



Information Coding / Computer Graphics, ISY, LiTH

# **Lecture 10**

## **Introduction to CUDA**

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### **Laborations**

**Labs 5 will be revised, expanded!**

**No changes are planned for lab 4 and 5.**

**Last minute changes may occur**

**The "lab questions" are vital! Answers *must* be written down  
before we can examine you!**

**Thus - no lab reports needed.**



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### **Lecture material**

**Lecture material available on the web. Latest version comes up before the lecture, but usually not more than an hour or two before. Last year's material is also available.**

**We have a local course page:**

**<http://computer-graphics.se/multicore/>**

**Lab material and lecture notes (and any additional material) are/will be on that page.**



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## **Previous lecture:**

**GPU development - why did it become  
a general purpose parallel architecture**

**GPU architecture**

**A quick look at GPU coding (Hello  
World!)**



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# **This lecture:**

**Programming model and language**

**Introduction to memory spaces and  
memory access**

**Shared memory**

**Matrix multiplication example**



## **Lecture questions:**

- 1. What concept in CUDA corresponds to a SM (streaming multiprocessor) in the architecture?**
- 2. How does matrix multiplication benefit from using shared memory?**
- 3. When do you typically need to synchronize threads?**



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# **CUDA = Compute Unified Device Architecture**

**Developed by NVidia**

**Only available on NVidia boards, G80 or  
better GPU architecture**

**Designed to hide the graphics heritage  
and add control and flexibility**



# **Computing model:**

- 1. Upload data to GPU**
- 2. Execute kernel**
- 3. Download result**

**Similar to shader-based solutions and  
OpenCL**





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## **Integrated source**

**Source of host and kernel code in the same source file!**

**Major difference to shaders and OpenCL.**

**Kernel code identified by special modifiers.**



# CUDA

## Architecture and C extension

**Spawn a large number of threads, to be ran virtually in parallel**

**Just like in graphics! Fragments/computations not *quite* executed in parallel.**

**A bunch at a time - a *warp*.**

**Looks much more like an ordinary C program! No more "data stored as pixels" - just arrays!**



## Simple CUDA example

A working, compilable example

```
#include <stdio.h>

const int N = 16;
const int blocksize = 16;

__global__
void simple(float *c)
{
    c[threadIdx.x] = threadIdx.x;
}

int main()
{
    int i;
    float *c = new float[N];
    float *cd;
    const int size = N*sizeof(float);

    cudaMalloc( (void**)&cd, size );
    dim3 dimBlock( blocksize, 1 );
    dim3 dimGrid( 1, 1 );
    simple<<<dimGrid, dimBlock>>>(cd);
    cudaMemcpy( c, cd, size, cudaMemcpyDeviceToHost );
    cudaFree( cd );

    for (i = 0; i < N; i++)
        printf("%f ", c[i]);
    printf("\n");
    delete[] c;
    printf("done\n");
    return EXIT_SUCCESS;
}
```



## Simple CUDA example

A working, compilable example

```
#include <stdio.h>

const int N = 16;
const int blocksize = 16;

__global__ Kernel
void simple(float *c)
{
    c[threadIdx.x] = threadIdx.x;
} thread identifier

int main()
{
    int i;
    float *c = new float[N];
    float *cd;
    const int size = N*sizeof(float);

    Allocate GPU memory
    cudaMalloc( (void**)&cd, size );
    dim3 dimBlock( blocksize, 1 ); 1 block, 16 threads
    dim3 dimGrid( 1, 1 );
    simple<<<dimGrid, dimBlock>>>(cd); Call kernel
    cudaMemcpy( c, cd, size, cudaMemcpyDeviceToHost );
    cudaFree( cd ); Read back data

    for (i = 0; i < N; i++)
        printf("%f ", c[i]);
    printf("\n");
    delete[] c;
    printf("done\n");
    return EXIT_SUCCESS;
}
```



