

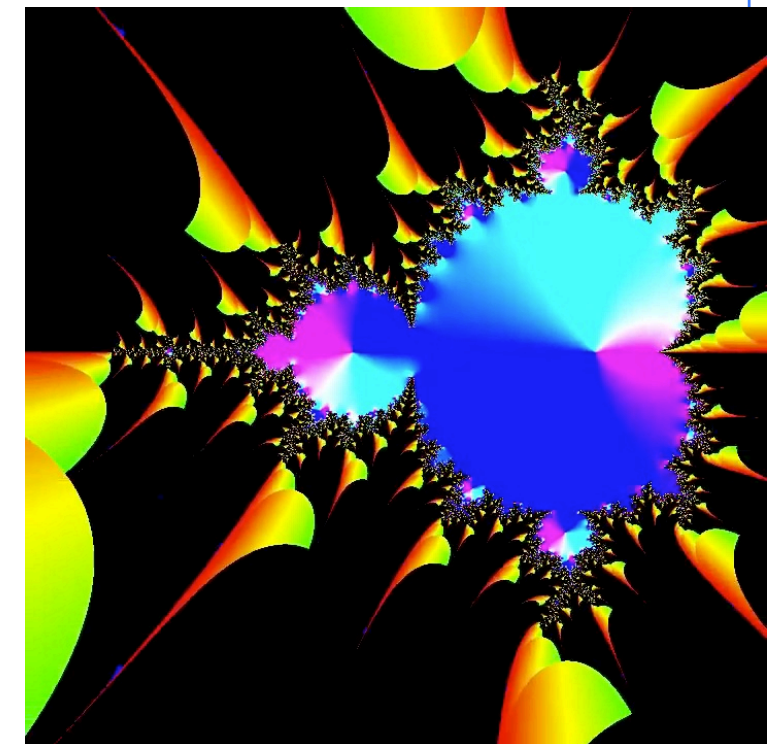


Information Coding / Computer Graphics, ISY, LiTH

TSBK07/TSBK11

Computer Graphics

Ingemar Ragnemalm, ISY





Lecture 12

Anti-aliasing

Ray-tracing

Radiosity

Path tracing



Project suggestion are rolling in

All that made one should have had a
response by now.

If you haven't decided, the last lectures
present several possibilities.

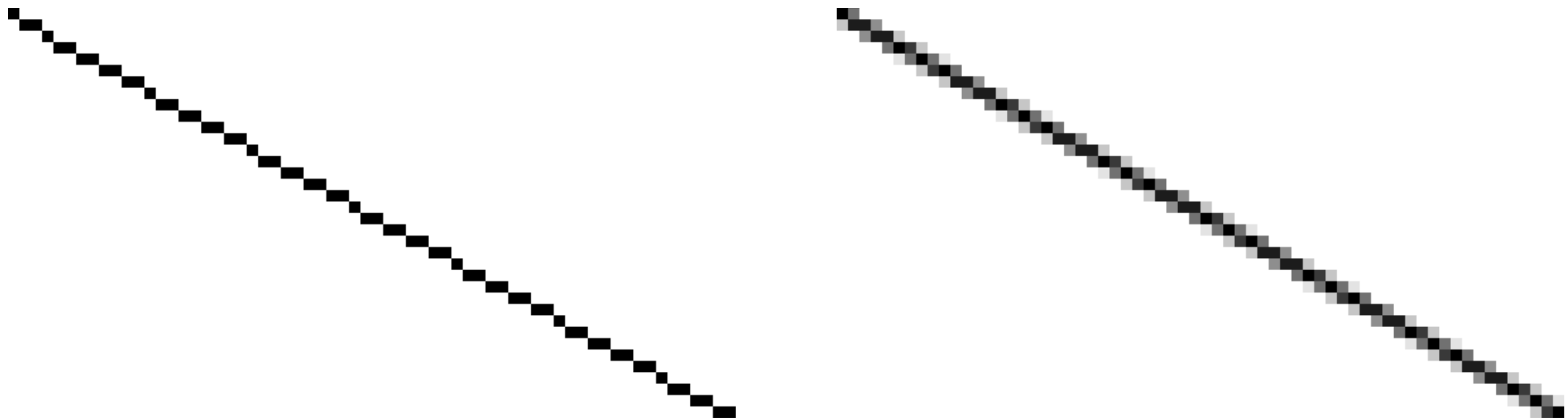


Lecture questions

1. How does the frequency contents vary in typical images?
2. What is the highest magnitude of errors for 2x supersampling?
3. How are shadows produced in ray tracing?
4. Why might you want to cast more than one ray per pixel?
5. How do you anti-alias ray-tracing even more than supersampling?
6. What is the difference between photon mapping and path tracing?



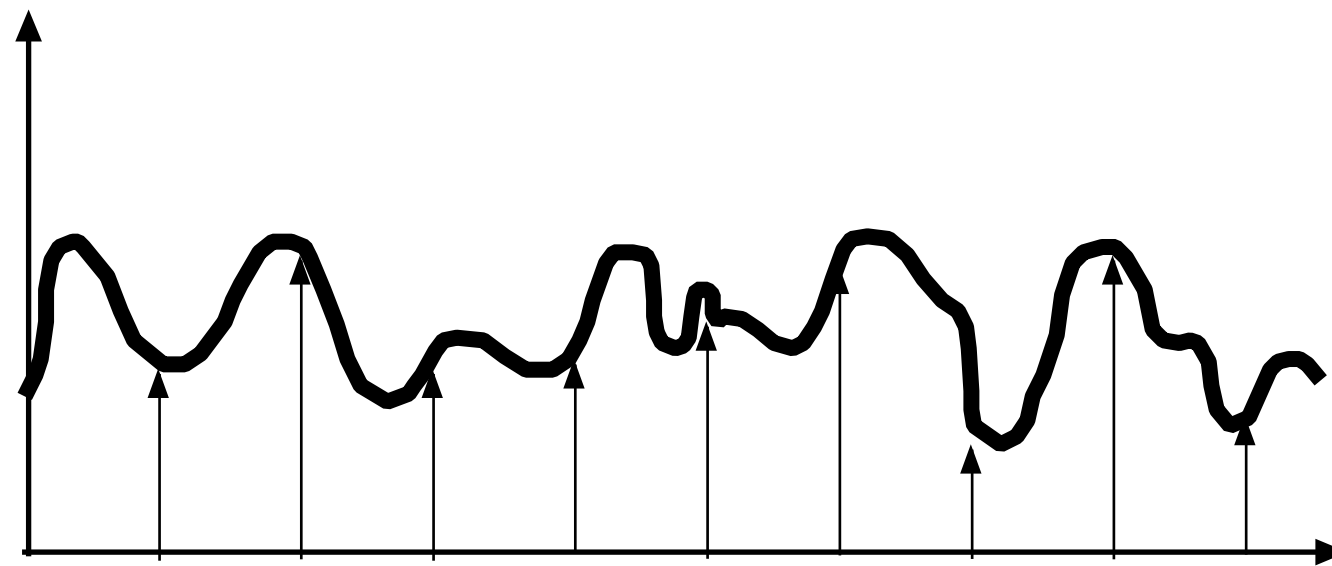
Anti-aliasing



anti-aliasing ... is often an absolute requirement these days (Stefan Gustavson, 2024)



Sampling

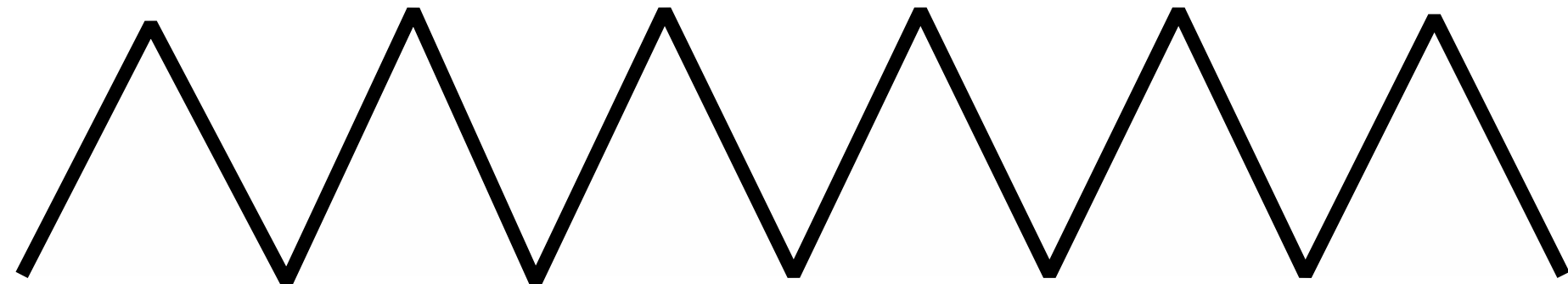


A digital image is a sampled version of an underlying analog 2D signal.

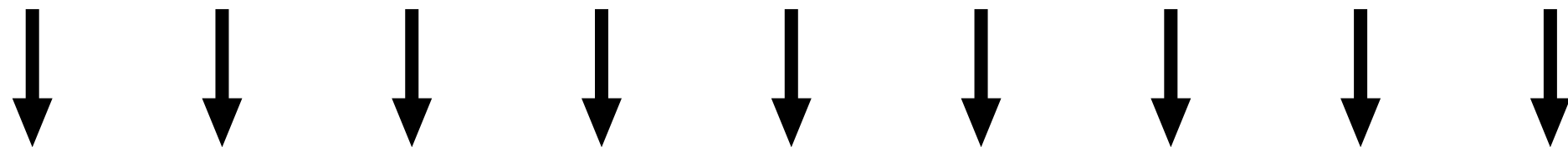


Information Coding / Computer Graphics, ISY, LiTH

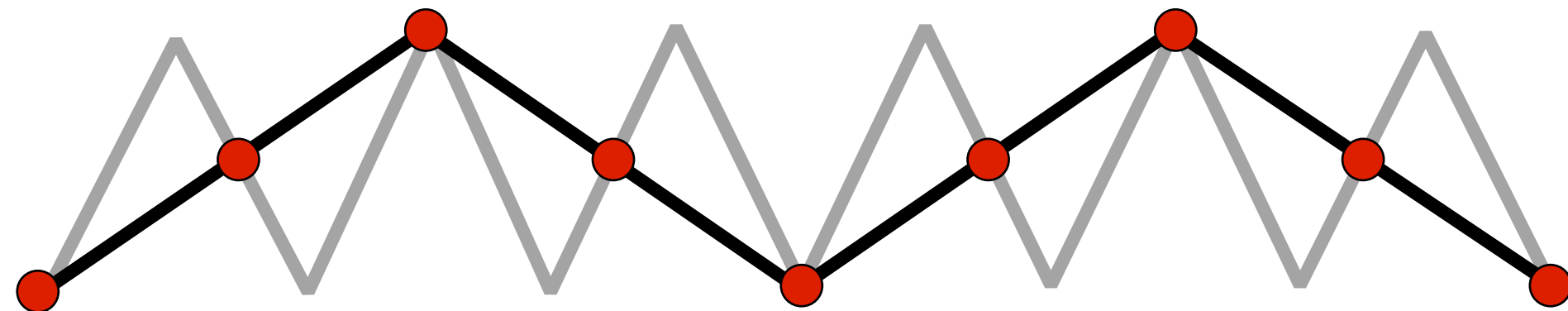
Signal



Sampling



Result





Frequency space

Any signal can be decomposed into sinus waves

The amplitudes of all sinus waves form a new space -
frequency space

This space exists in any dimension. An image is a 2D
signal and has a 2D frequency space.



Sampling + reconstruction

When presenting the digital signal, it is reconstructed to an analog signal.

A signal can be decomposed into different frequency bands.

What parts of the original signal that are accurately reconstructed depend on the frequencies.

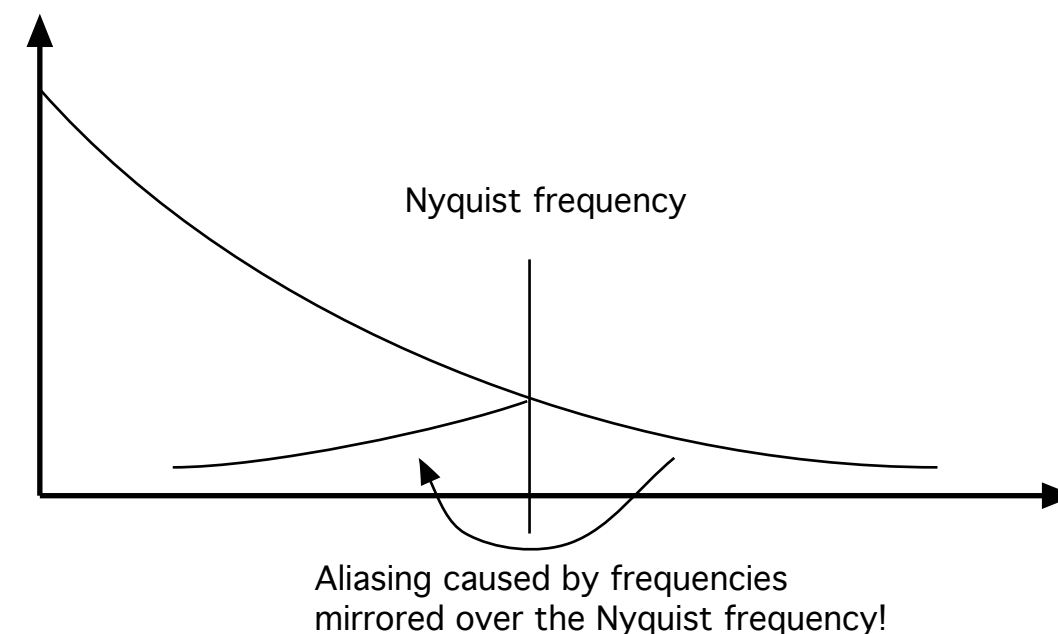
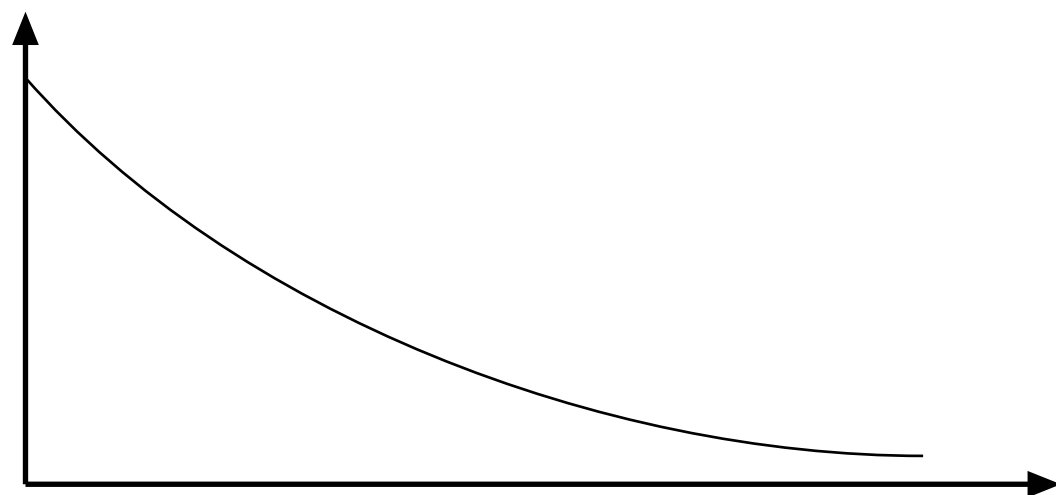


Aliasing in frequency space!

Which frequencies are preserved and which cause problems?

Amplitudes usually lower for higher frequencies!

The $1/f$ rule!



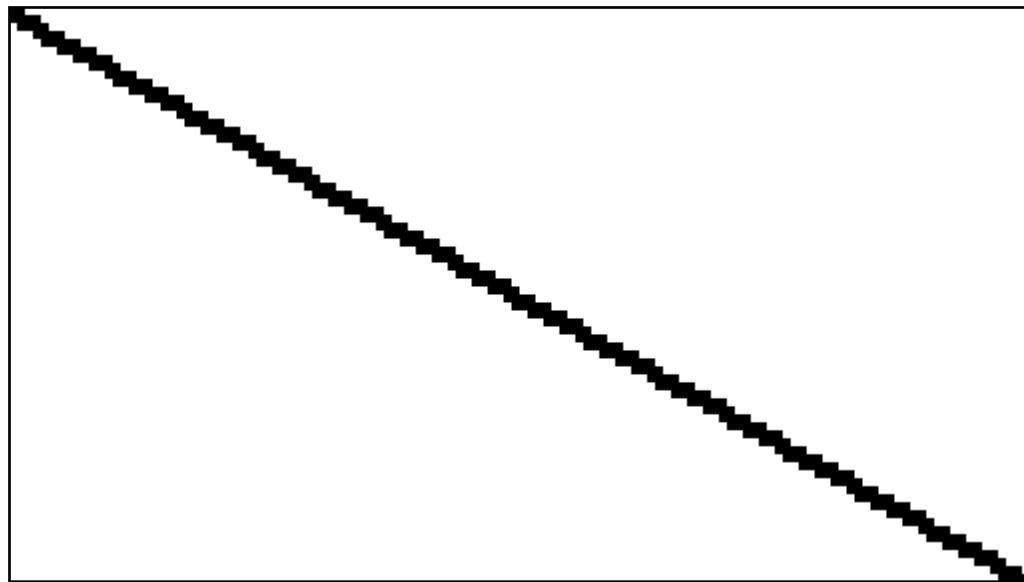


Anti-aliasing methods

- Linear post-filtering. Bad.
- Super-sampling: Split pixels in sub-pixels. Check how many sub-pixels that hit one pixel.
- Edge smoothing: Estimate edges, smooth edges.
- Non-linear post-filtering.



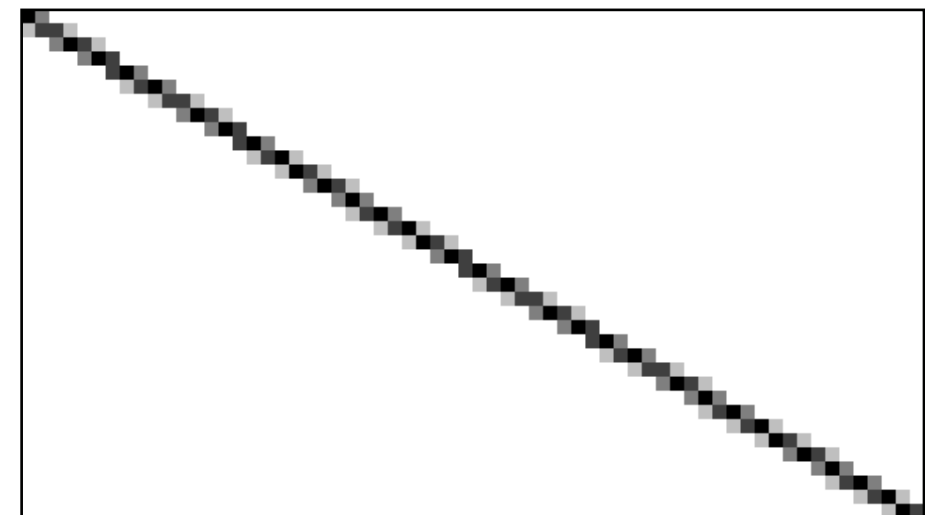
Supersampling



Draw in a high-res
image buffer

Simple but slow and
memory-demanding

Sample down to
destination buffer

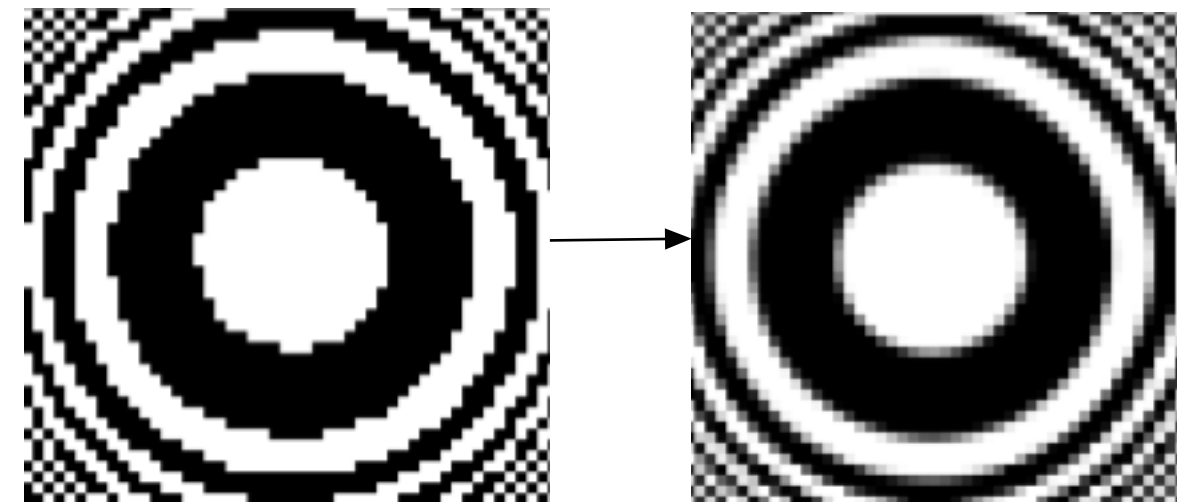
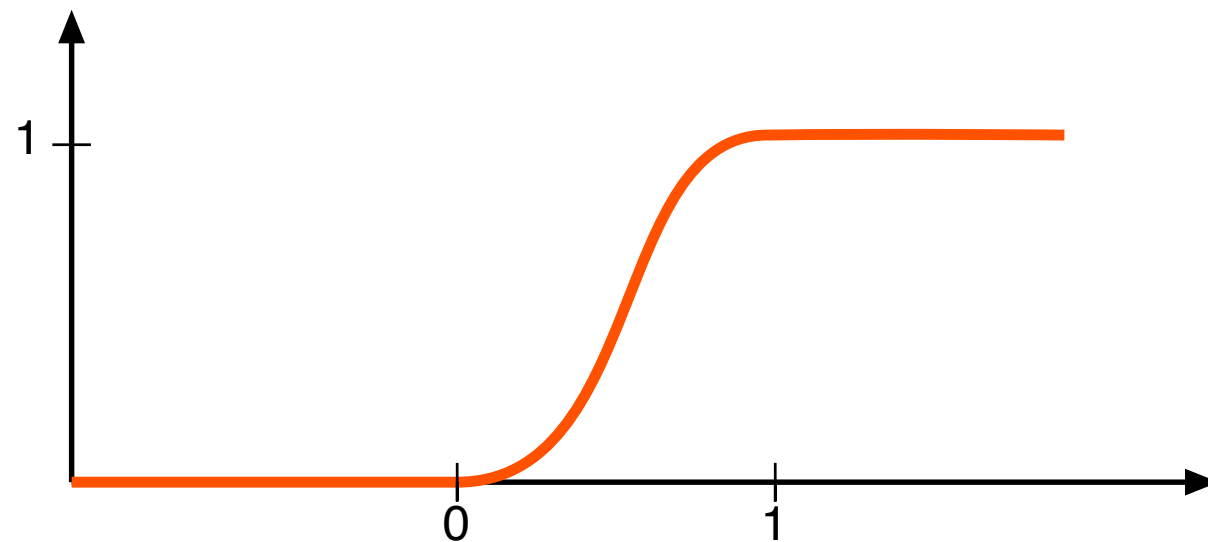




Edge smoothing

For line drawings and similar.

