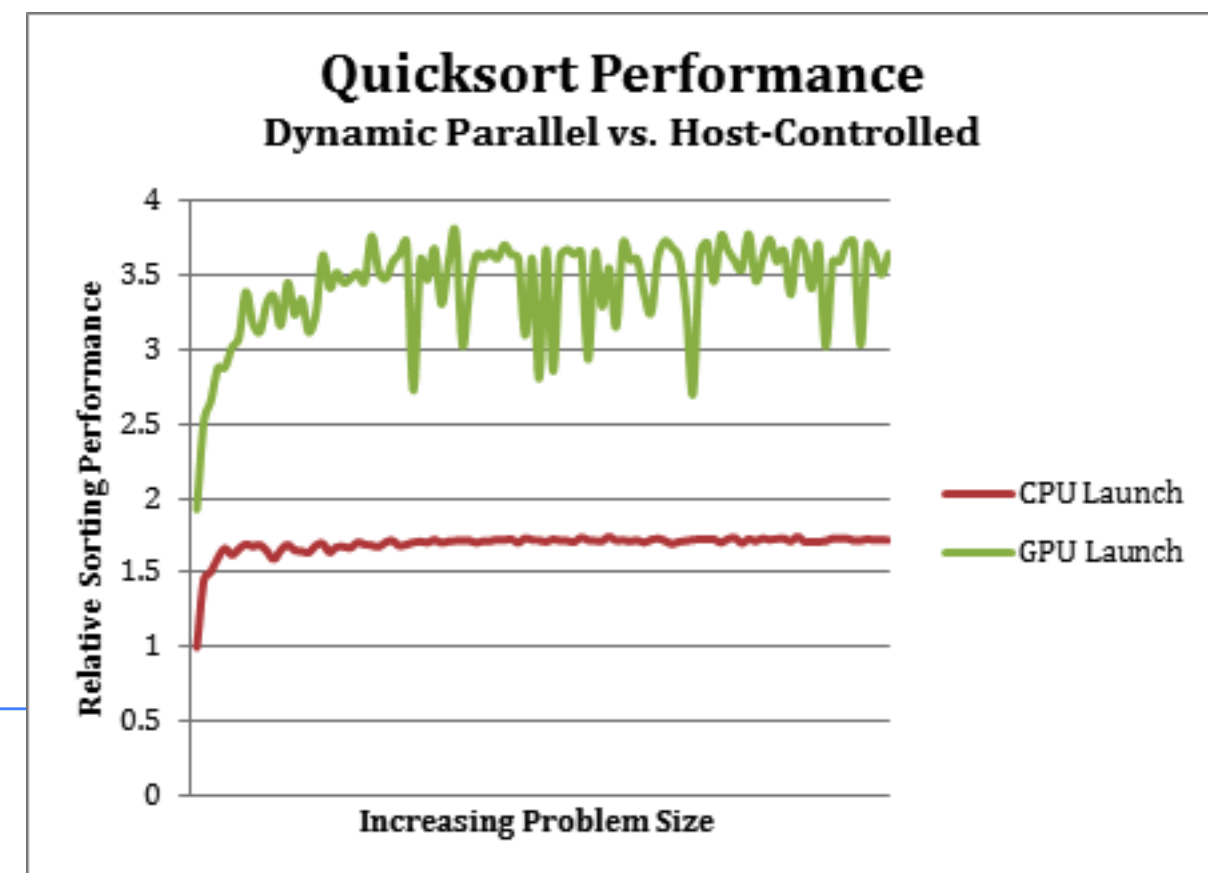
But... does this really do a good job on partitioning?



## Advantages

- **Less work for CPU**
- **Less synchronizing (from CPU side)**
- **Easier programming!**

They claim it matters this much (but your milage will vary)





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# **Recursive CUDA kernels, a promising improvement**

**Big change in GPU computing?**

**Southfork has GPUs that support it.**



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