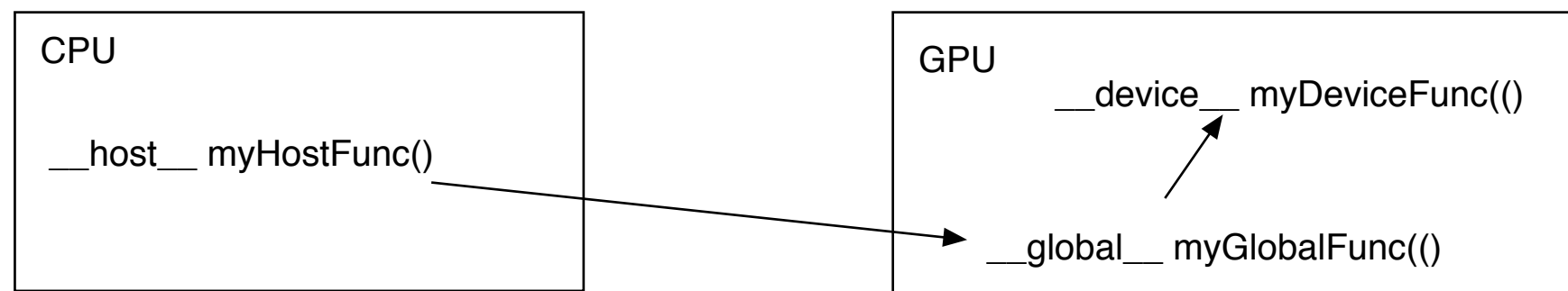
## Modifiers for code

**Three modifiers are provided to specify how code should be used:**

**\_\_global\_\_ executes on the GPU, invoked from the CPU. This is the entry point of the kernel.**

**\_\_device\_\_ is local to the GPU**

**\_\_host\_\_ is CPU code (superfluous).**





## **Memory management**

**cudaMalloc(ptr, datasize)  
cudaFree(ptr)**

**Similar to CPU memory management, but done by the  
CPU to allocate on the GPU**

**cudaMemCpy(dest, src, datasize, arg)**

**arg = cudaMemcpyDeviceToHost  
or cudaMemcpyHostToDevice**



## Kernel execution

**simple<<<griddim, blockdim>>>(…)**

**grid = blocks, block = threads**

**Built-in variables for kernel:**

***threadIdx* and *blockIdx*  
*blockDim* and *gridDim***

**(Note that no prefix is used, like GLSL does.)**



## Compiling Cuda

**nvcc**

**nvcc is nvidia's tool, /usr/local/cuda/bin/nvcc**

**Source files suffixed .cu**

**Command-line for the simple example:**

```
nvcc simple.cu -o simple
```

**(Command-line options exist for libraries etc)**





## **Compiling Cuda for larger applications**

**nvcc and gcc in co-operation**

**nvcc for .cu files**

**gcc for .c/.cpp etc**

**Mixing languages possible.**

**Final linking must include C++ runtime libs.**

**Example: One C file, one CU file**



## Example of multi-unit compilation

Source files: cudademokernel.cu and cudademo.c

```
nvcc cudademokernel.cu -o cudademokernel.o -c
```

```
gcc -c cudademo.c -o cudademo.o -I/usr/local/cuda/include
```

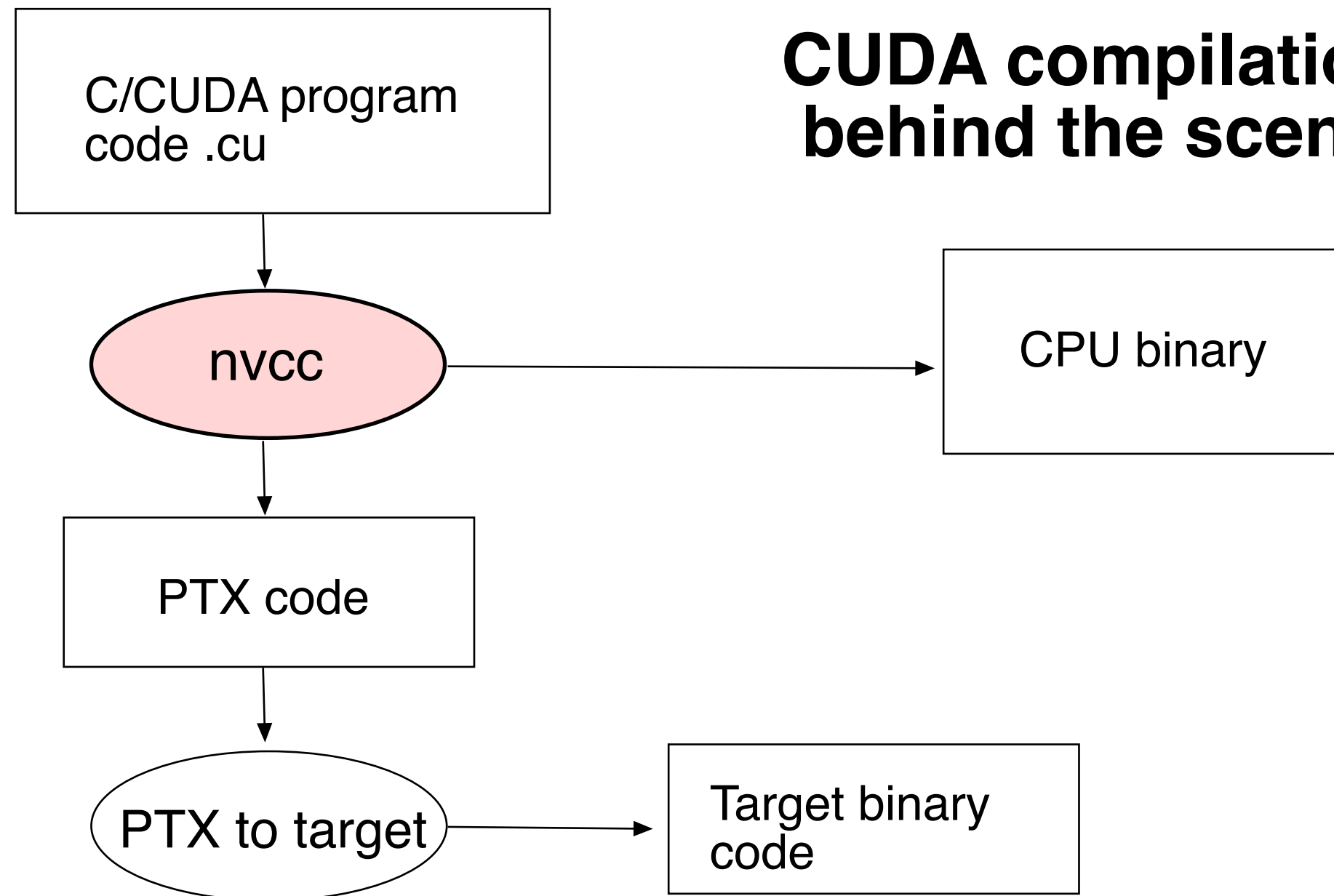
```
g++ cudademo.o cudademokernel.o -o cudademo -L/usr/local/cuda/lib -lcuda -lcudart -lm
```