Measure edge by gradients in image, use the "smoothstep" function on edges.



"If frequencies are known, add "frequency clamping", smooth high frequencies.



Multisampling

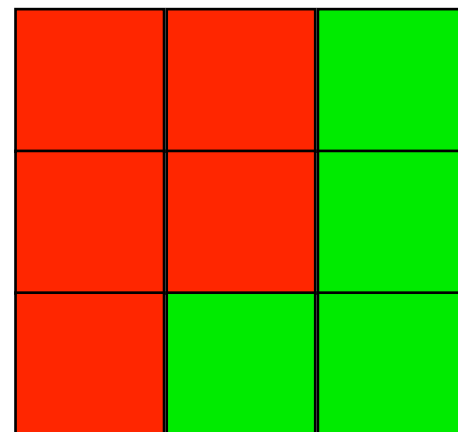
Variant of supersampling

More efficient

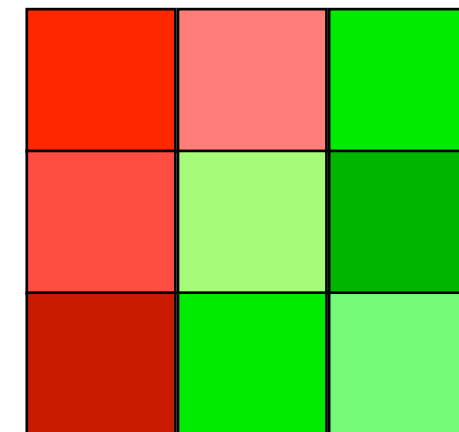
Only improves edges



Multisampling



Multisampling: Only one execution of fragment shader for all samples from the same geometry



Supersampling: One execution of fragment shader for each sample



Multisampling

Less fragment processing

Fewer texture accesses

Same number of memory writes and same post-processing



FXAA = Fast approXimative AA

Post-processing

No higher resolution image

Non-linear filter

Don't filter patterns

Several recent methods of this kind



Anti-aliasing in OpenGL

`GL_POLYGON_SMOOTH` - Old built-in, avoid

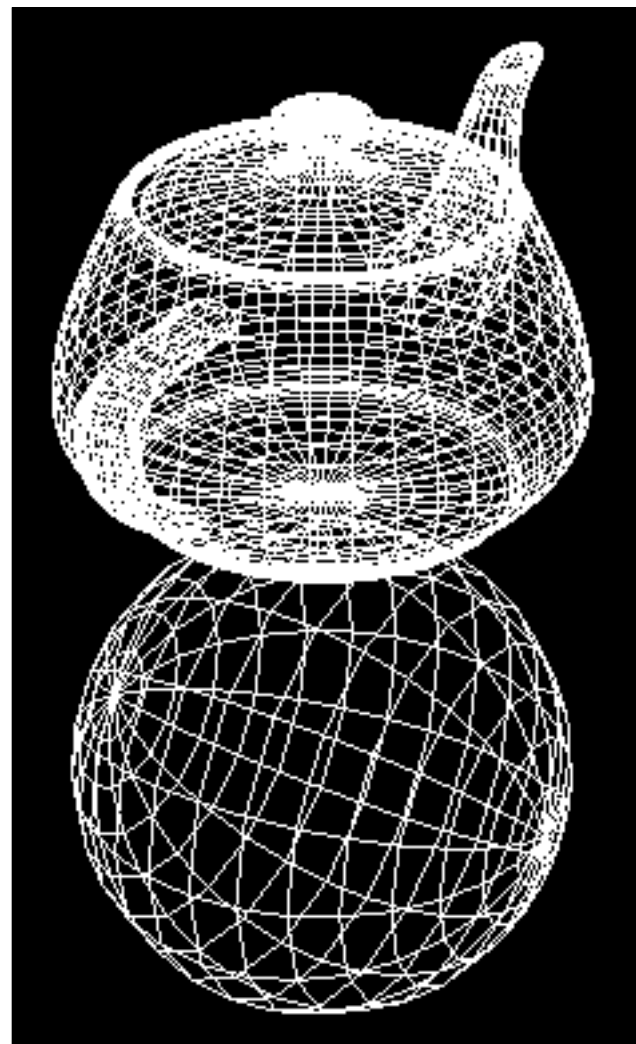
Accumulation buffer tricks: Obsolete, avoid

`glEnable(GL_MULTISAMPLE);` Preferred!

Can also be done by shaders. Usually unnecessary.



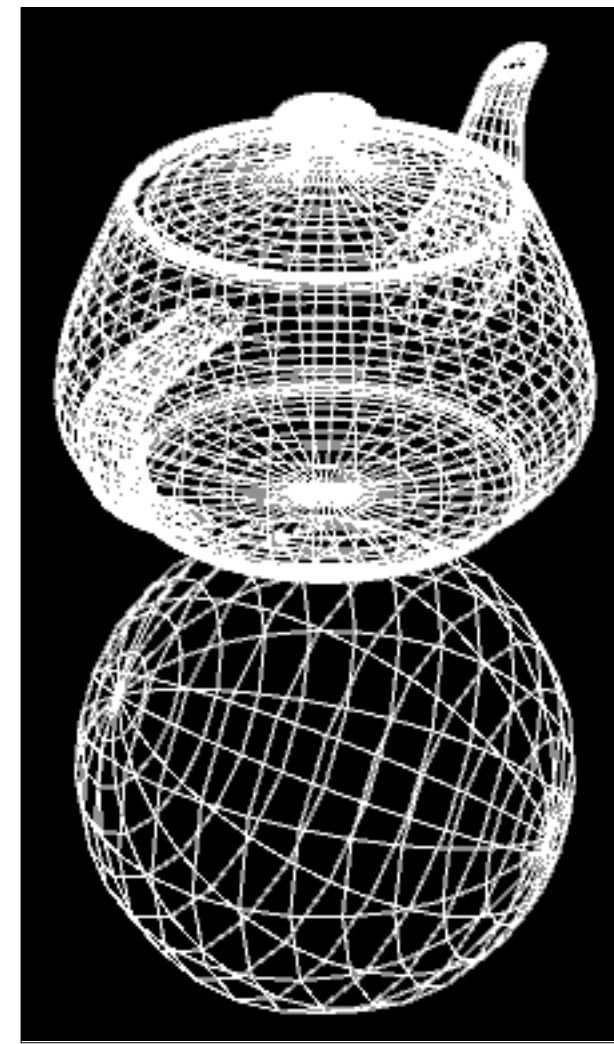
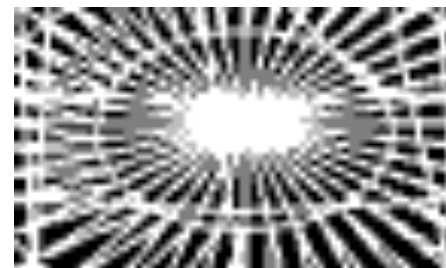
FSAA example



No AA



AA





Anti-aliasing

We will return to anti-aliasing in the ray-tracing part (with even more elaborate supersampling)



Off-line (?) rendering and global illumination

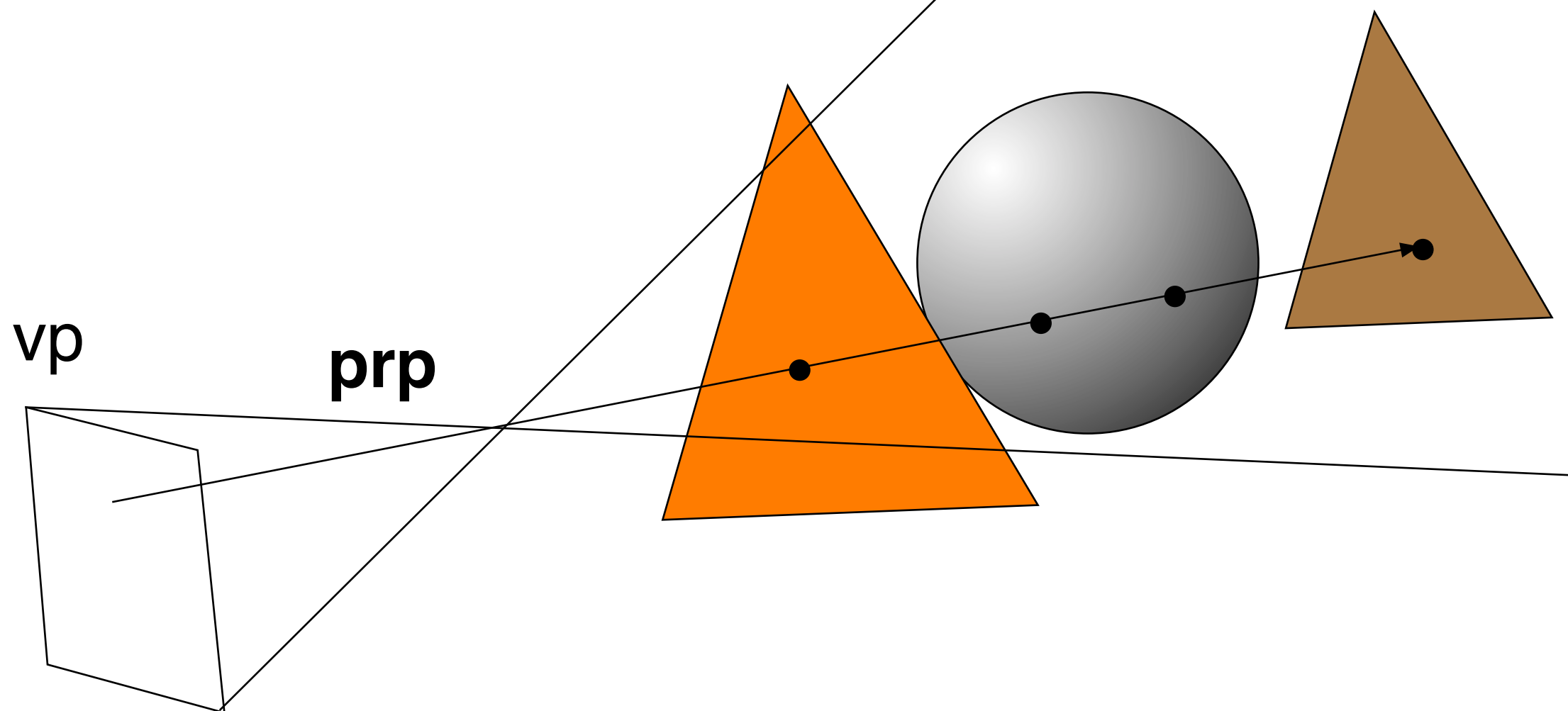
Performance demanding methods that give better lighting

Ray-casting
Ray-tracing
Radiosity
Photon mapping
Path tracing



Ray-casting

Follow rays from each pixel through the scene





Full 3D raycasting

for every pixel (x,y) in the image

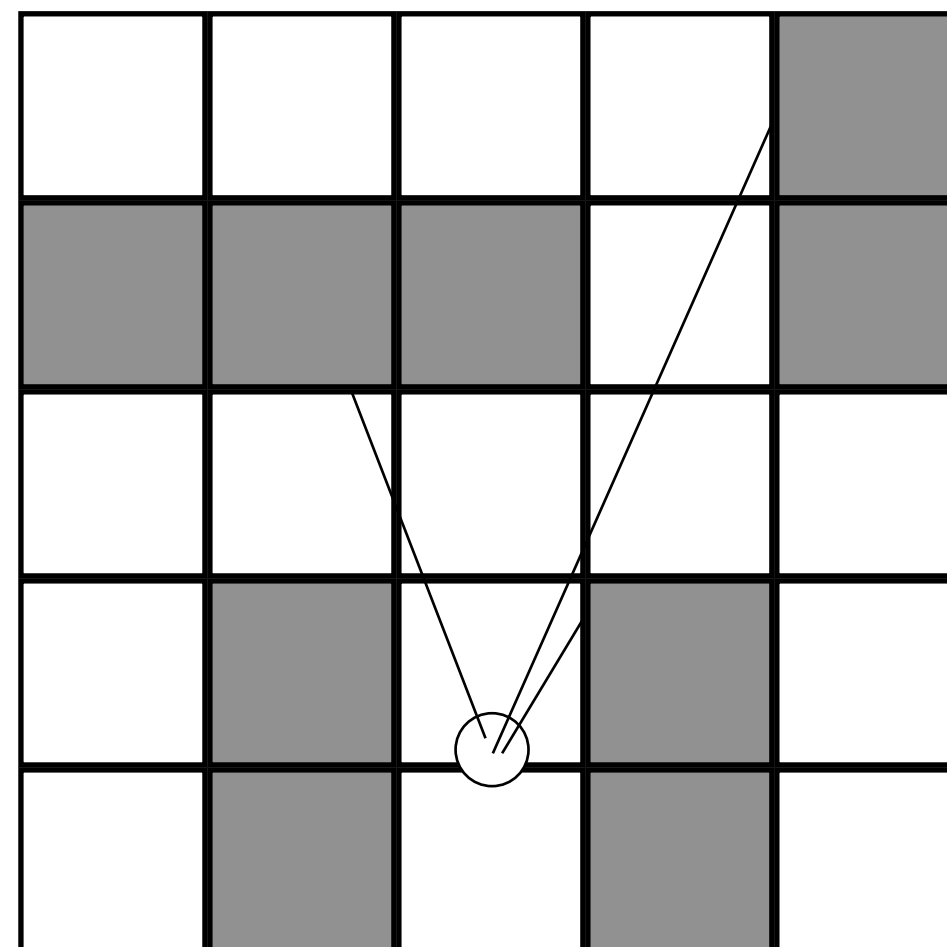
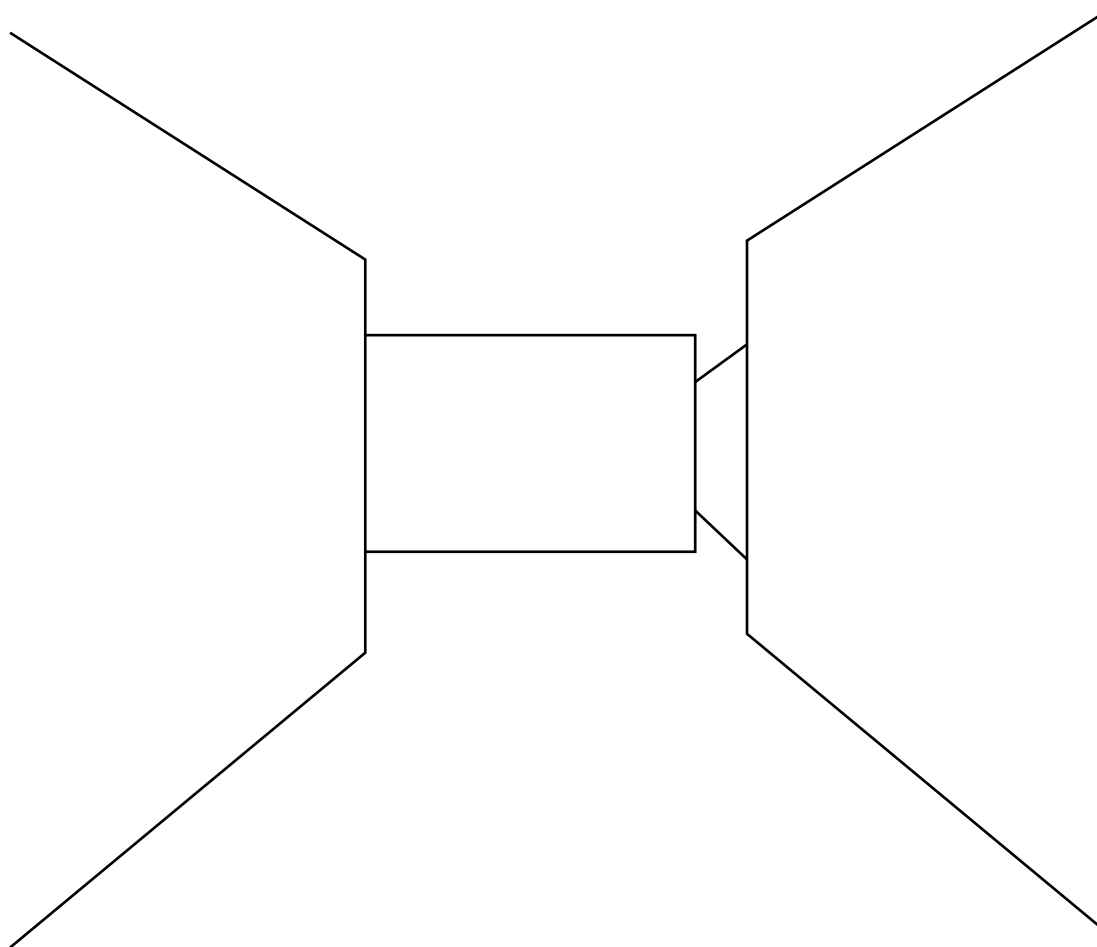
calculate a ray from the pixel through the camera (cop)
and through the scene

calculate intersecions with all objects in the scene

the pixel value is calculated from the closest
intersection found



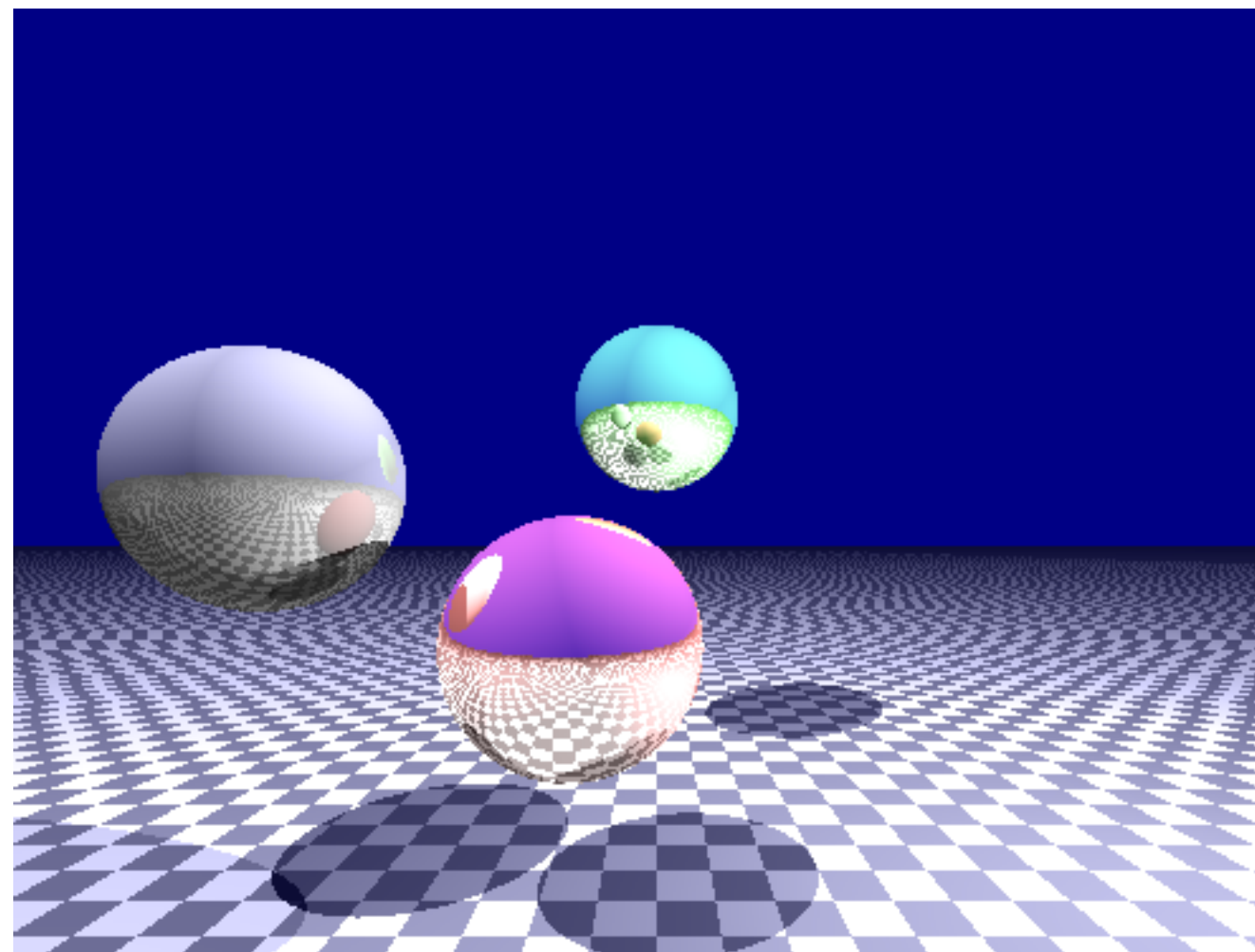
Raycasting in 2D or 3D grid ("Ray-marching")





Ray-tracing

The classic method for rendering realistic images of shiny and transparent objects with shadows.

