

Lecture 11

More CUDA



In this episode...

- Error checking
- Query device capabilities
 - CUDA events
- More on CUDA memory:

Coalescing, Constant memory, Texture memory...

- OpenGL integration
 - Reduction (intro)

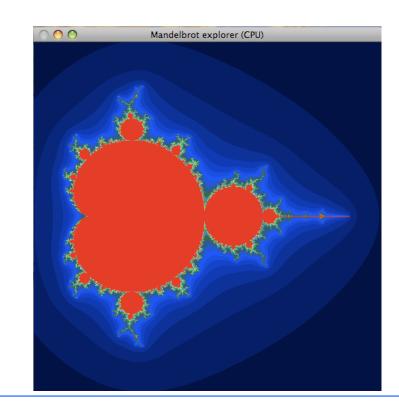


Lab 4

Happened earlier than usual. Everybody done or almost done?

Last year major change: "Mandelbrot revisited" part, to follow up lab 1.

Everything OK so far?



(Except for the drivers in the Multicore lab.)



The story so far...

- CUDA and its language extensions
 - The CUDA architecture
 - Intro to memory
- Matrix multiplication example, using shared memory



CUDA and its language extensions

Kernel involation myKernel<<>>>()

__global__ _device__ _host__

cudaMalloc(), cudaMemcpy()

threadIdx, blockIdx, blockDim, gridDim

Using nvcc



The CUDA architecture

Blocks and threads

Grid-block-thread hierarchy

Indexing data with thread/block numbers



Intro to memory

global memory

shared memory

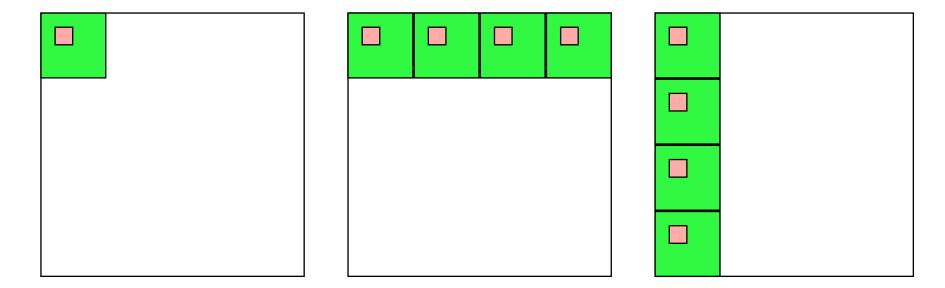
constant memory

local memory

texture memory/texture units



Matrix multiplication example, using shared memory



Huge speedup - my measly 9400M went from obvious loser to clearly faster than CPU!



Over to today's episode:



Lecture questions:

- 1. Why can using constant memory improve performance?
 - 2. What is CUDA Events used for?
- 3. What does coalescing mean and what should we do to get a speedup from coalescing?
- 4. How can you efficiently calculate the maximum of a dataset in parallel?



Error checking

- Functions returns error codes (but kernel launch does not)
 - cudaGetLastError()
 - cudaPeekLastError()



Asynchronous error checking

Asynchronous errors can not be returned by the function call!

Call cudaDeviceSynchronize() and check its returned error code.



Query devices

You can't trust all devices to have the same - or even similar - data.

New boards may have totally different data.

Query CUDA for a list of features using cudaGetDeviceProperties()



Example query result

```
--- Information for GeForce 9400M ----
```

Compute capability: 1.1

Total global memory (VRAM): 259712 kB

Total constant Mem: 64 kB

Number of SMs: 2

Shared mem per SM: 16 kB

Registers per SM: 8192

Threads in warp: 32

Max threads per block: 512

Max thread dimensions: (512, 512, 64)

Max grid dimensions: (65535, 65535, 1)



What is important?

Compute capability - can this board at all work with our program?

Amount of shared memory - make sure we fit.

Max threads, max dimensions - make sure we fit.

Threads in warp: A lower bound for performance.

Number of SMs: Lower bound for blocks



Compute capability

Essentially CUDA/architecture version number.

1.0: Original release.

1.1: Mapped memory, atomic operations.

1.3: Double support.

2.0: Fermi.