Link with g++ to include C++ runtime



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## CUDA compilation behind the scene





## **Executing a Cuda program**

**Must set environment variable to find Cuda runtime.**

```
export DYLD_LIBRARY_PATH=/usr/local/cuda/lib:$DYLD_LIBRARY_PATH
```

**Then run as usual:**

**./simple**

**A problem when executing without a shell!**

**Launch with `execve()`**



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# **Computing with CUDA**

**Organization and access**

**Blocks, threads...**



## Warps

**A warp is the minimum number of data items/threads that will actually be processed in parallel by a CUDA capable device. This number varies with different GPUs.**

**We usually don't care about warps but rather discuss threads and blocks.**



## Processing organization

**1 warp = 32 threads**

**1 kernel - 1 grid**

**1 grid - many blocks**

**1 block - 1 SM**

**1 block - many threads**

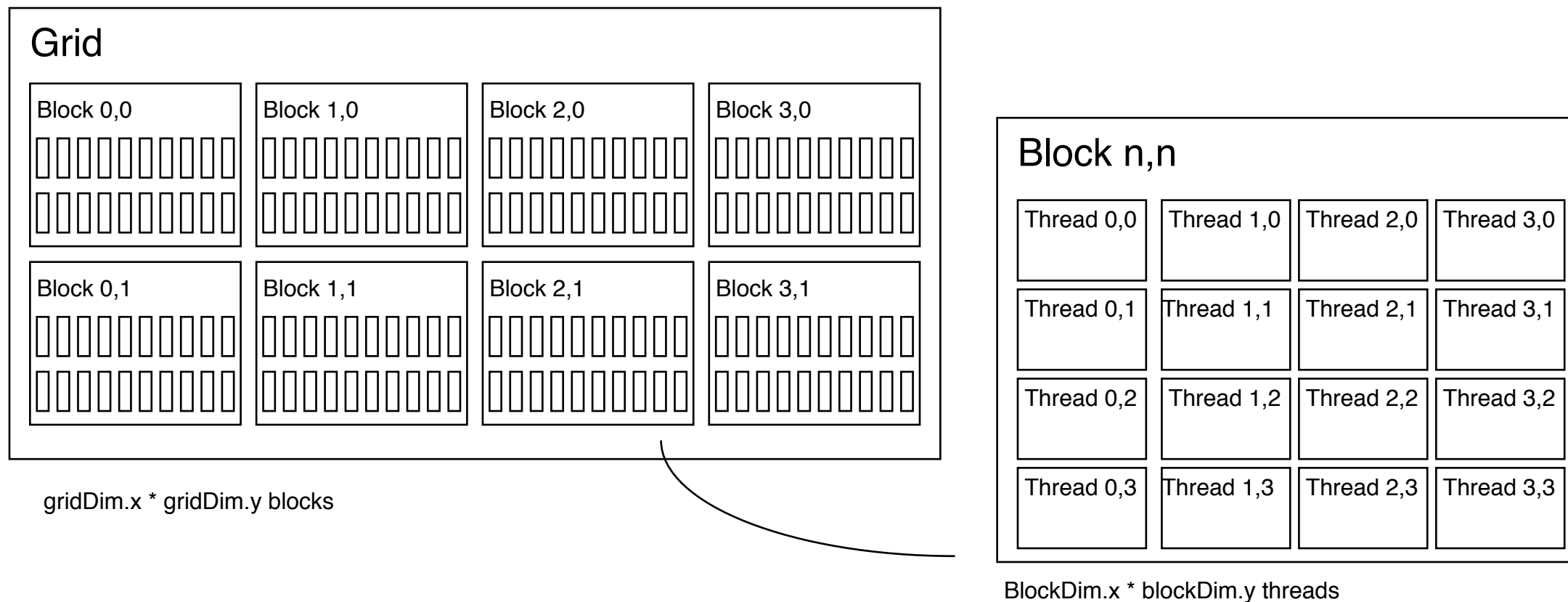
**Use many threads and many blocks! > 200 blocks  
recommended.**