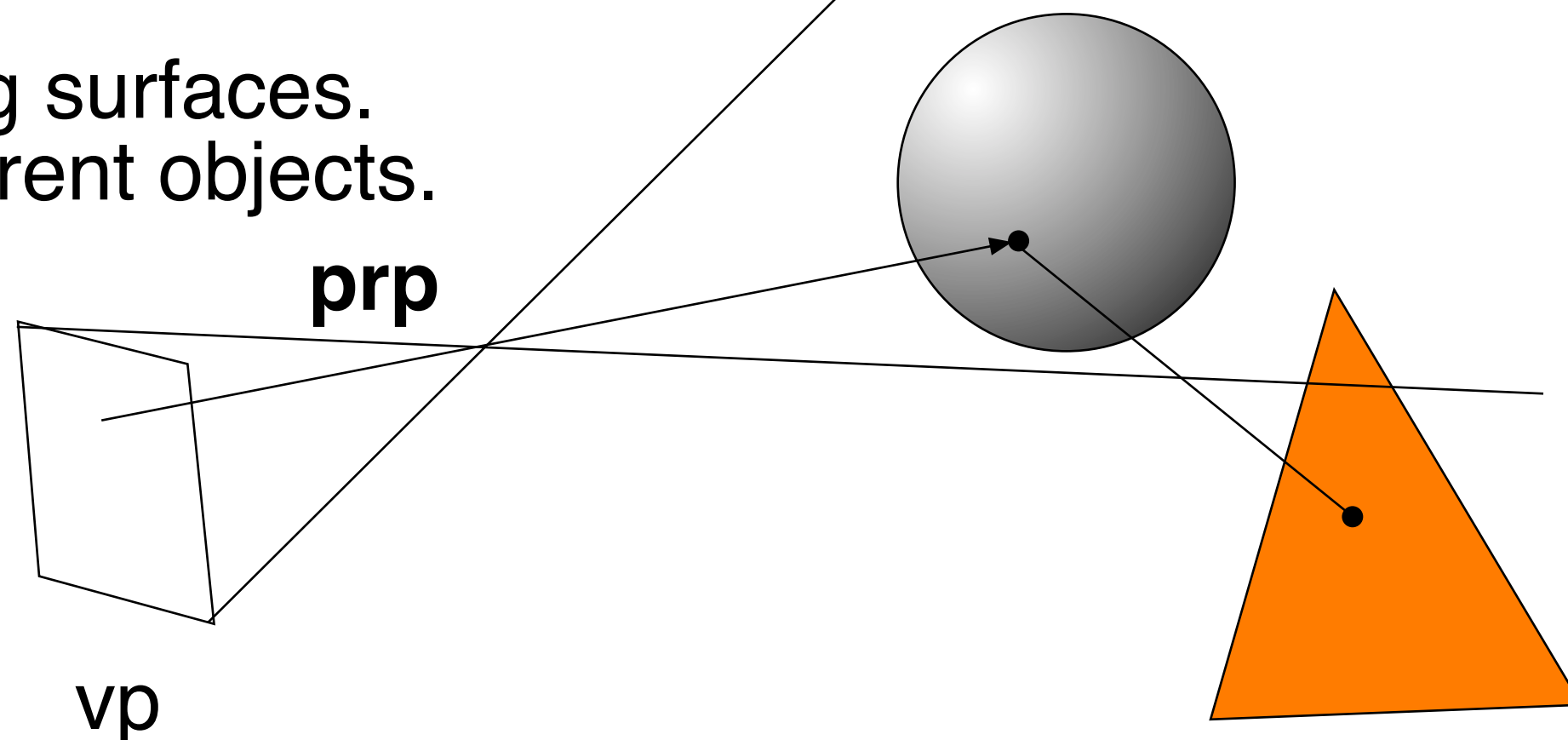




Ray-tracing basics

Cast rays from the camera as before.
From some surfaces, follow rays to the next surface.
This supports:

- Mirroring surfaces.
- Transparent objects.





At the intersection

Three things can happen when a ray intersects an object

- 1) Lighting, non-mirroring reflection
- 2) Reflection
- 3) Refraction



Non-mirroring reflection

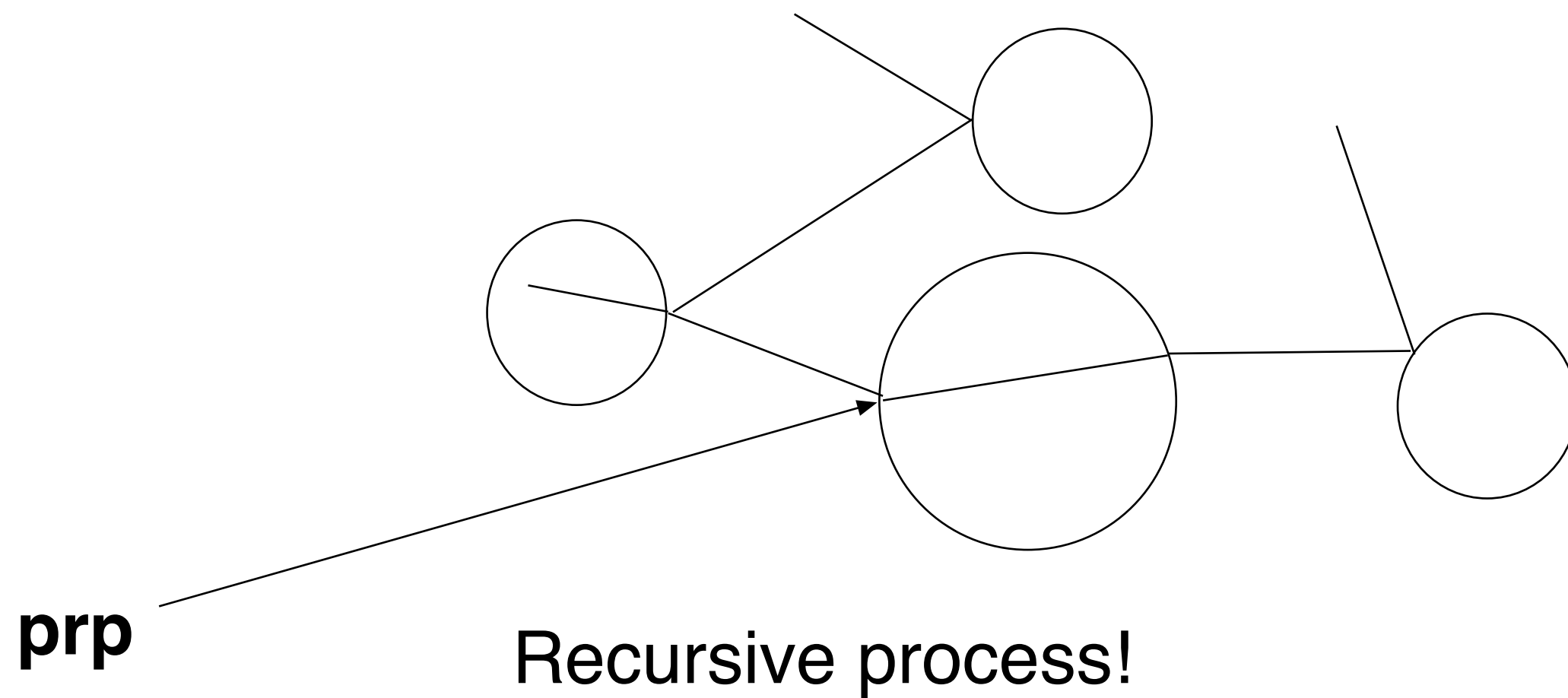
Apply e.g. the three-component light model

Ambient light
Diffuse reflection
Specular reflection

(or other model)

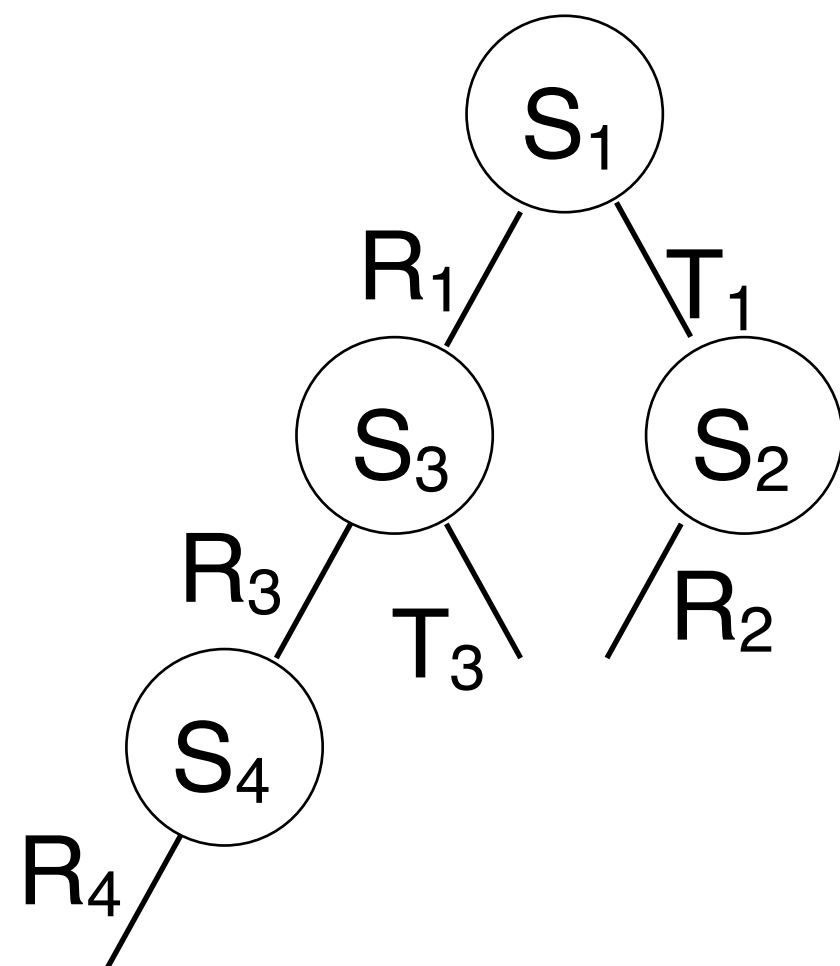


Reflection and refraction

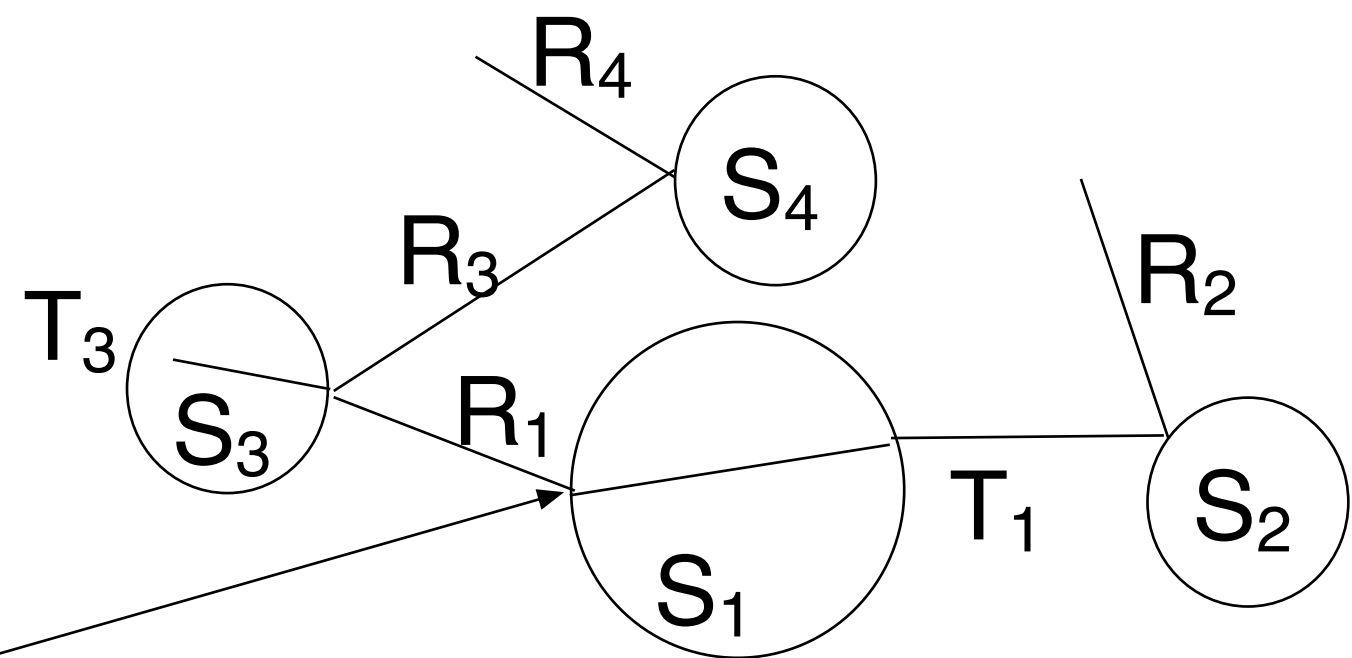




The ray-tracing tree



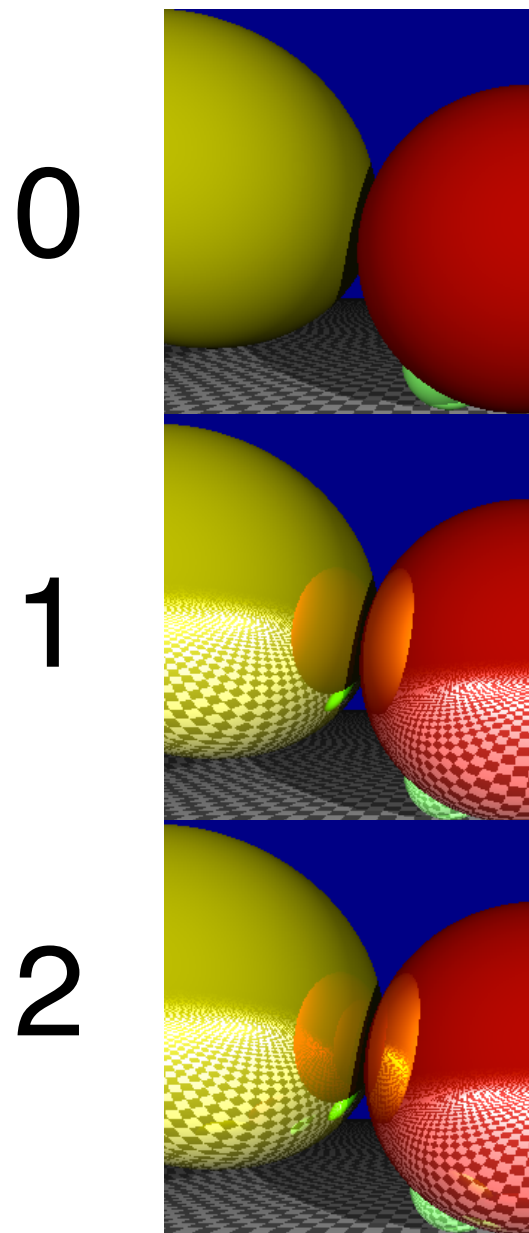
prp



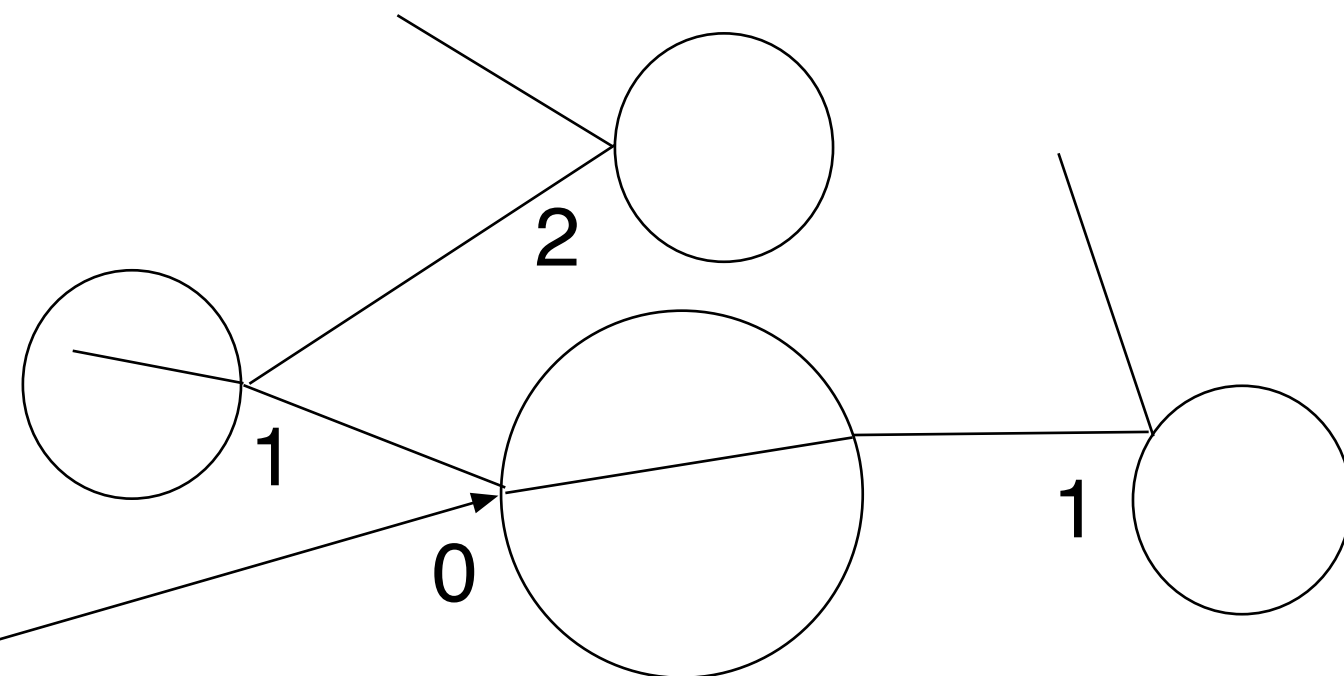


The maximum depth

How deep can the tree get?
How many reflections and refractions
are allowed?