3.0: Kepler.

5.0: Maxwell.



Feature Support			ompute	Capabilit	ty		
(Unlisted features are supported for all compute capabilities)	1.0	1.1	1.2	1.3	2.x, 3.0	3.5	
Atomic functions operating on 32-bit integer values in global memory (Atomic Functions)	No			Yes			LiTH
atomicExch() operating on 32-bit floating point values in global memory (atomicExch())	No			163			
Atomic functions operating on 32-bit integer values in shared memory (Atomic Functions)							
atomicExch() operating on 32-bit floating point values in shared memory (atomicExch())	N	No		Yes			
Atomic functions operating on 64-bit integer values in global memory (Atomic Functions)							
Warp vote functions (Warp Vote Functions)							
Double-precision floating-point numbers		No		Yes			
Atomic functions operating on 64-bit integer values in shared memory (Atomic Functions)							
Atomic addition operating on 32-bit floating point values in global and shared memory (atomicAdd())							
ballot() (Warp Vote Functions)							
threadfence_system() (Memory Fence Functions)	No		Ye		es		
syncthreads_count(),							
syncthreads_and(),							
syncthreads_or() (Synchronization Functions)							
Surface functions (Surface Functions)	1						
 3D grid of thread blocks							
Funnel shift (see reference manual)			No Yes			Yes	



	FERMI GF100	FERMI GF104	KEPLER GK104	KEPLER GK110
Compute Capability	2.0	2.1	3.0	3.5
Threads / Warp	32	32	32	32
Max Warps / Multiprocessor	48	48	64	64
Max Threads / Multiprocessor	1536	1536	2048	2048
Max Thread Blocks / Multiprocessor	8	8	16	16
32-bit Registers / Multiprocessor	32768	32768	65536	65536
Max Registers / Thread	63	63	63	255
Max Threads / Thread Block	1024	1024	1024	1024
Shared Memory Size Configurations (bytes)	16K	16K	16K	16K
	48K	48K	32K	32K
			48K	48K
Max X Grid Dimension	2^16-1	2^16-1	2^32-1	2^32-1
Hyper-Q	No	No	No	Yes
Dynamic Parallelism	No	No	No	Yes

Compute Capability of Fermi and Kepler GPUs



Compute Capability	1.0	1.1	1.2	1.3	2.0	2.1	3.0	3.5
SM Version	sm_10	sm_11	sm_12	sm_13	sm_20	sm_21	sm_30	sm_35
Threads / Warp	32	32	32	32	32	32	32	32
Warps / Multiprocessor	24	24	32	32	48	48	64	64
Threads / Multiprocessor	768	768	1024	1024	1536	1536	2048	2048
Thread Blocks / Multiprocessor	8	8	8	8	8	8	16	16
Max Shared Memory / Multiprocessor (bytes)	16384	16384	16384	16384	49152	49152	49152	49152
Register File Size	8192	8192	16384	16384	32768	32768	65536	65536
Register Allocation Unit Size	256	256	512	512	64	64	256	256
Allocation Granularity	block	block	block	block	warp	warp	warp	warp
Max Registers / Thread	124	124	124	124	63	63	63	255
Shared Memory Allocation Unit Size	512	512	512	512	128	128	256	256
Warp allocation granularity	2	2	2	2	2	2	4	4
Max Thread Block Size	512	512	512	512	1024	1024	1024	1024
Shared Memory Size Configurations (bytes)	16384	16384	16384	16384	49152	49152	49152	49152
[note: default at top of list]					16384	16384	16384	16384
							32768	32768
Warp register allocation granularities					64	64	256	256
[note: default at top of list]					128	128		



Do I care about Compute capability?

While learning CUDA - not much. Stick to the basics, it works on all.

But if you write professional CUDA code, of course.



CUDA Events

Timing!

Two ways of timing CUDA programs:

- · CPU timer. Synchronize at start and end.
 - CUDA Events. Synchronize at end.

Synchronize? Because CUDA runs asynchronously.



CUDA Events API

cudaEventCreate - initialize an event variable

cudaEventRecord - place a marker in the queue

cudaEventSynchronize - wait until all markers have received values

cudaEventElapsedTime - get the time difference between two events