**Thread # multiple of 32**



# Distributing computing over threads and blocks

## Hierarcical model







## Indexing data with thread/block IDs

Calculate index by blockIdx, blockDim, threadIdx

Another simple example, calculate square of every element, device part:

```
// Kernel that executes on the CUDA device
__global__ void square_array(float *a, int N)
{
    int idx = blockIdx.x * blockDim.x + threadIdx.x;
    if (idx < N) a[idx] = a[idx] * a[idx];
}
```



## Host part of square example

### Set block size and grid size

```
// main routine that executes on the host
int main(int argc, char *argv[])
{
    float *a_h, *a_d; // Pointer to host and device arrays
    const int N = 10; // Number of elements in arrays
    size_t size = N * sizeof(float);
    a_h = (float *)malloc(size);
    cudaMalloc((void **) &a_d, size); // Allocate array on device
    // Initialize host array and copy it to CUDA device
    for (int i=0; i<N; i++) a_h[i] = (float)i;
    cudaMemcpy(a_d, a_h, size, cudaMemcpyHostToDevice);
    // Do calculation on device:
    int block_size = 4;
    int n_blocks = N/block_size + (N%block_size == 0 ? 0:1);
    square_array <<< n_blocks, block_size >>> (a_d, N);
    // Retrieve result from device and store it in host array
    cudaMemcpy(a_h, a_d, sizeof(float)*N, cudaMemcpyDeviceToHost);
    // Print results and cleanup
    for (int i=0; i<N; i++) printf("%d %f\n", i, a_h[i]);
    free(a_h); cudaFree(a_d);
}
```



## Julia example

For this case: Separate for x and y

```
__global__ void kernel( unsigned char *ptr, float r, float im)
{
    // map from blockIdx to pixel position
    int x = blockIdx.x * blockDim.x + threadIdx.x;
    int y = blockIdx.y * blockDim.y + threadIdx.y;

    int offset = x + y * DIM;

    // now calculate the value at that position
    int juliaValue = julia( x, y, r, im );
    --- calculate colors ---
    ptr[offset*4 + 0] = red;
    ptr[offset*4 + 1] = green;
    ptr[offset*4 + 2] = blue;
    ptr[offset*4 + 3] = 255;
}
```

Actual index  
which implies  
memory position

Two arrows point from the text "Actual index which implies memory position" to the lines `int x = blockIdx.x * blockDim.x + threadIdx.x;` and `int y = blockIdx.y * blockDim.y + threadIdx.y;` in the code block above.