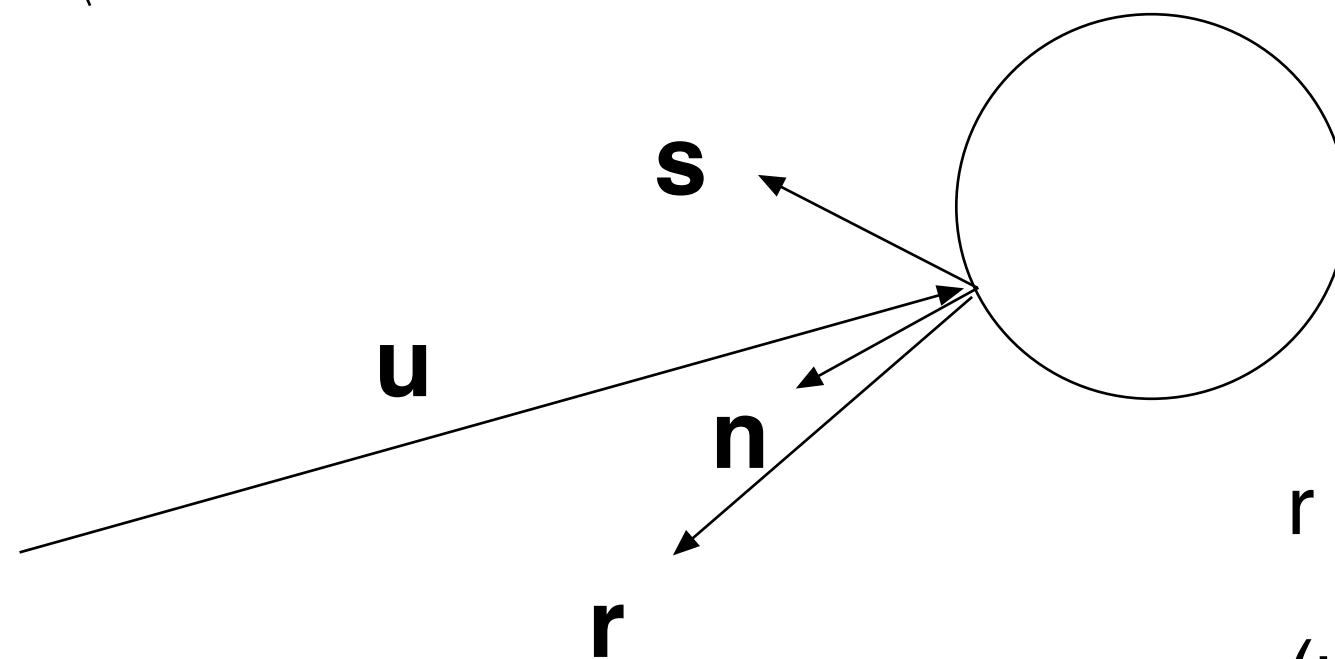
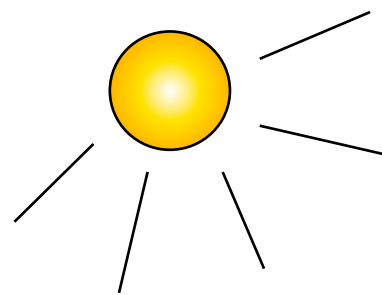


prp





Reflections



Look for more
contributions here

$$r = u - (2u \cdot n)n$$

(u = direction vector of the
incoming ray)



Refractions

Snell's law:

$$\eta_1 \sin\theta_1 = \eta_2 \sin\theta_2$$

Refraction index:

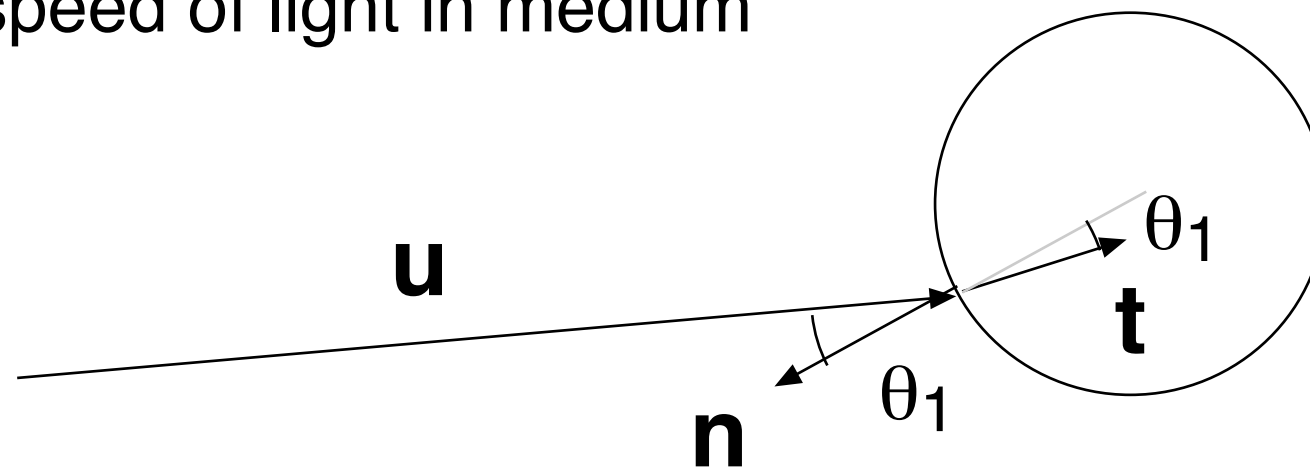
$$\eta = c / v$$

c: speed of light in vacuum

v: speed of light in medium

Transparent object

Look for more contributions here



Outgoing angle is given by incoming angles and the density of each material.



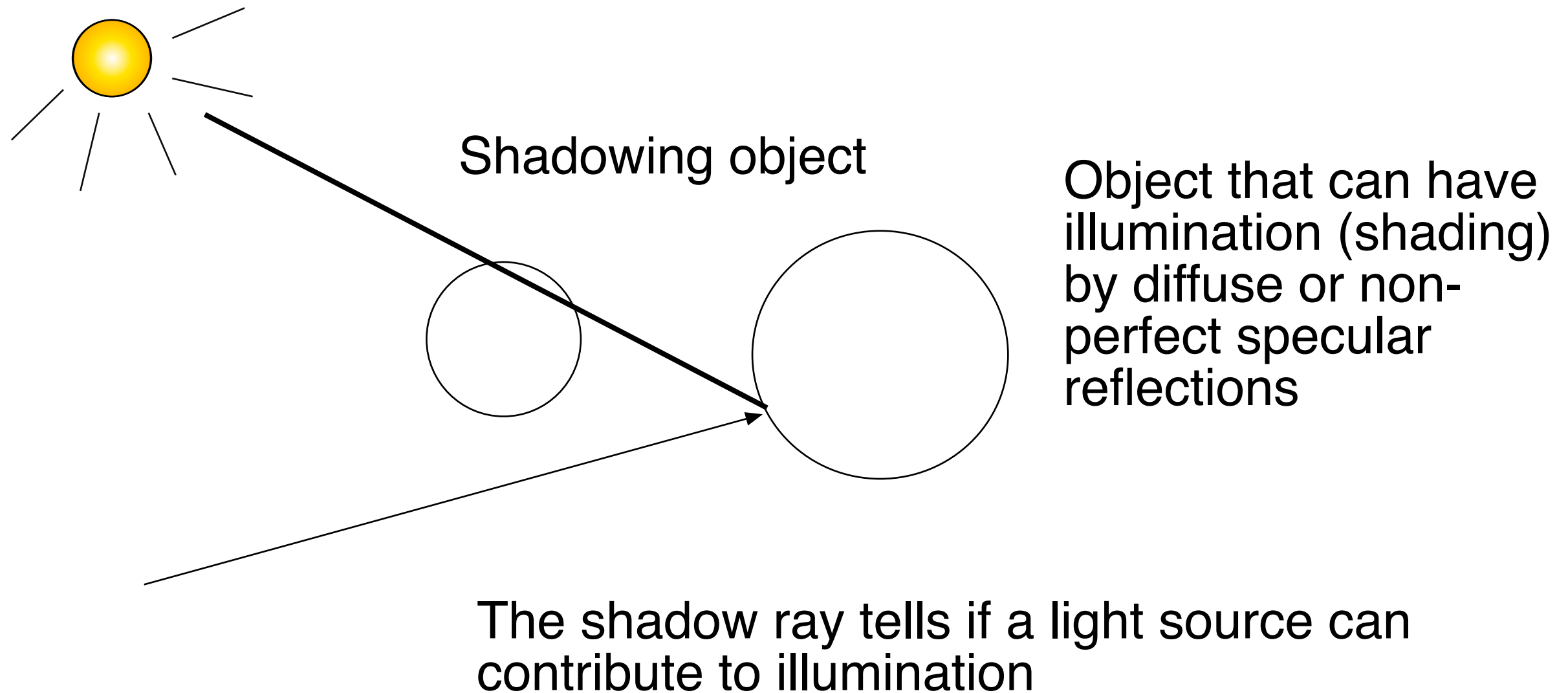
Summing up

The total intensity is the sum of

- ambient light
- diffuse reflections from each light source
- specular reflections from each light source
- mirroring reflections
- refractions



The shadow ray





Ray-surface intersections

Ray equation:

$$\mathbf{p} = \mathbf{p}_0 + \mu \mathbf{u}, \mu > 0$$

Combine with the equation of the surface.

Easiest surface: Sphere!

$$x^2 + y^2 + z^2 = r^2$$

Not quite as easy as for ray casting, since $\mathbf{p}_0$ can now be any point.



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```
function RayTrace(p0, u, depth)
  if depth > max then return BLACK
   $\mu := \text{FindIntersection}(p0, u)$  // Returns more data, see below
  if  $\mu \leq 0$  then return BACKGROUND_COLOR

   $I_{\text{local}} := 0$ 
   $I_R := 0$ 
   $I_T := 0$ 

  if  $k_a \neq 0$  and  $k_d \neq 0$  and  $k_s \neq 0$  then
     $I_{\text{local}} := k_a * I_a + \sum (\text{diffuse shading} + \text{specular shading})$ 
    // Sum is for all visible light sources

  if  $k_R \neq 0$  then
     $R := \text{CalculateReflection}(u, N)$ 
     $I_R := \text{RayTrace}(p0 + \mu * u, R, \text{depth}+1)$ 

  if  $k_T \neq 0$  then
     $T := \text{CalculateRefraction}(u, N, h_1, h_2)$ 
     $I_T := \text{RayTrace}(p0 + \mu * u, T, \text{depth}+1)$ 