**Every thread computes one single pixel!**



# **Memory access**

**Vital for performance!**

**Memory types**

**Coalescing**

**Example of using shared memory**



## **Memory types**

**Global**

**Shared**

**Constant (read only)**

**Texture cache (read only)**

**Local**

**Registers**

**Care about these when optimizing - not to begin with**



## **Global memory**

**400-600 cycles latency!**

**Shared memory fast temporary storage**

**Coalesce memory access!**

**Continuous**

**Aligned on power of 2 boundary**

**Addressing follows thread numbering**

**Use shared memory for reorganizing data for  
coalescing!**



## **Using shared memory to reduce number of global memory accesses**

**Read blocks of data to shared memory**

**Process**

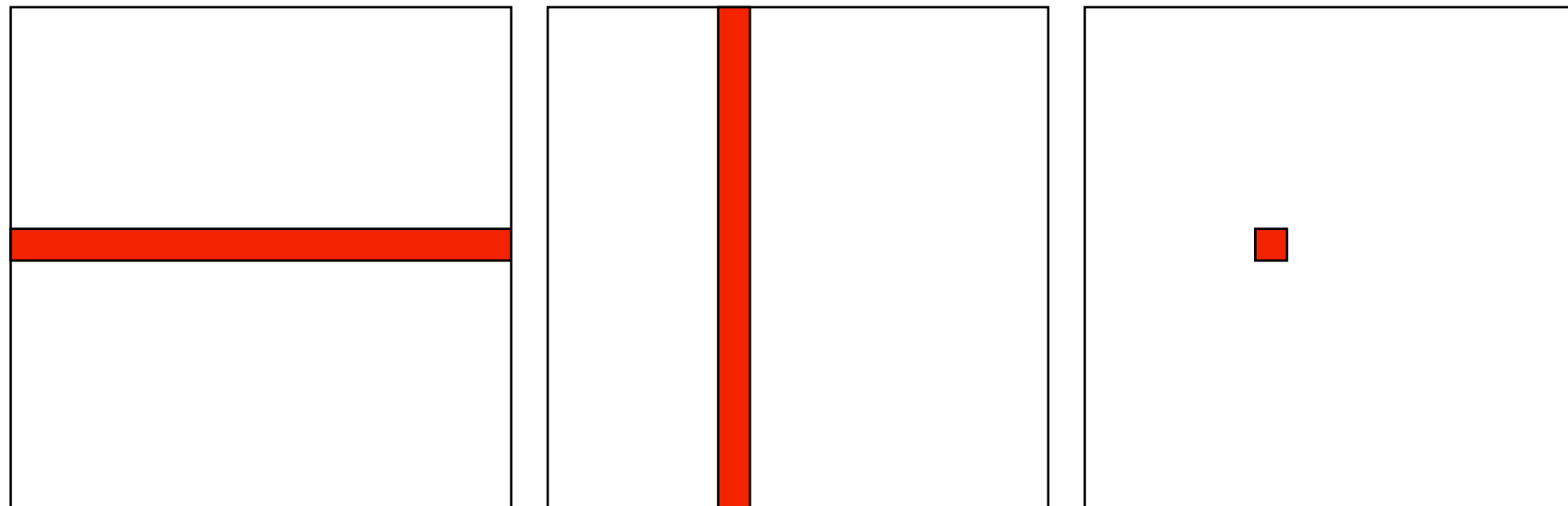
**Write back as needed**

**Shared memory as "manual cache"**

**Example: Matrix multiplication**



## Matrix multiplication



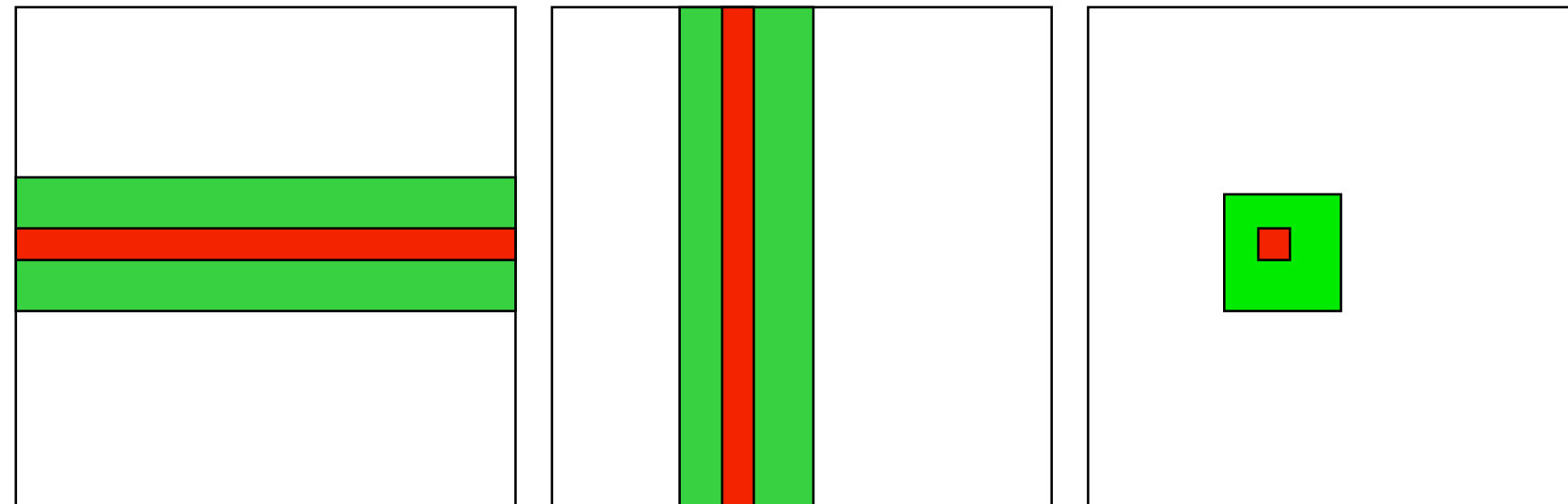
To multiply two  $N \times N$  matrices, every item will have to be accessed  $N$  times!

Naive implementation:  $2N^3$  global memory accesses!





## Matrix multiplication



Let each block handle a part of the output.

Load the parts of the matrix needed for the block into shared memory.



# Matrix multiplication on CPU

## Simple triple "for" loop

```
void MatrixMultCPU(float *a, float *b, float *c, int theSize)
{
    int sum, i, j, k;

    // For every destination element
    for(i = 0; i < theSize; i++)
        for(j = 0; j < theSize; j++)
            {
                sum = 0;
                // Sum along a row in a and a column in b
                for(k = 0; k < theSize; k++)
                    sum = sum + (a[i*theSize + k]*b[k*theSize + j]);
                c[i*theSize + j] = sum;
            }
}
```



## Naive GPU version

Replace outer loops by thread indices

```
__global__ void MatrixMultNaive(float *a, float *b, float *c, int
                                theSize)
    {
        int sum, i, j, k;

        i = blockIdx.x * blockDim.x + threadIdx.x;
        j = blockIdx.y * blockDim.y + threadIdx.y;

        // For every destination element
        sum = 0;
        // Sum along a row in a and a column in b
        for(k = 0; k < theSize; k++)
            sum = sum + (a[i*theSize + k]*b[k*theSize + j]);
        c[i*theSize + j] = sum;
    }
```



## **Naive GPU version inefficient**

**Every thread makes  $2N$  global memory accesses!**

**Can be significantly reduced using shared memory**



## Optimized GPU version

**Data split into blocks.**

**Every element takes part in all the blocks in the same  
*row* for A, *column* for B**

**For every such block**

**Every thread reads *one* element to shared memory**

**Then loop over the appropriate row and column  
for the block**



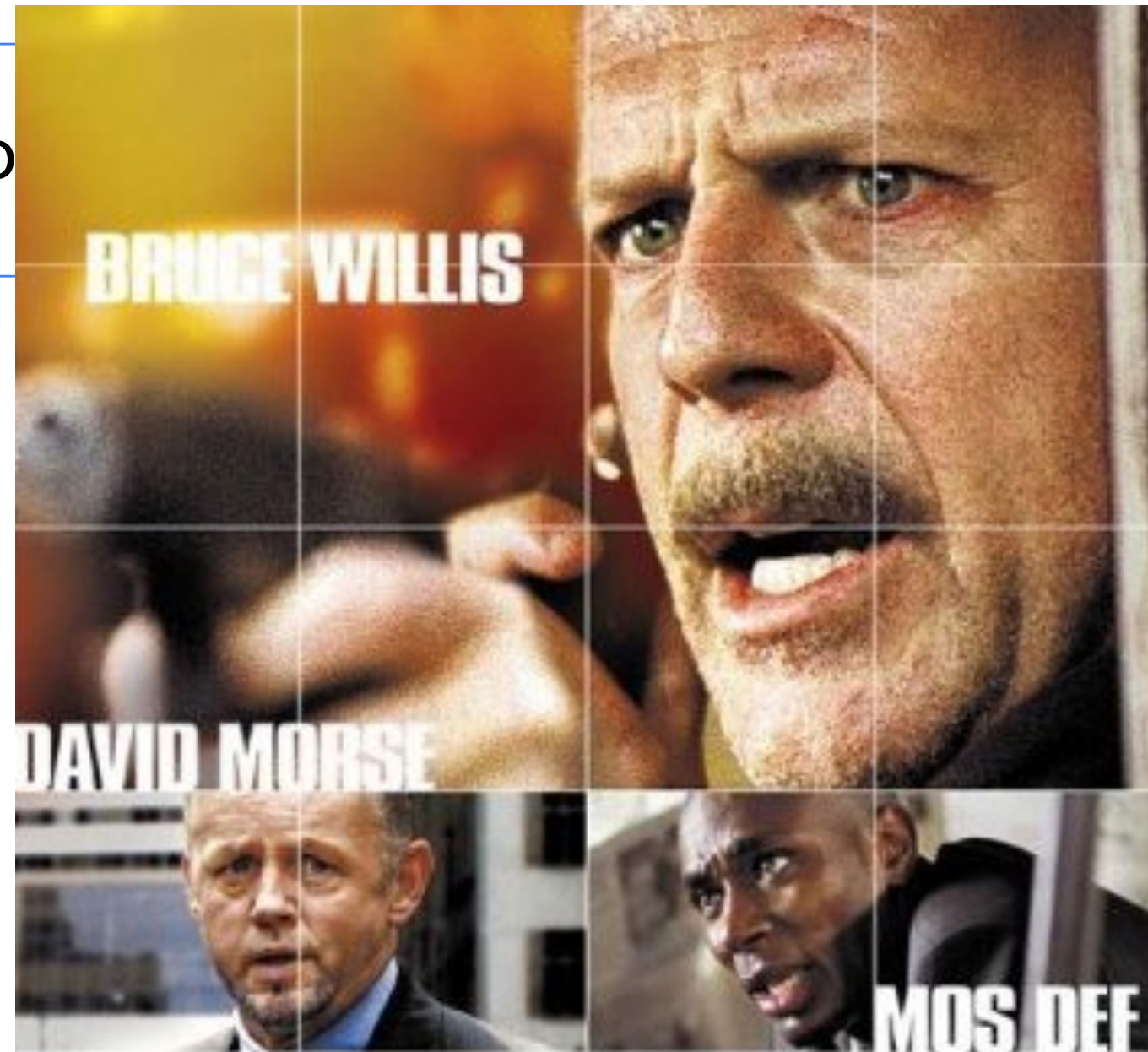
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**Example: 16 blocks**