  return  $I_{\text{local}} + I_R + I_T$ 
```



Problems in ray-tracing

- Computational load
- Aliasing
- Lack of realism due to extreme sharpness
- No indirect light



Reducing object-intersection calculations

The same large world problems showing up again!

Don't test everything, use some large world structure!



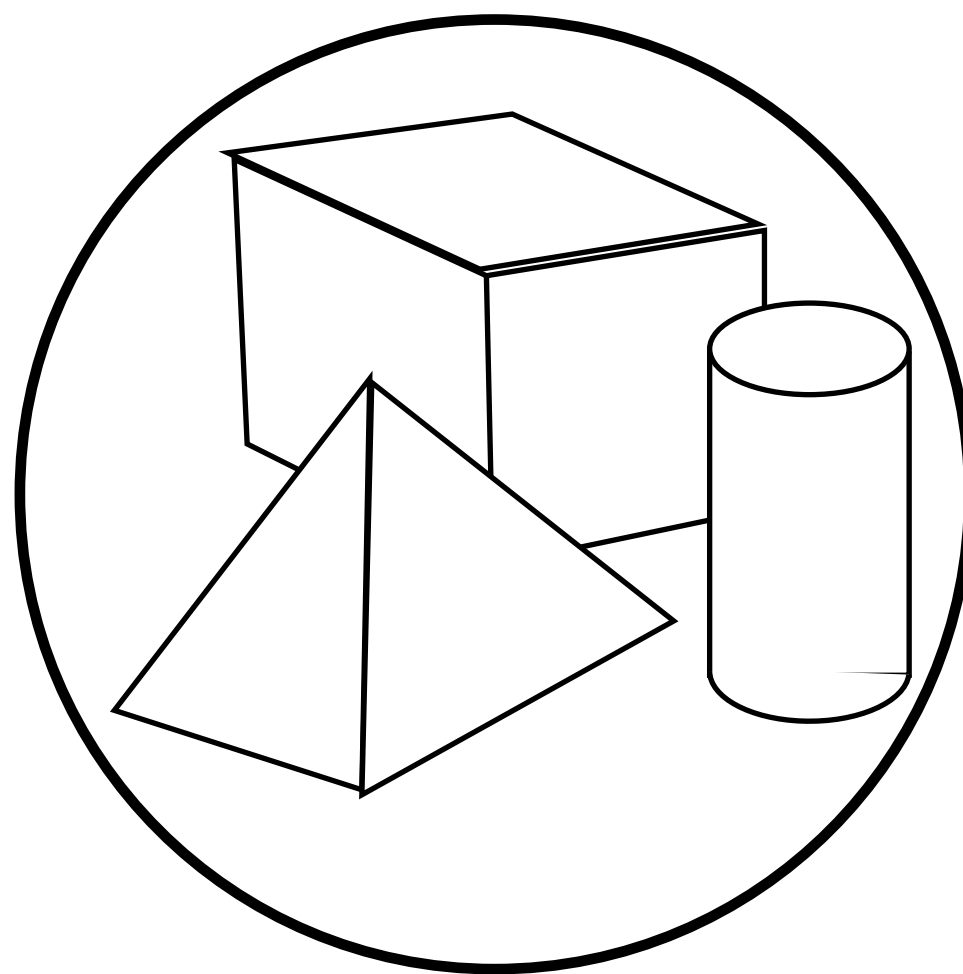
Reducing object-intersection calculations

Make sure that each ray doesn't have to be tested against all objects!

- Group objects within simple grouping surfaces (e.g. spheres or boxes)
- Divide space into cells
 - uniform or adaptive subdivision

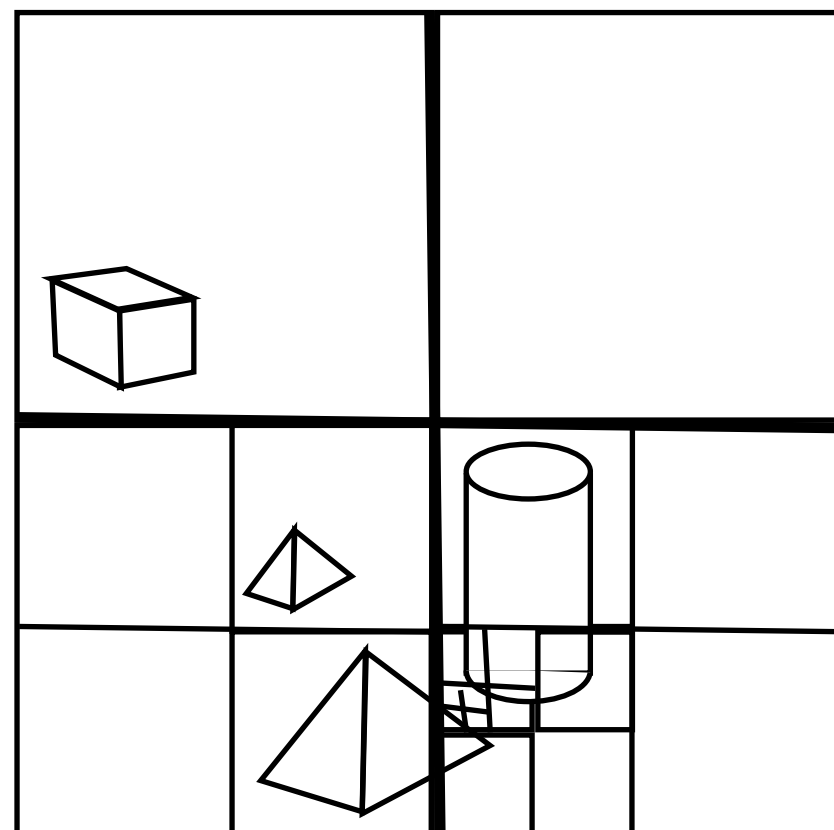


Group objects into simple bounding objects





Divide space into cells



(Quad-tree)

Same principle as in VSD and collision detection



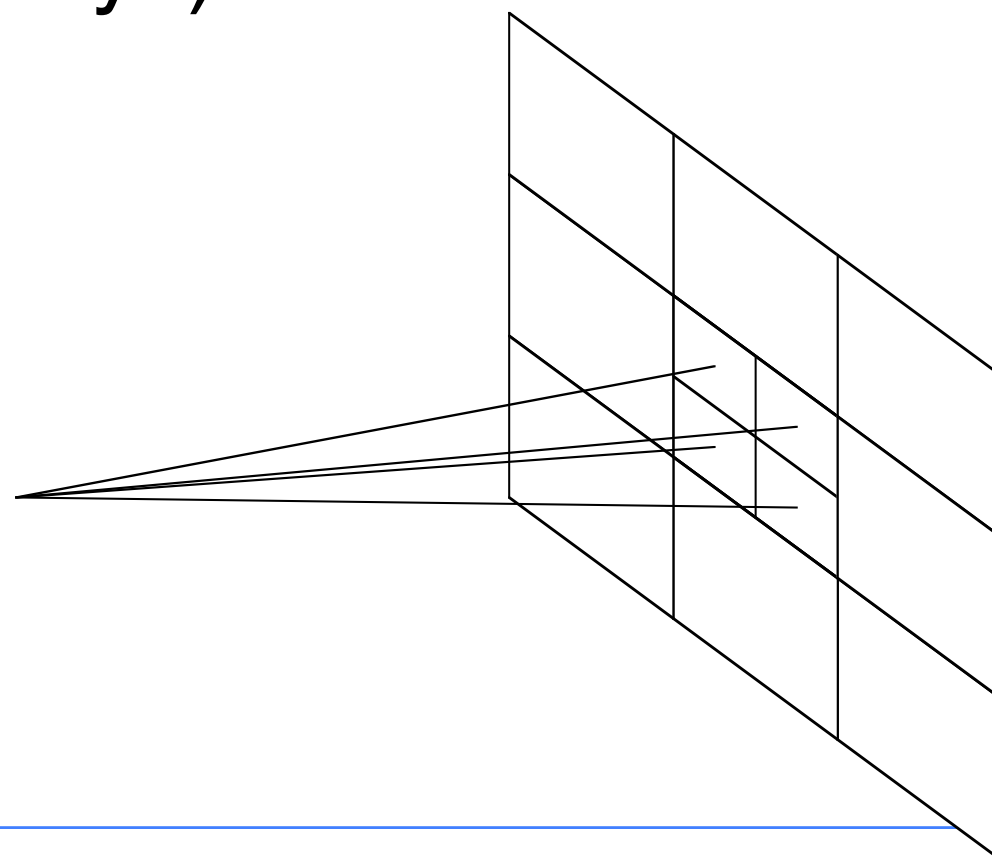
Anti-aliasing in ray-tracing

- Supersampling
- Distributed ray tracing



Supersampling in ray-tracing

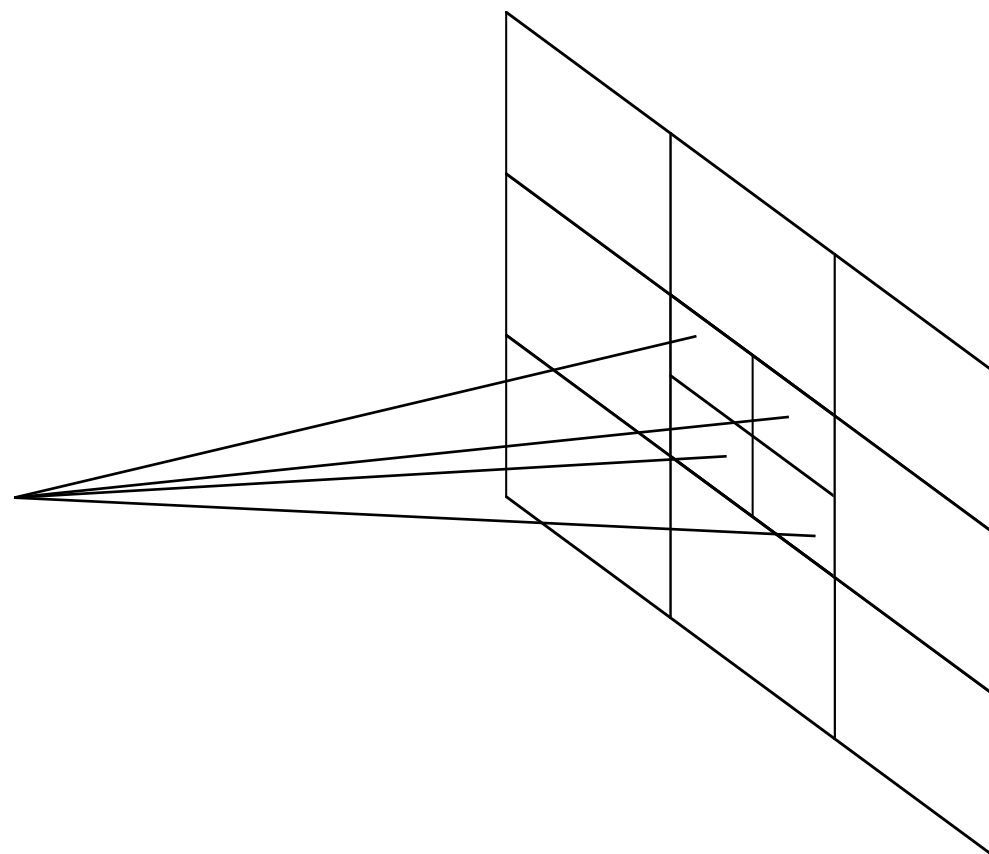
Send several rays for each pixel. (Typical for fast rendering: 4 rays)





Distributed ray-tracing

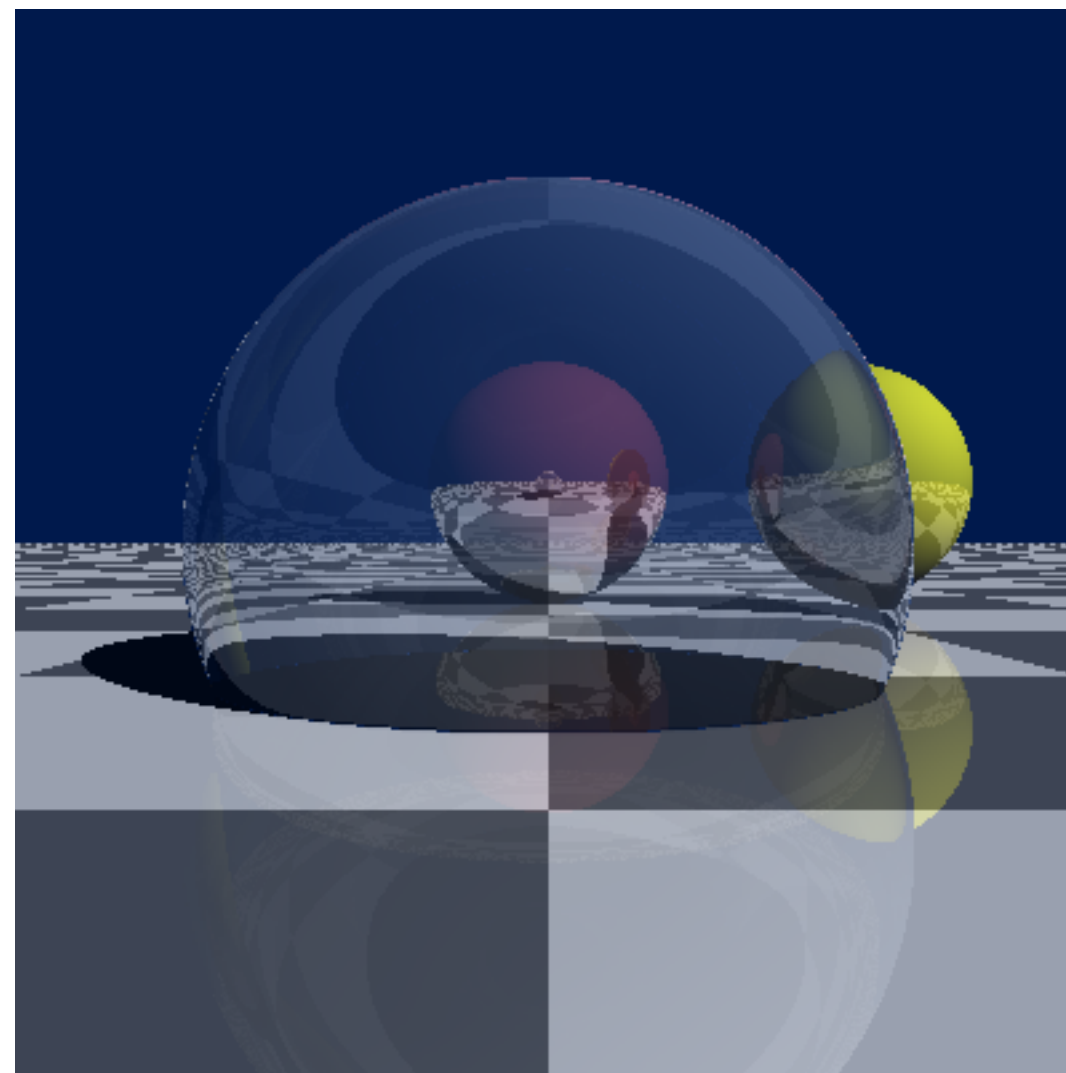
Rays (multiple per pixel) are sent in a randomized pattern. Aliasing is replaced by noise!





Anti-aliasing in ray-tracing

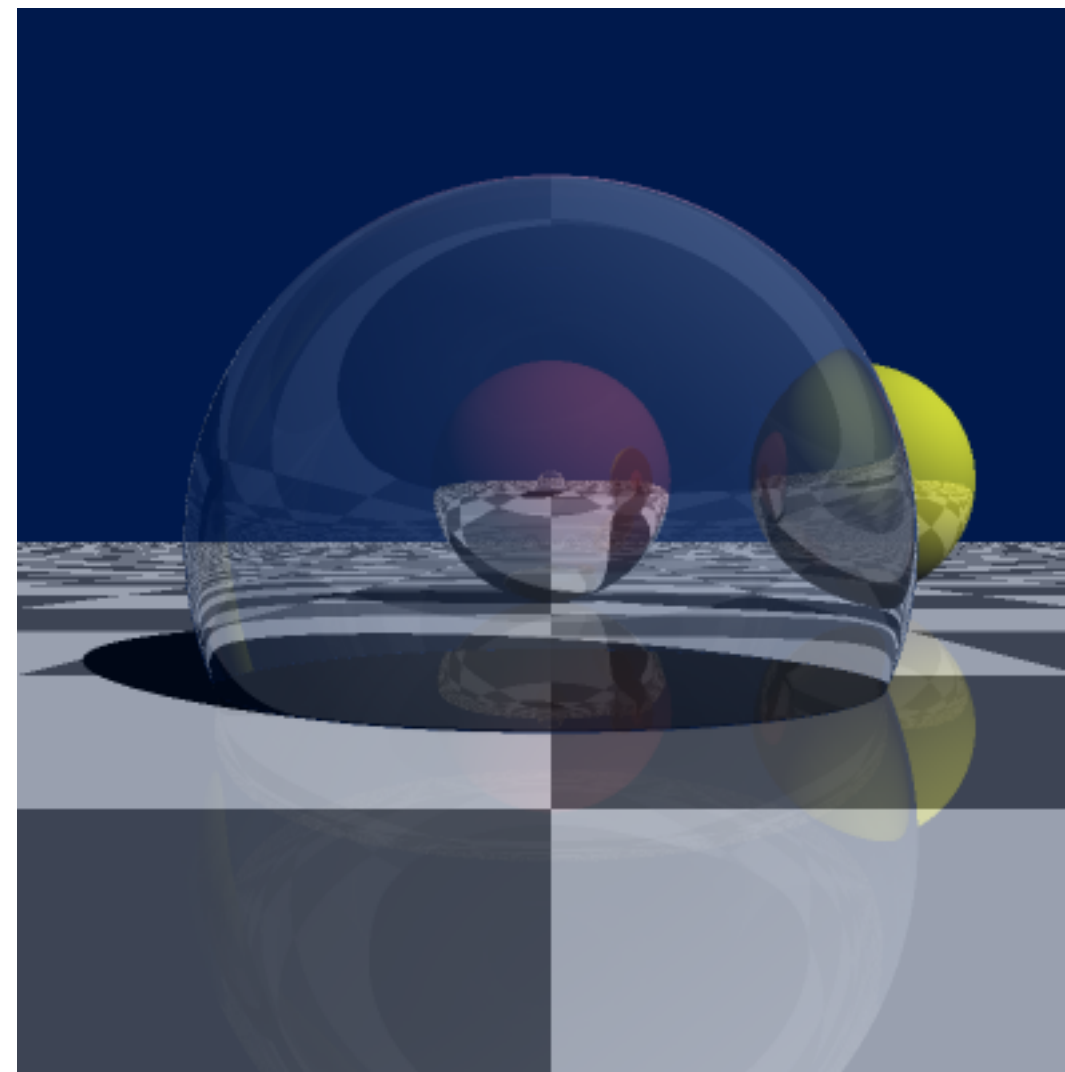
Example:
Without
anti-aliasing





Anti-aliasing in ray-tracing

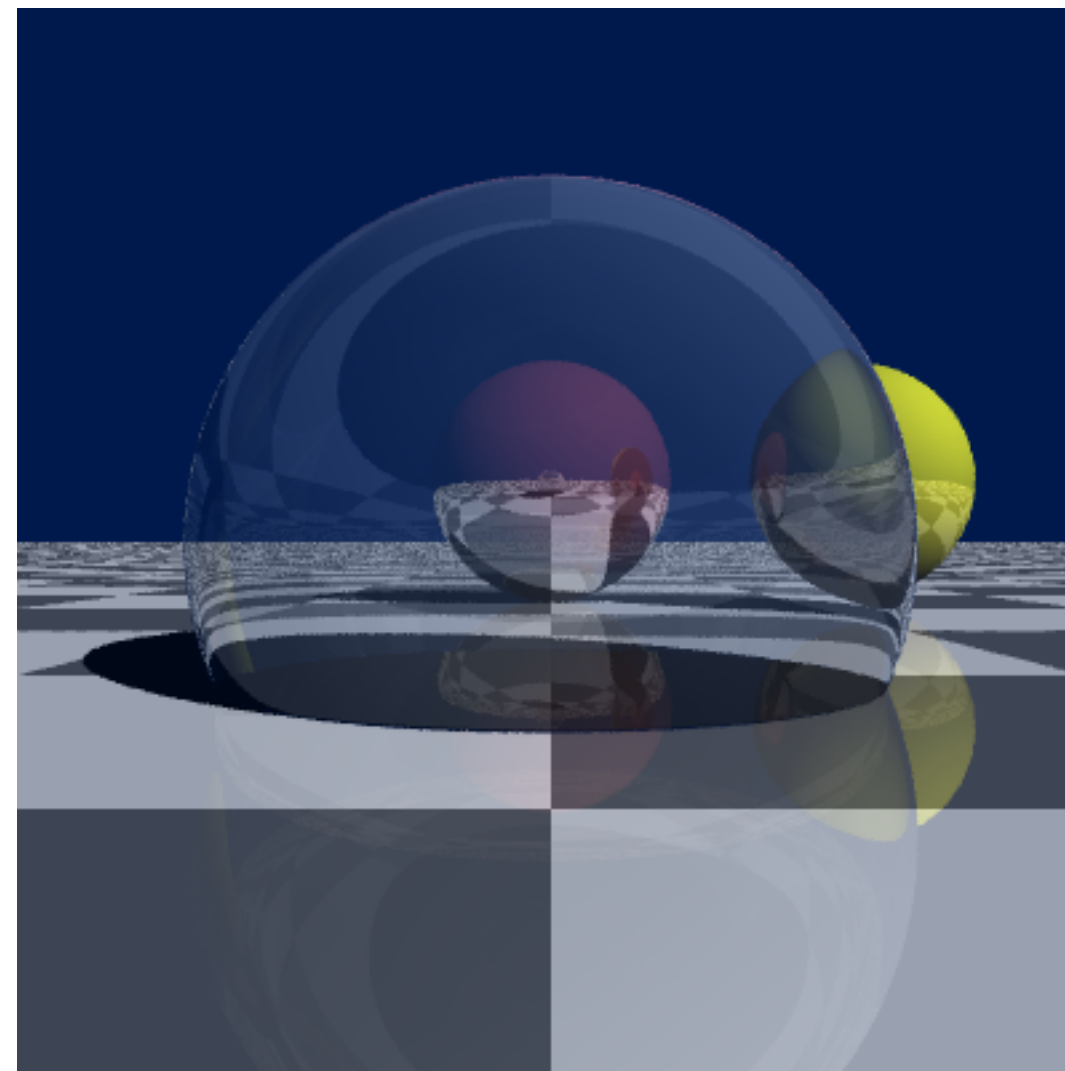
Example:
Super-
sampling
(2x2)





Anti-aliasing in ray-tracing

Example:
Distributed
raytracing
(2x2)





Anti-aliasing in ray-tracing

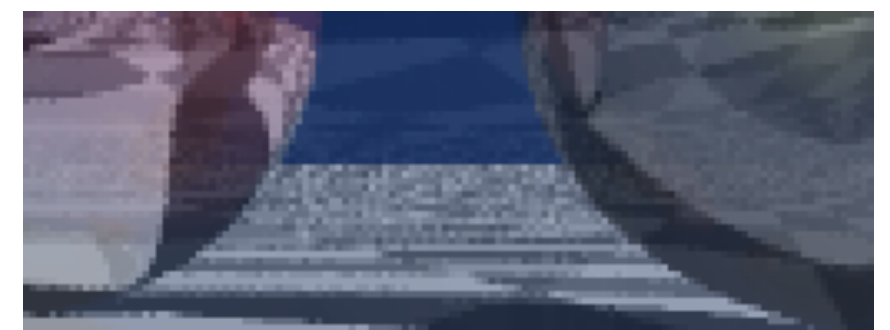
Zoomed-in detail



Without
anti-alias



Super-
sampling



Distributed
raytracing



Distributed ray-tracing

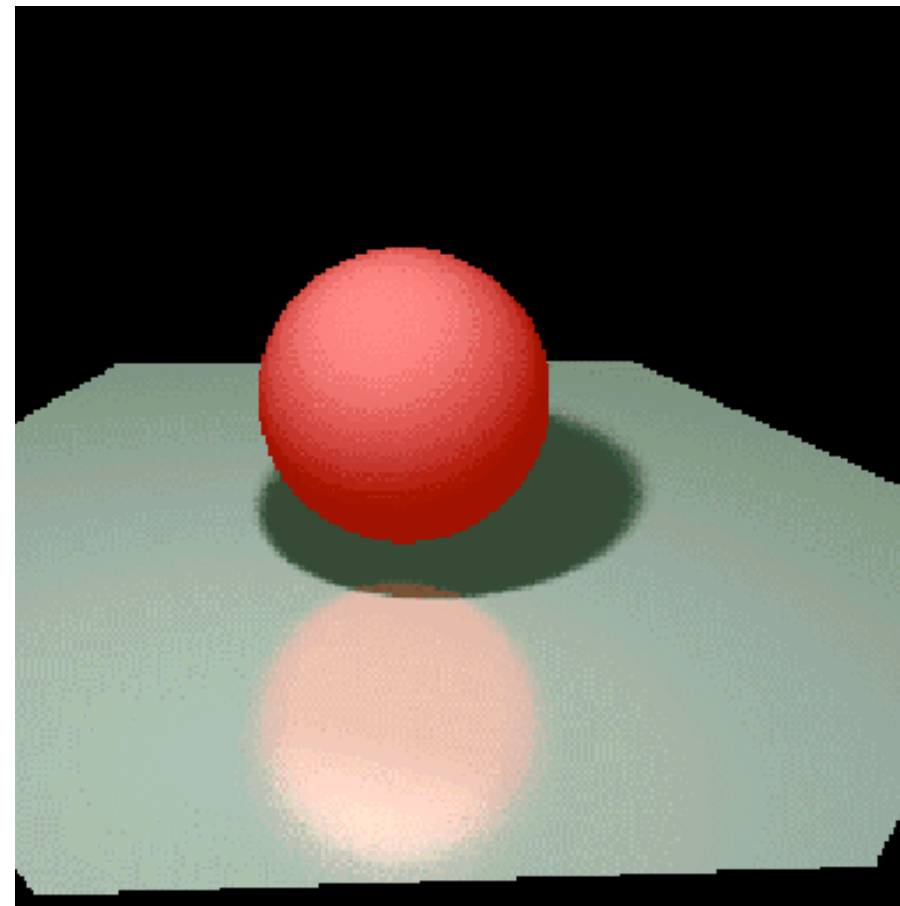
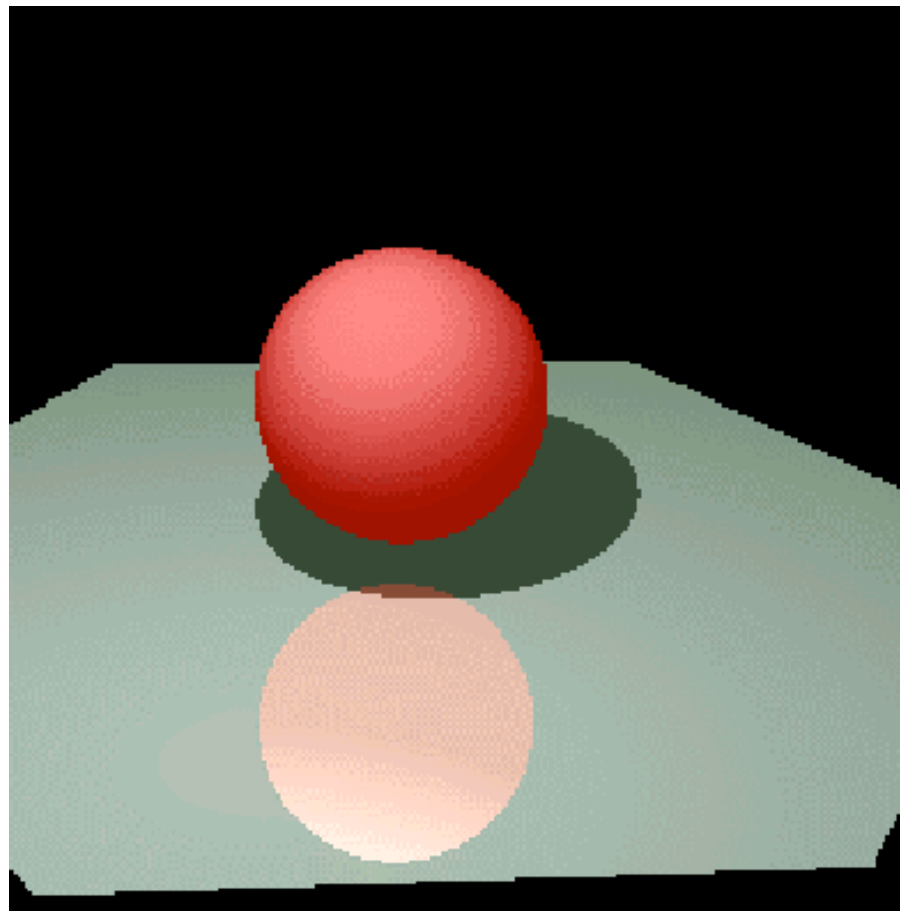
Anti-aliasing through stochastic sampling.

Also used for:

- gloss (fuzzy reflections)
- fuzzy translucency
- soft shadows
- depth of field (out-of-focus effect)
- motion blur



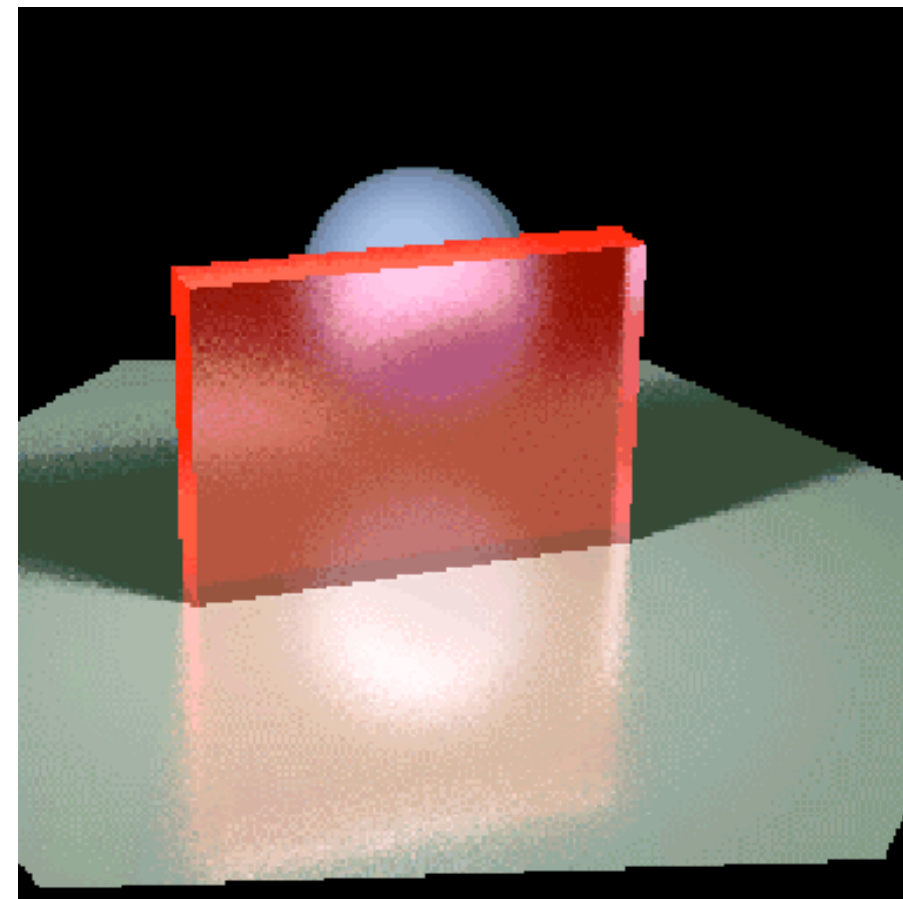
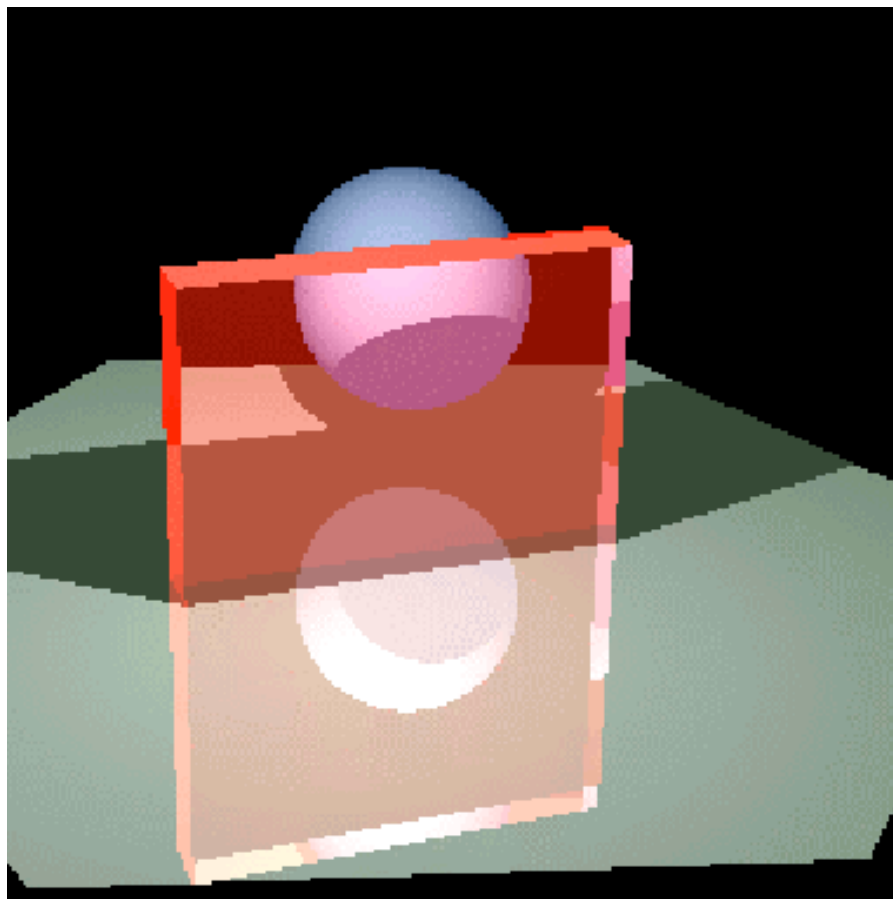
Gloss (fuzzy reflections)



Jittering reflection ray



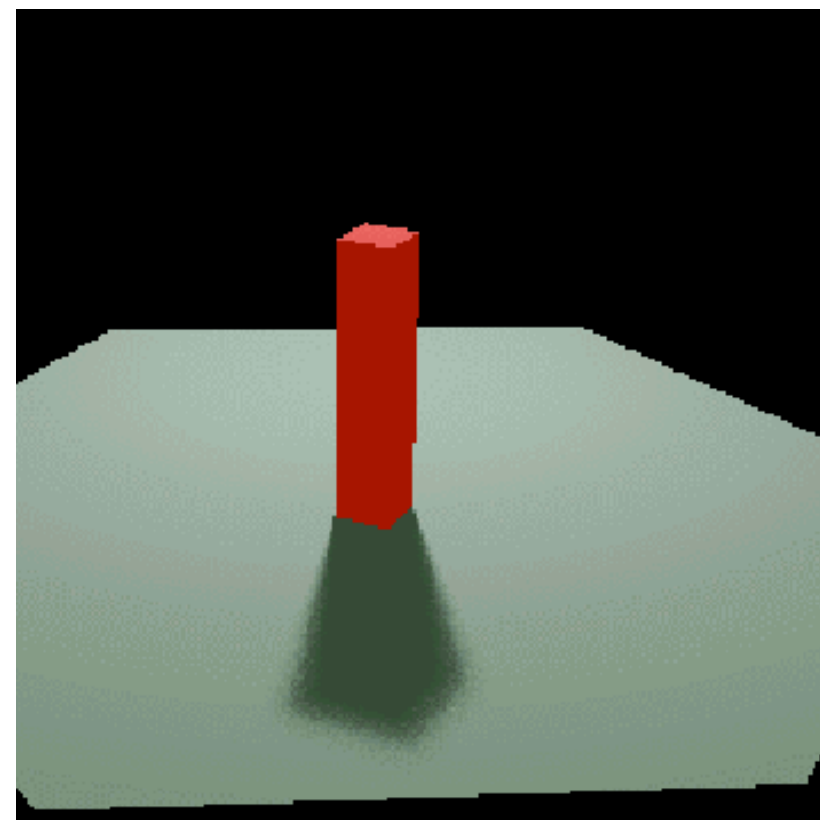
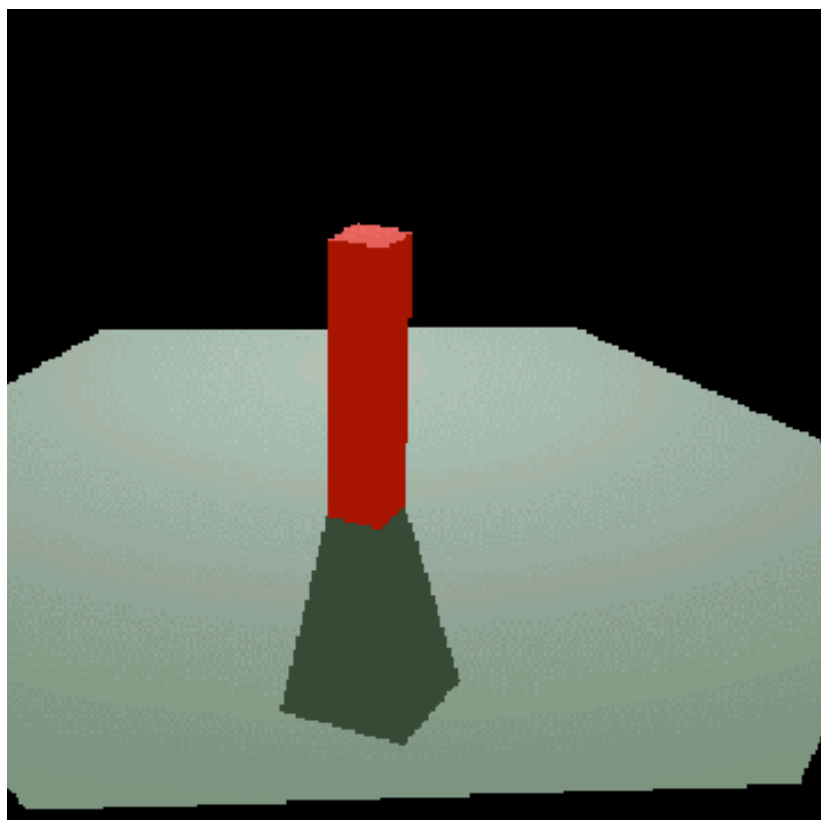
Fuzzy translucency



Jittering refraction ray



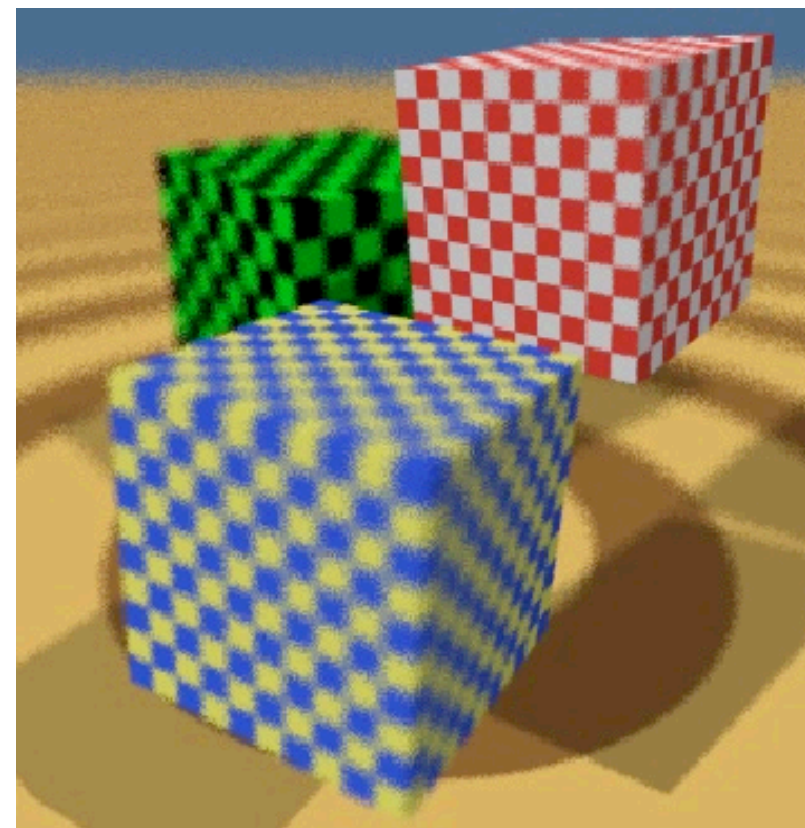
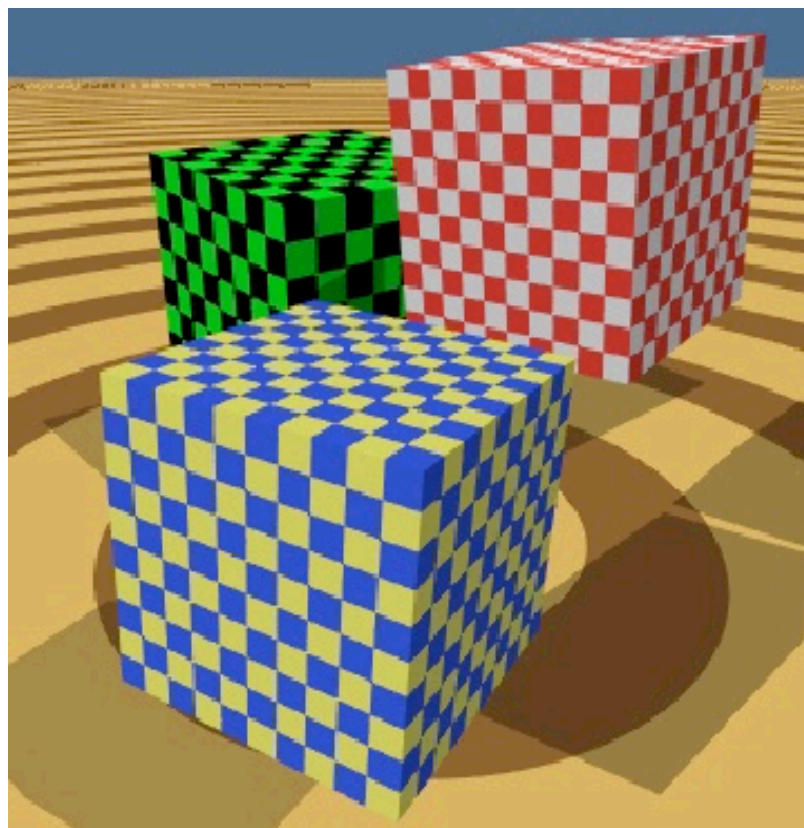
Soft shadows



Jittering shadow ray



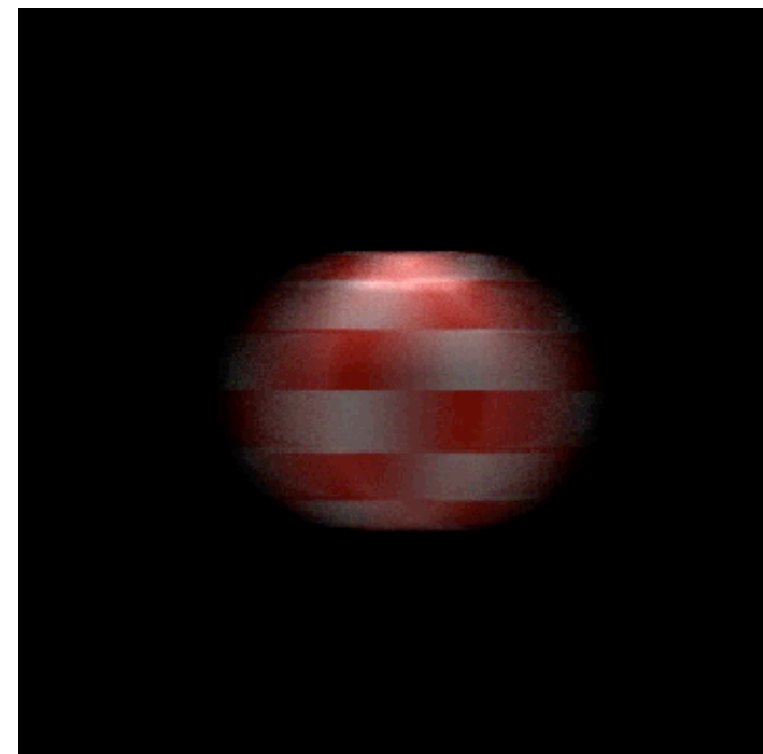
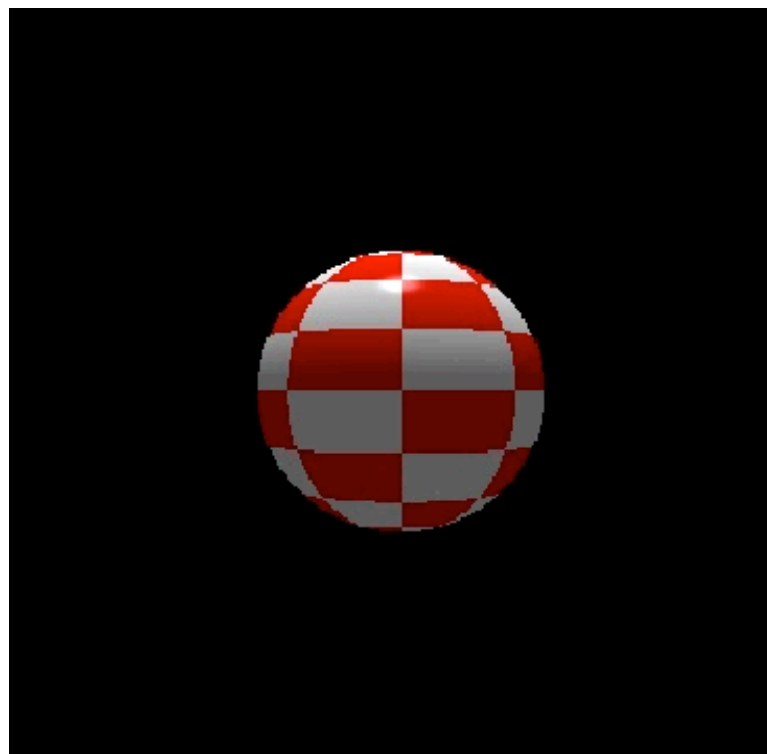
Depth of field (out-of-focus effect)



Jittering main ray (simulates the size of the lens)



Motion blur



Jittering time