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# 16 BLOCKS

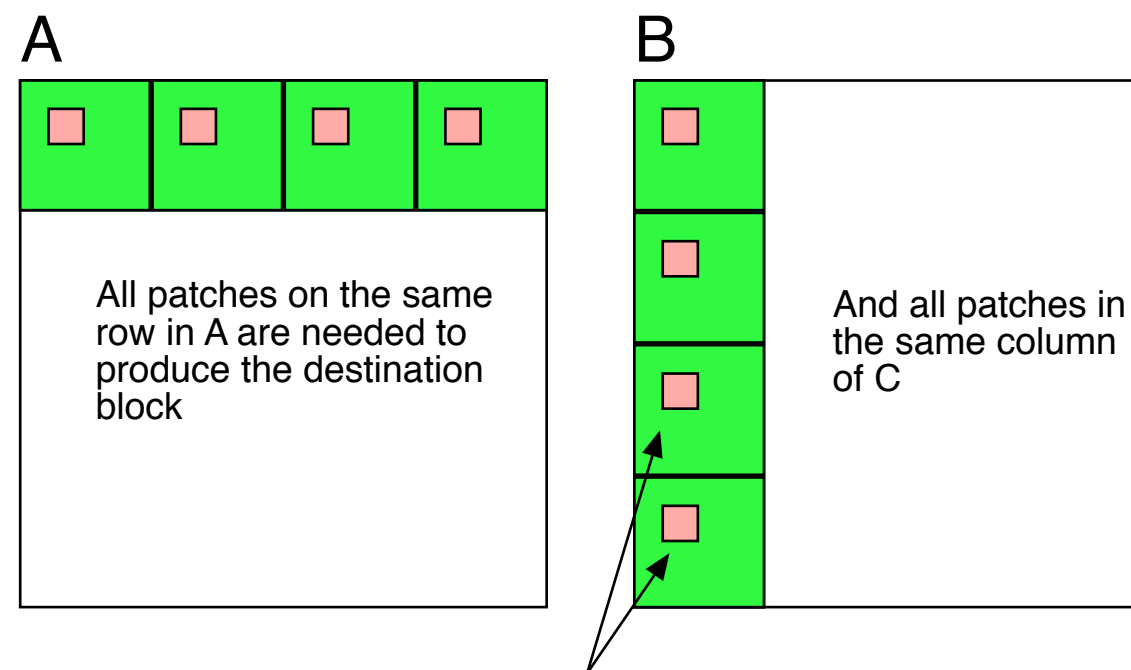
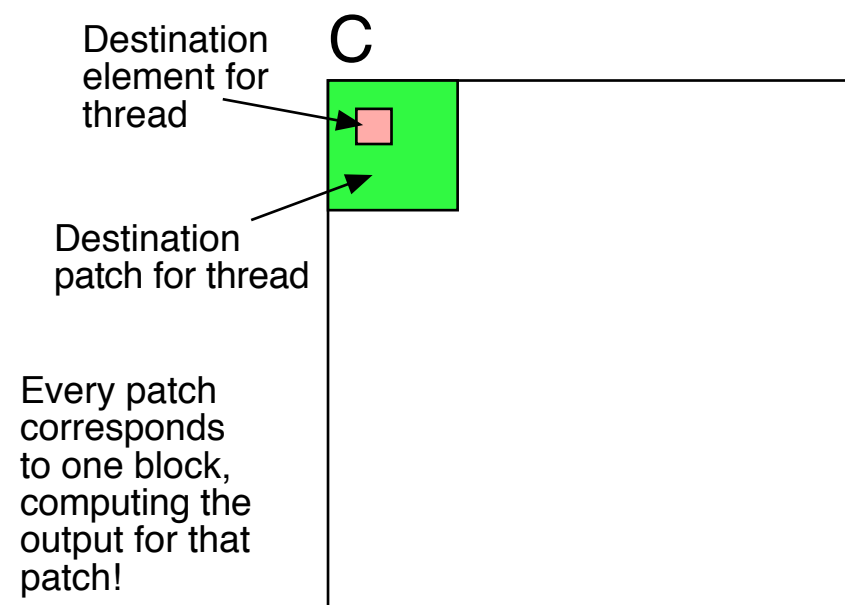
FILM BY RICHARD DONNER