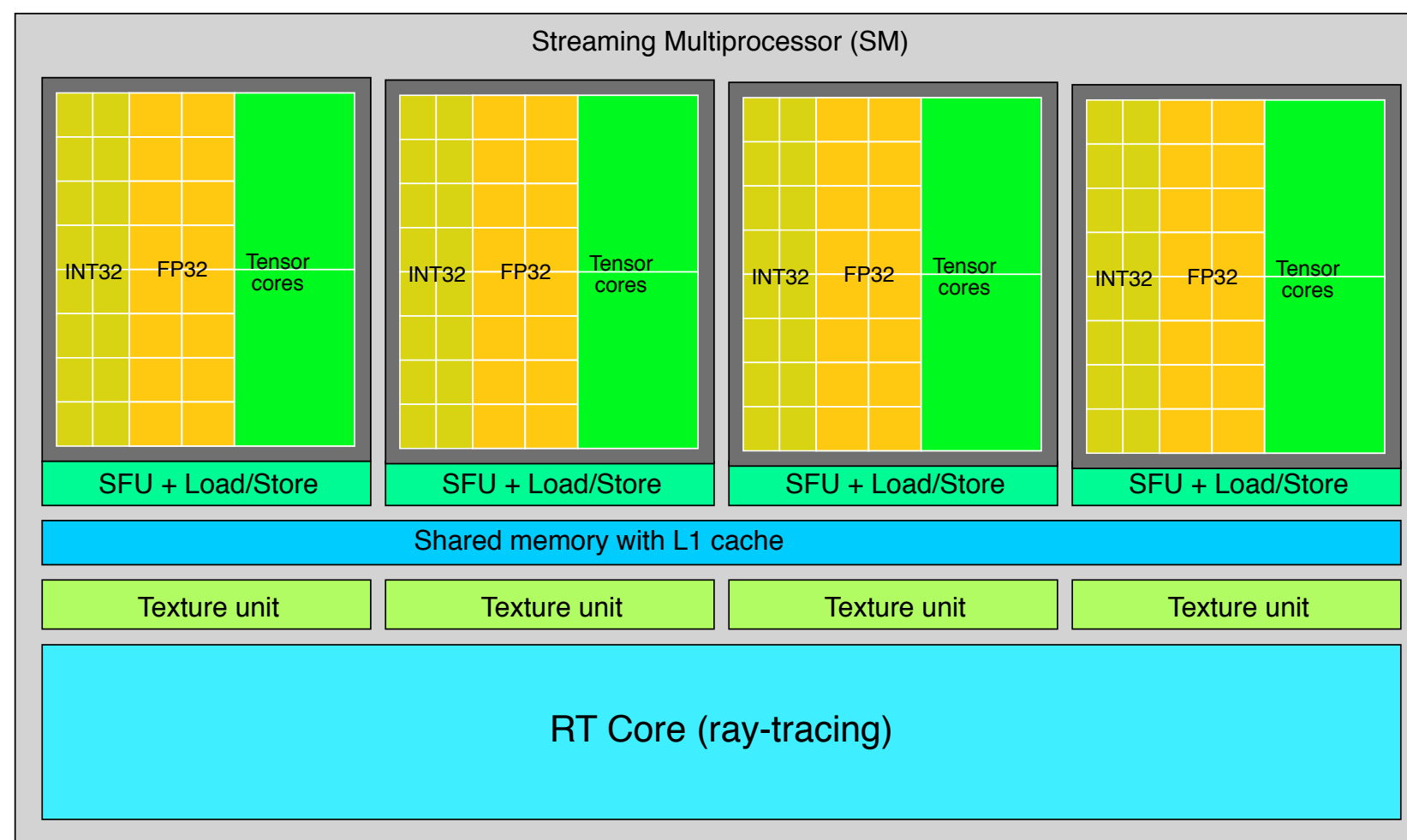
Ray-tracing in the fragment shader

Does not fit the GPU rendering model!

- Recursion not allowed! Use lists instead!
- Limited amount of data available to a shader - needs to use textures or other buffers for input

Not impossible but we may need to use tricks, multi-pass rendering etc.

Ray-tracing on GPU often done in "GPU computing languages" (CUDA, OpenCL) rather than shaders.



**The Turing
GPU and
later**

RTX boards

RT cores = Raytracing cores

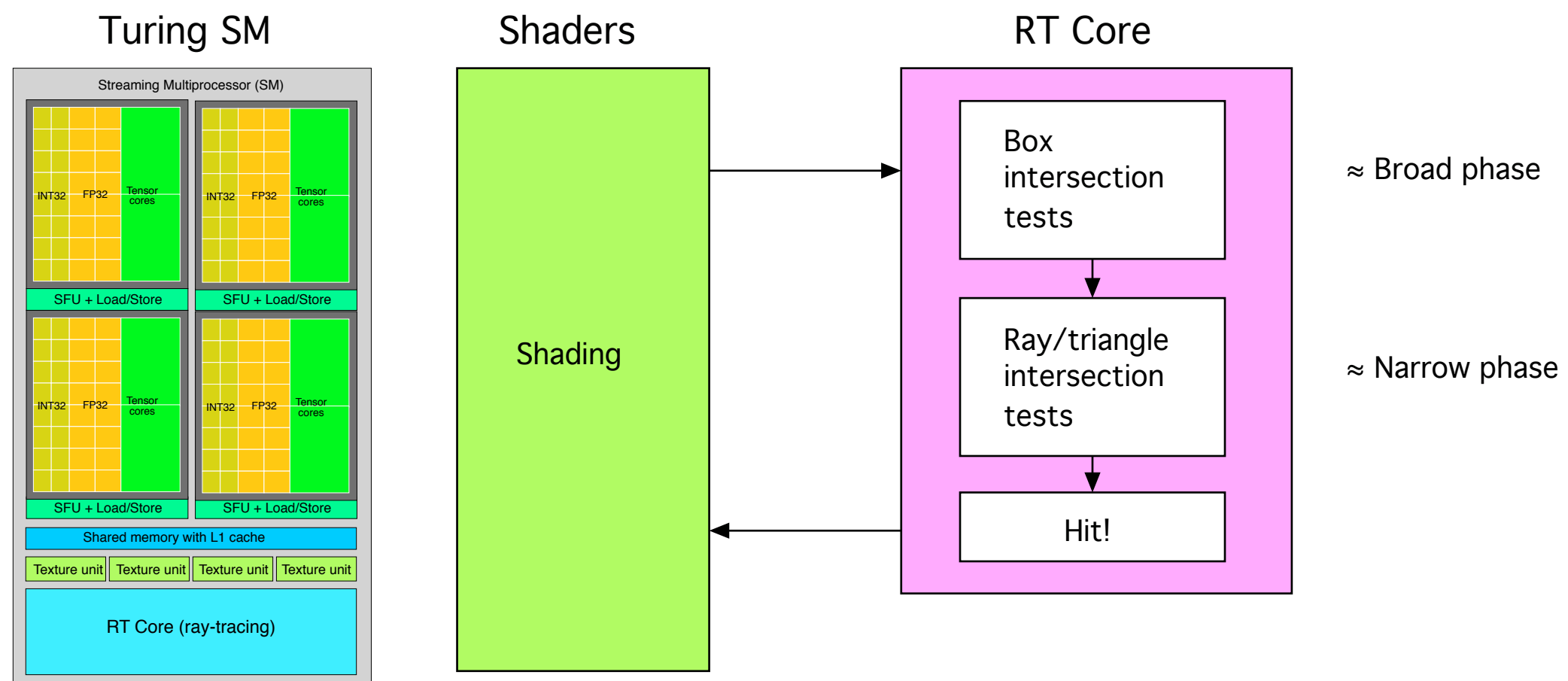
Special-purpose hardware in RTX GPUs

Available through Vulkan, CUDA etc.



RT cores

Accelerates ray-box and ray-triangle calculations





Conclusions on ray-tracing

No longer an offline method!

Moving into real-time now!

Variations of ray-tracing a hot topic.

But... how about global illumination?

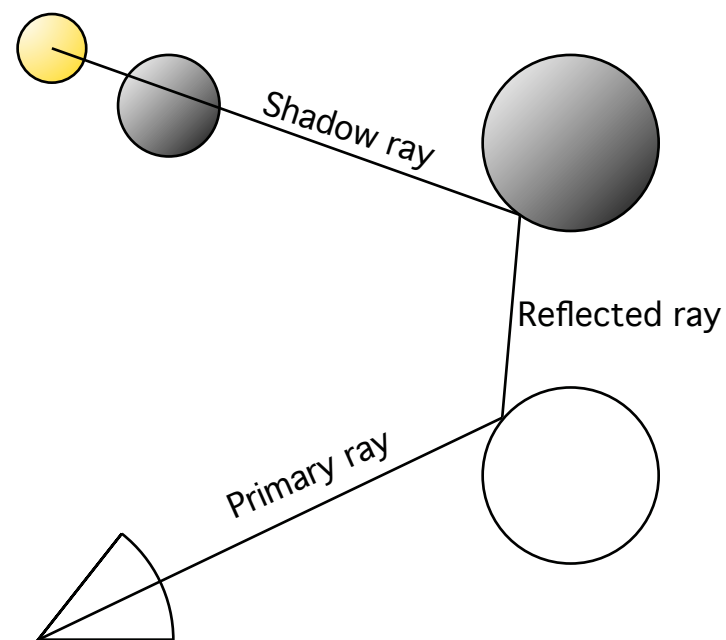
- Radiosity
- Photon mapping
- Path tracing



Ray-tracing limitations

Trace rays from the camera. Reflect, refract.

Shadow rays check visibility from surface to light source.



Only direct light can be handled this way!

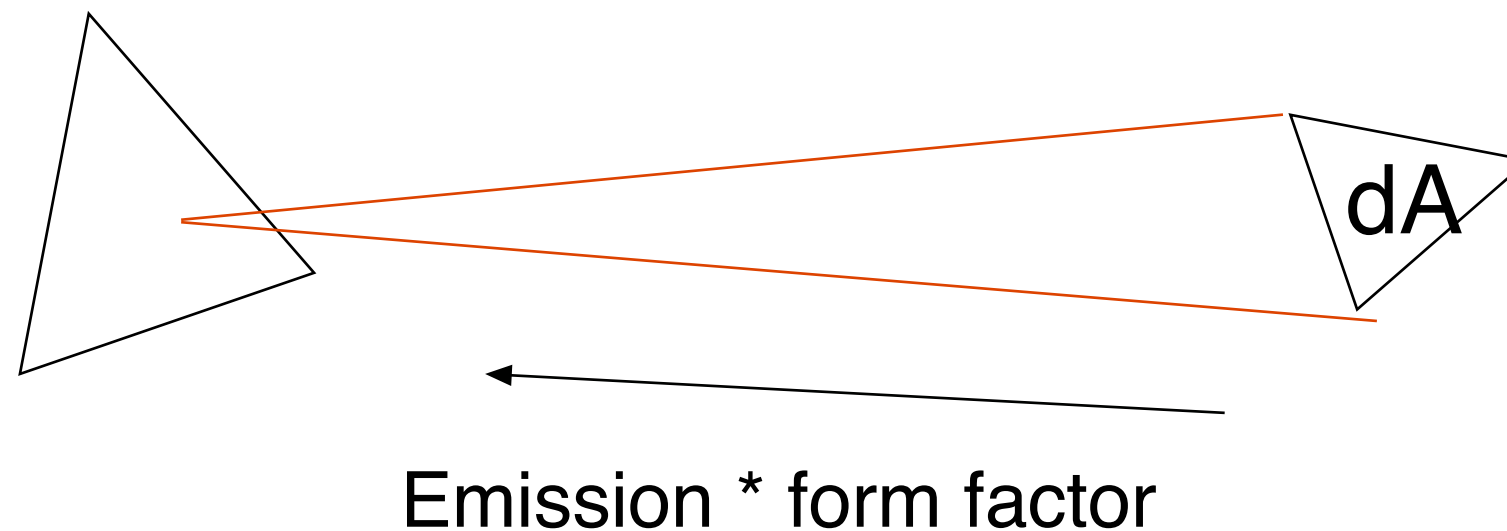


Radiosity method

Models indirect light from surface to surface. Only diffuse surfaces.

Incoming light is summed to outgoing. Amount of light based on the solid angle, the form factor.

Accumulate, repeat to approach correct light.





The model

A surface emits energy that is a sum of reflected and emitted energy:

Energy * area = emitted + reflected

$$B_k * dA_k = E_k * dA_k + R_k \int B_j * F_{kj} * dA_k$$

Emitted light (true light sources only)

Form factor between j and k

Outgoing energy from the surface element j

Reflectivity



Simplified to discrete patches

$$B_k = E_k + R_k * \sum B_j * F_{jk}$$

=> Equation system!

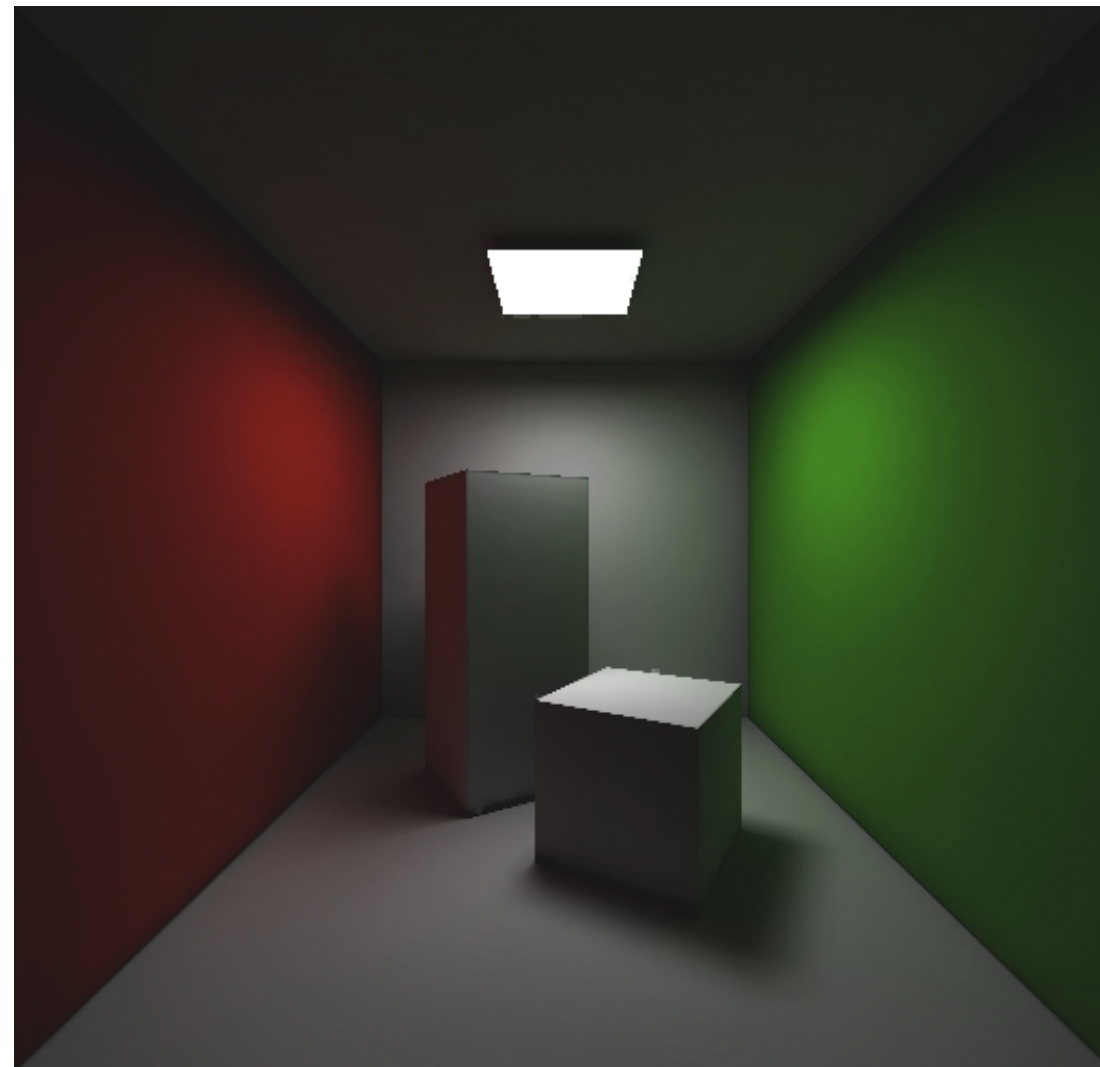
- 1) Solve equation system! Can be done incrementally.
- 2) We must interpolate between patches (e.g. Gouraud shading)
- 3) The form factors F_{jk} must be calculated



Example

TSBK03 project on
progressive
refinement

(Variant of Cornell
Box, standard scene
for illumination)





More global illumination models

Very important problem, much research!

- Photon mapping
 - Path tracing
- Approximation by proximity measurements
 - Hybrid models
- Many variants and parallel implementations



Photon mapping

"Backwards ray-tracing"

Applies "backwards" light (from light sources) to measure how light is scattered over a scene

Gives a good measure of indirect light



Photon Mapping

Follow rays from light source with ray-tracing methods

Accumulate light in "photon maps"

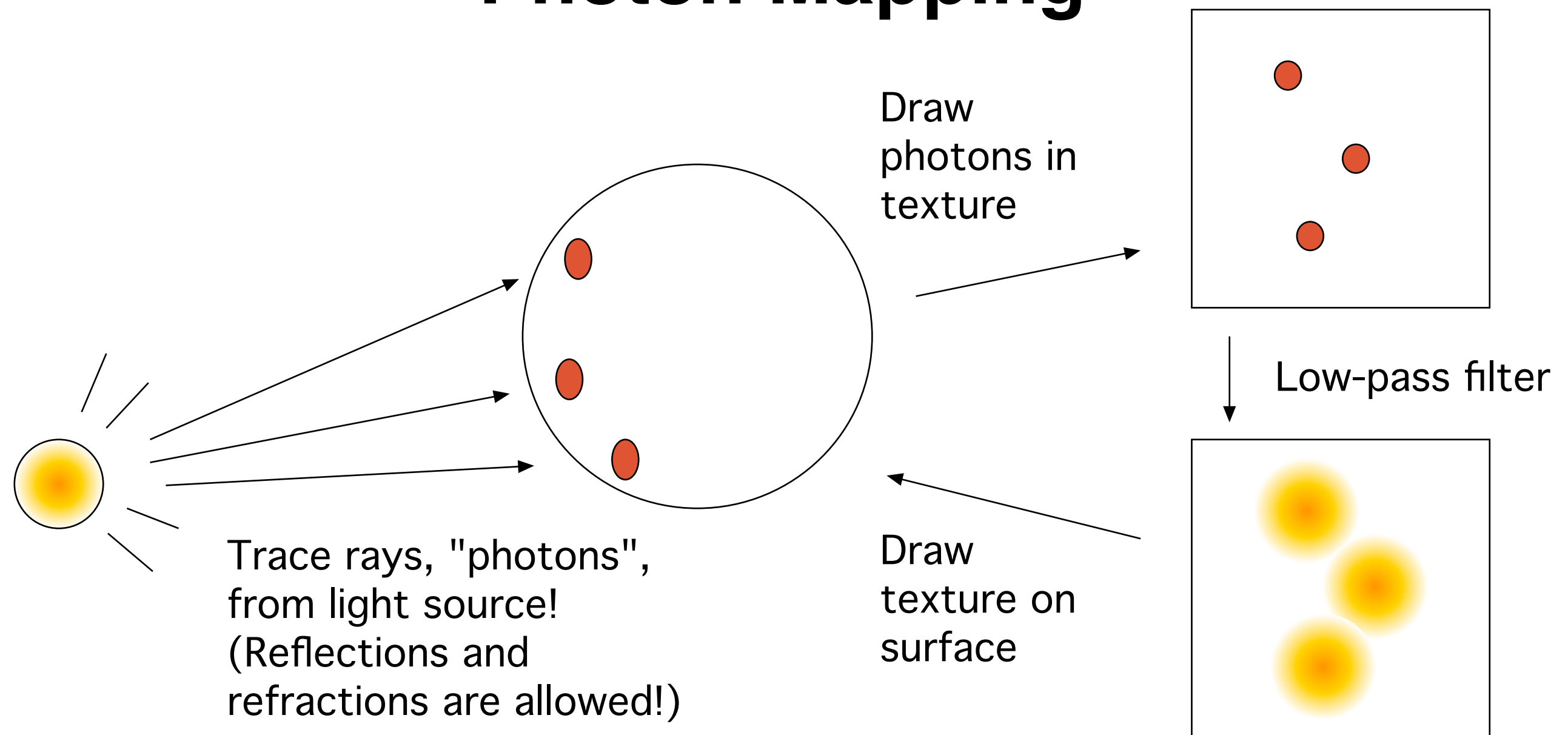
Saves information about every photon - allows specular surfaces!

Low-pass filter

Then render scene using these maps as surfaces.
Handles both diffuse and specular reflections!



Photon Mapping



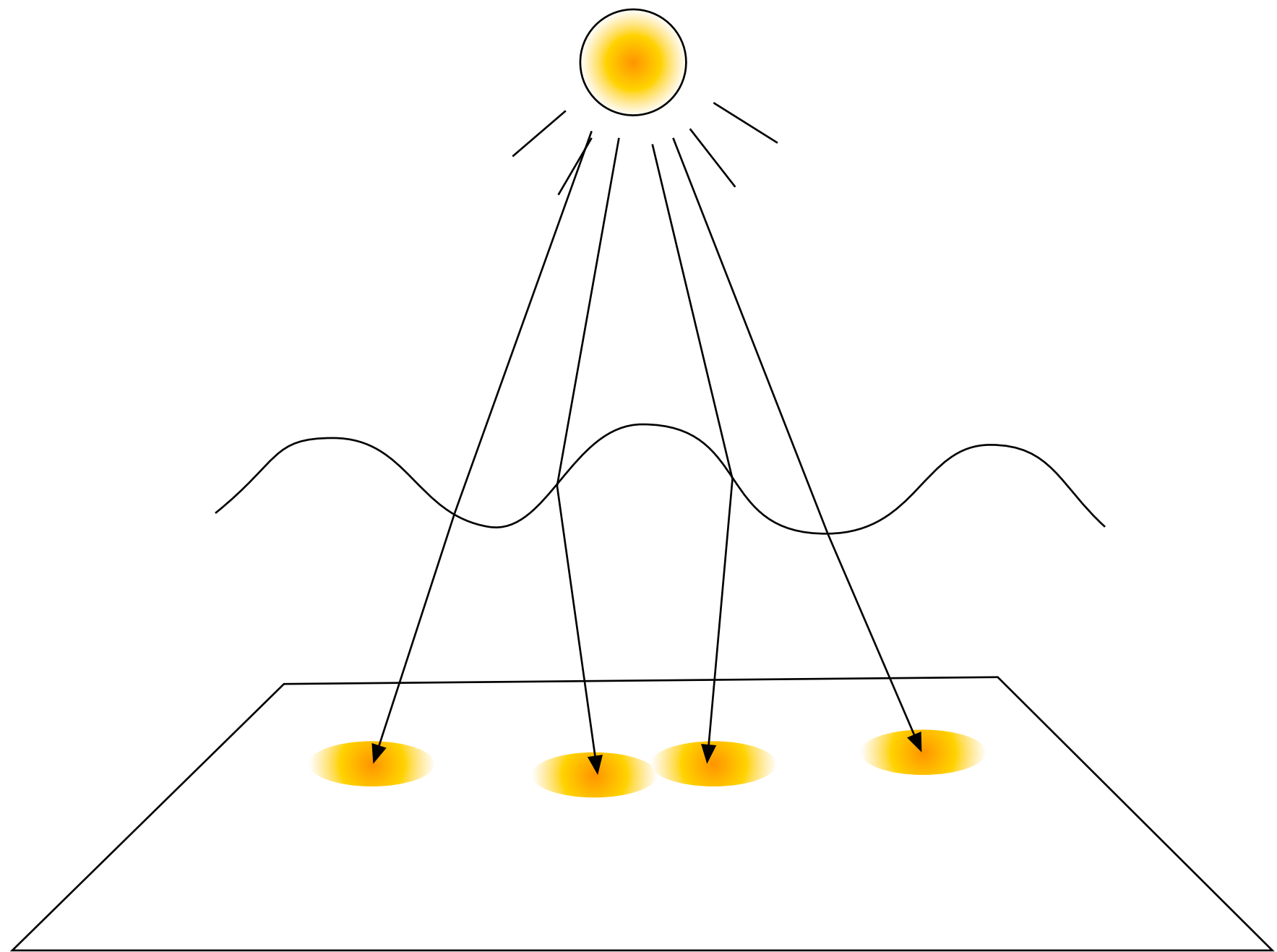


Caustics

Nice case for photon mapping

Bottom of lake only
surface to illuminate

(Harder if the lake bottom
is not flat or if there are
several objects to
illuminate.)

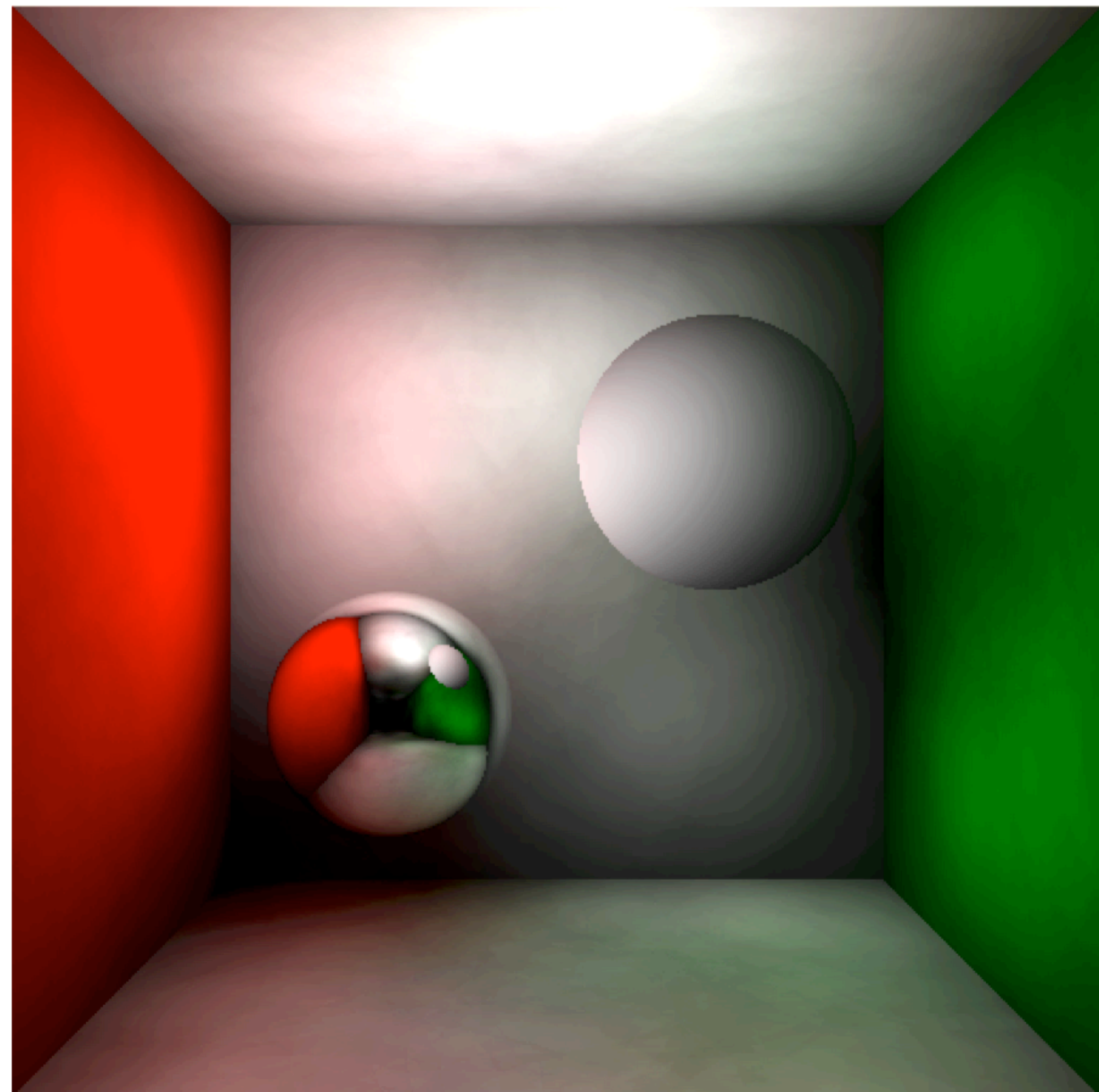




Photon Mapping Example

(The Schindler demo)

Typical features: Reflections,
caustics and diffuse
shadows





Path tracing

Similar to ray-tracing, but more rays.

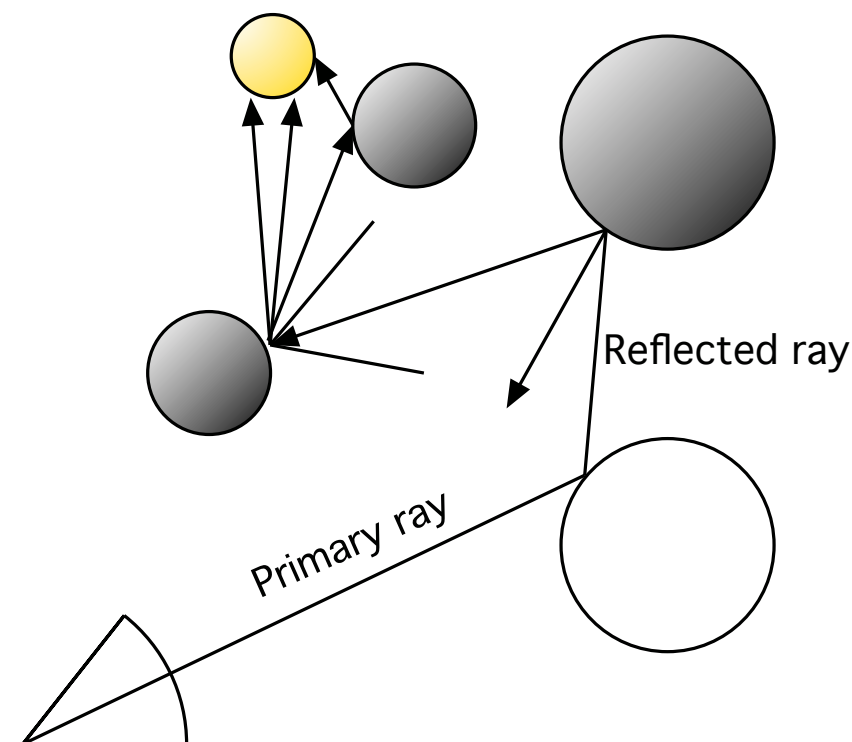
Cast rays to search for "light paths".

Essentially cast multiple "shadow rays" to find indirect light.



"Backwards" path tracing

When hitting that opaque surface, cast many "shadow rays" recursively and see if they hit a light source! Search for light paths!





"Forwards" path tracing

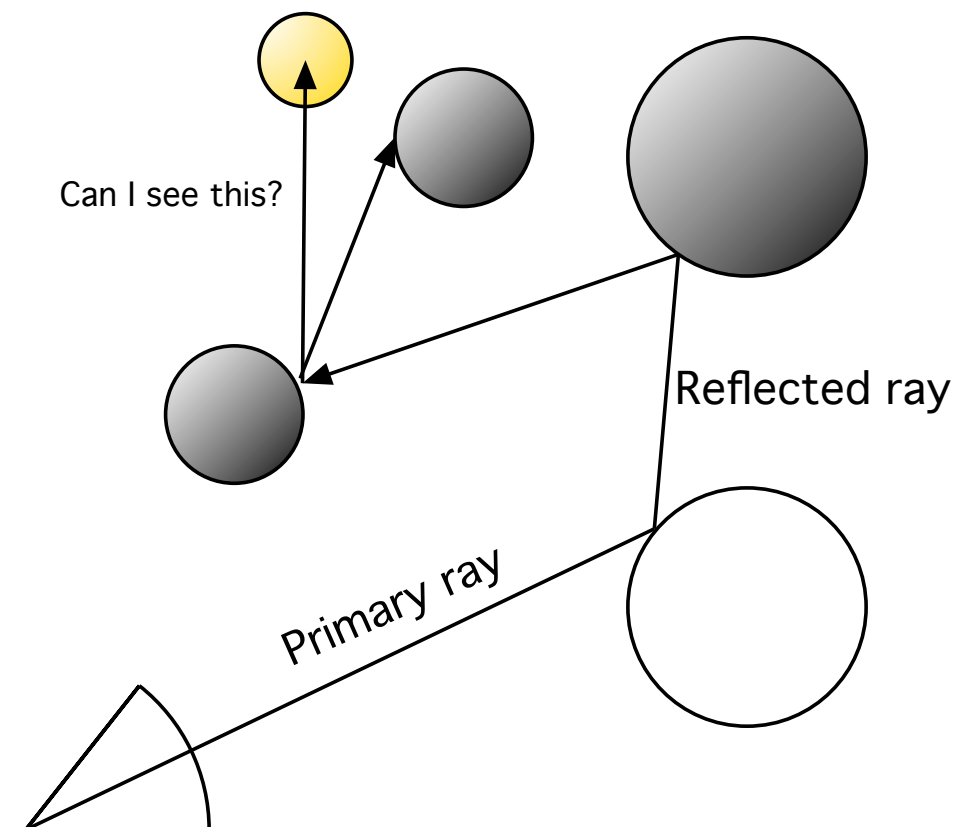
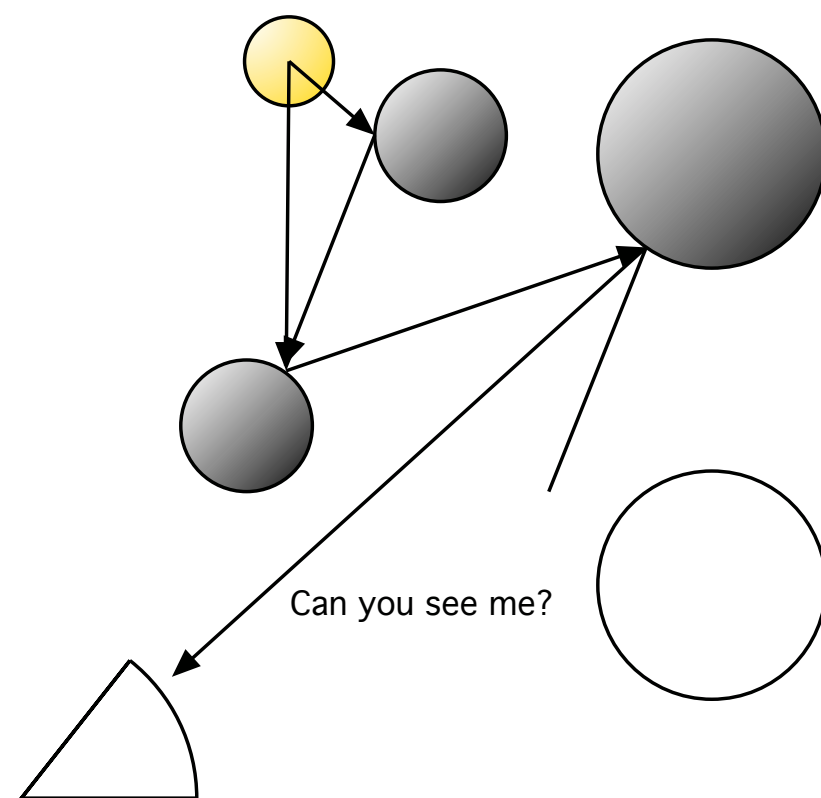
Instead of going from the camera, go from the light source, trace until you hit the camera.

Both cases can be accelerated by traditional "shadow rays" to detect that a surface has direct light or a direct path to the camera.



Shadow rays still relevant

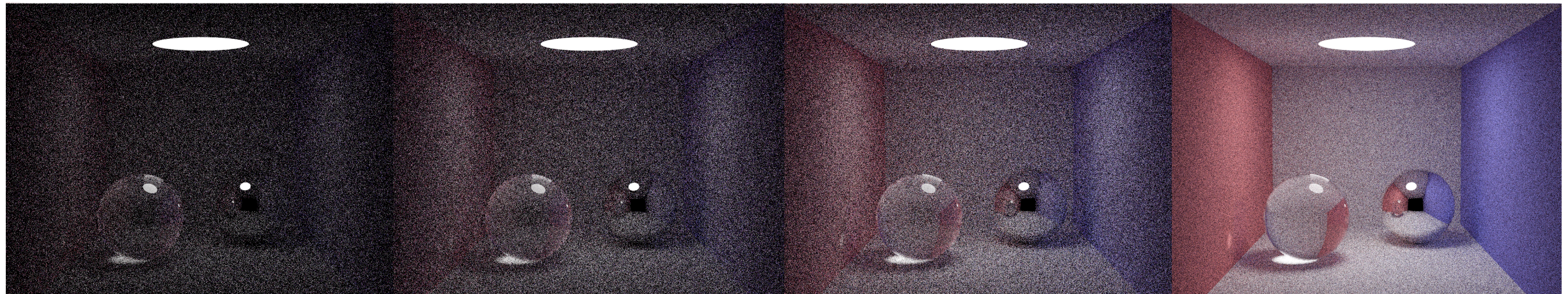
Both cases use traditional "shadow rays" to detect that a surface has direct light or a direct path to the camera.





Results (using Kevin Beason's "smallpt")

Small path tracer available on-line.



4 spp
(21s)

8 spp
(42s)

16 spp

64 spp

We need *many* rays to get a good result!
Beason reports thousands!
Parallel computing vital!



Beason's path tracer

Casts multiple primary rays. Secondary rays make random bounces but never multiply!

Uses shadow rays.

Uses light models for more realistic light.



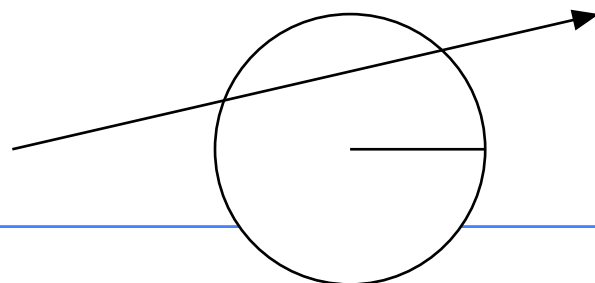
Beason likes spheres

All parts of the scene are spheres! The walls are large spheres!

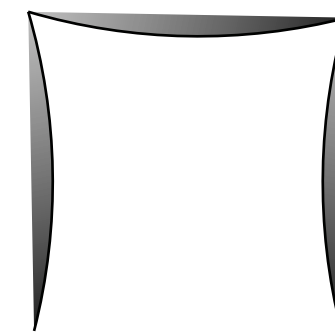
```
double intersect(const Ray &r)
const
{
    // returns distance, 0 if nohit
    Vec op = p-r.o;
    // Solve  $t^2 \cdot d \cdot d + 2 \cdot t \cdot (o-p) \cdot d + (o-p) \cdot (o-p) - R^2 = 0$ 
    double t, eps=1e-4, b=op.dot(r.d), det=b*b-op.dot(op)+rad*rad;
    if (det<0)
        return 0;
    else
        det=sqrt(det);
    return (t=b-det)>eps ? t : ((t=b+det)>eps ? t : 0);
}
```

// Scene description. Even the walls are spheres!