16ブロック

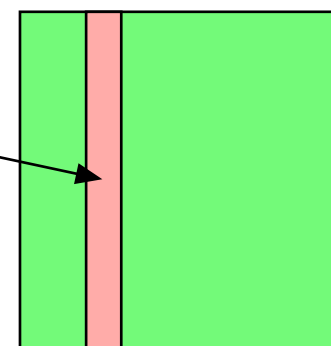
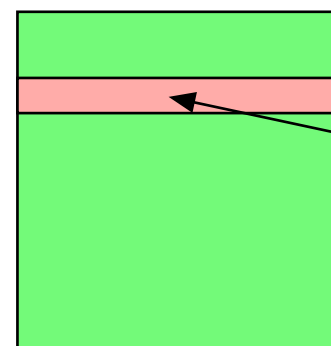
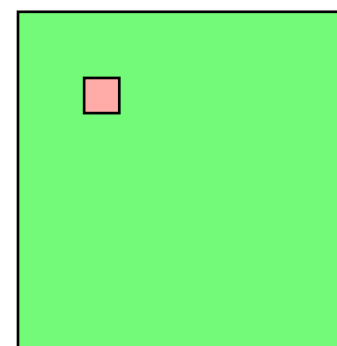


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For every patch, the thread reads one element matching the destination element

For every patch, we loop over the part of one row and column to perform that part of the computation



What one thread reads is used by everybody in the same row (A) or column (B)!





## Optimized GPU version

Loop over patches (1D)

Allocate shared memory

Copy one element to shared memory

Loop over row/column in patch, compute, accumulate result for one element

Write result to global memory

```
__global__ void MatrixMultOptimized( float* A, float* B, float* C, int theSize)
{
    int i, j, k, b, ii, jj;

    // Global index for thread
    i = blockIdx.x * blockDim.x + threadIdx.x;
    j = blockIdx.y * blockDim.y + threadIdx.y;

    float sum = 0.0;
    // for all source patches
    for (b = 0; b < gridDim.x; b++)
    {
        __shared__ float As[BLOCKSIZE*BLOCKSIZE];
        __shared__ float Bs[BLOCKSIZE*BLOCKSIZE];

        // Index locked to patch
        ii = b * blockDim.x + threadIdx.x;
        jj = b * blockDim.y + threadIdx.y;

        As[threadIdx.y*blockDim.x + threadIdx.x] = A[ii*theSize + j];
        Bs[threadIdx.y*blockDim.x + threadIdx.x] = B[i*theSize + jj];

        __syncthreads(); // Synchronize to make sure all data is loaded

        // Loop, perform computations in patch
        for (k = 0; k < blockDim.x; ++k)
            sum += As[threadIdx.y*blockDim.x + k]
                * Bs[k*blockDim.x + threadIdx.x];

        __syncthreads(); // Synch so nobody starts next pass prematurely
    }

    C[i*theSize + j] = sum;
}
```



## **Modified computing model:**

**Upload data to global GPU memory**

**For a number of parts, do:**

**Upload partial data to shared memory**

**Process partial data**

**Write partial data to global memory**

**Download result to host**



# Synchronization

**As soon as you do something where one part of a computation depends on a result from another thread, you must synchronize!**

**\_\_syncthreads()**

**Typical implementation:**

- **Read to shared memory**
  - **\_\_syncthreads()**
- **Process shared memory**
  - **\_\_syncthreads()**
- **Write result to global memory**



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### **Summary:**

- **Make threads and blocks to make the hardware occupied**
  - **Access data depending on thread/block number**
    - **Memory accesses are expensive!**
      - **Shared memory is fast**
  - **Make threads within a block cooperate**
    - **Synchronize**



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**That's all folks!**

**Next: More about memory management and optimization.**