```
Sphere spheres[] =
{
    //Scene: radius, position, emission, color, material
    Sphere(1e5, Vec( 1e5+1,40.8,81.6), Vec(),Vec(.75,.25,.25),DIFF),//Left
    Sphere(1e5, Vec(-1e5+99,40.8,81.6),Vec(),Vec(.25,.25,.75),DIFF),//Rght
    Sphere(1e5, Vec(50,40.8, 1e5),    Vec(),Vec(.75,.75,.75),DIFF),//Back
    Sphere(1e5, Vec(50,40.8,-1e5+170), Vec(),Vec(),    DIFF),//Frnt
    Sphere(1e5, Vec(50, 1e5, 81.6),    Vec(),Vec(.75,.75,.75),DIFF),//Botm
    Sphere(1e5, Vec(50,-1e5+81.6,81.6),Vec(),Vec(.75,.75,.75),DIFF),//Top
    Sphere(16.5,Vec(27,16.5,47),    Vec(),Vec(1,1,1)*.999, SPEC),//Mirr
    Sphere(16.5,Vec(73,16.5,78),    Vec(),Vec(1,1,1)*.999, REFR),//Glas
    Sphere(600, Vec(50,681.6-.27,81.6),Vec(12,12,12), Vec(), DIFF)
    //Lite
};
```



As in the book but differently expressed.



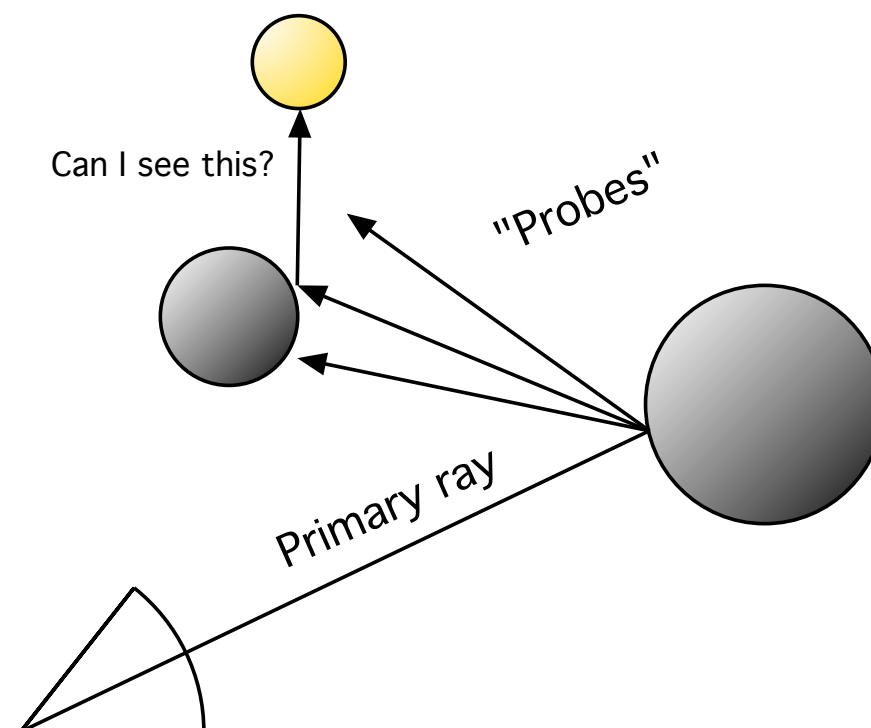


Path tracing in fragment shader

Hours to produce a noisy image? A bit better with openmp...?

But how about doing it on the GPU?

My first attempts: Simple path tracer:

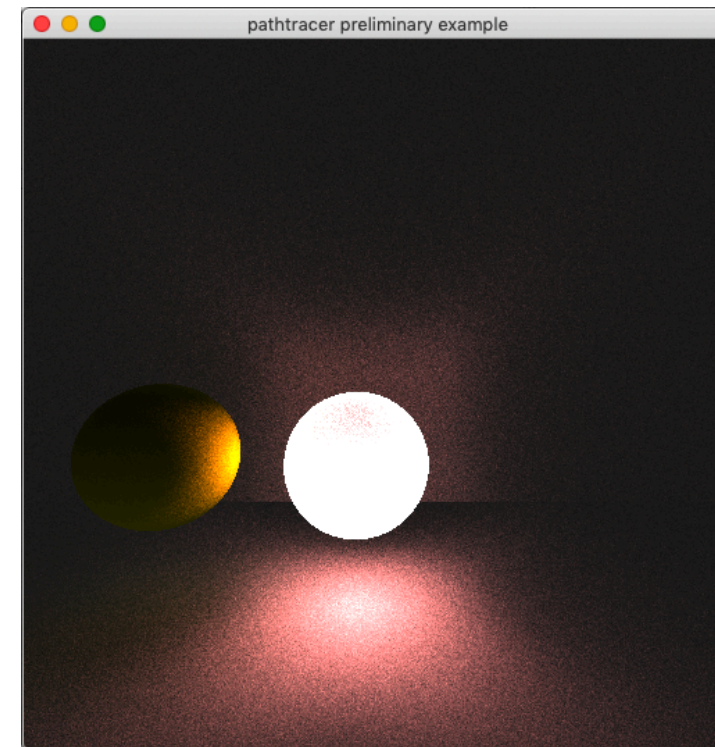
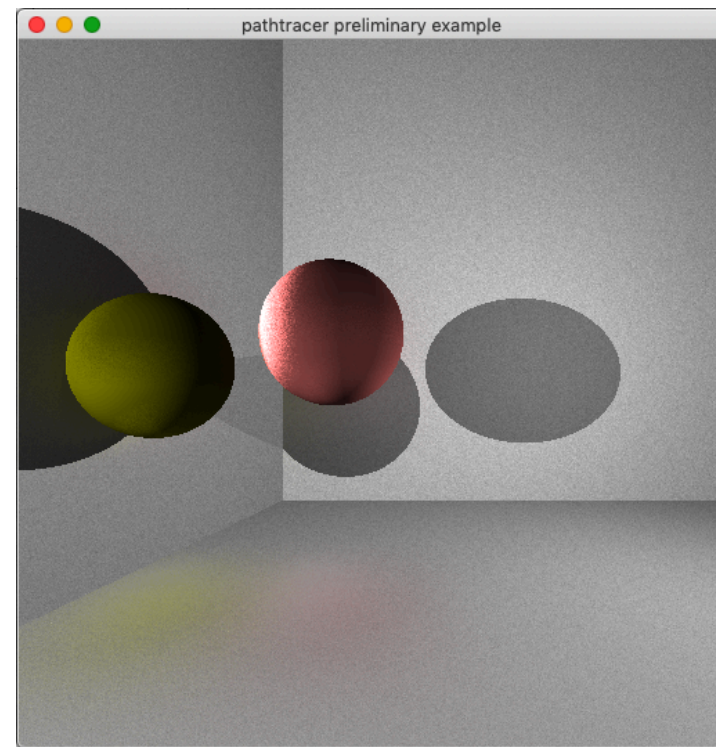




My simplified path tracer

Two variants: One with point lights, one with only emissive objects.

Pretty OK in real time (or almost) on my 650M. Cheating?





Summary

Ray-tracing:

Searches for surfaces and direct light. Good for shiny surfaces, transparency etc. “Hard” images.

Radiosity:

Models light patch to patch. Good for realistic images of diffuse surfaces. Can not handle specular reflections!

Photon Mapping: accumulates light in surfaces

Path tracing: searches in multiple directions for light paths