



Vulkan

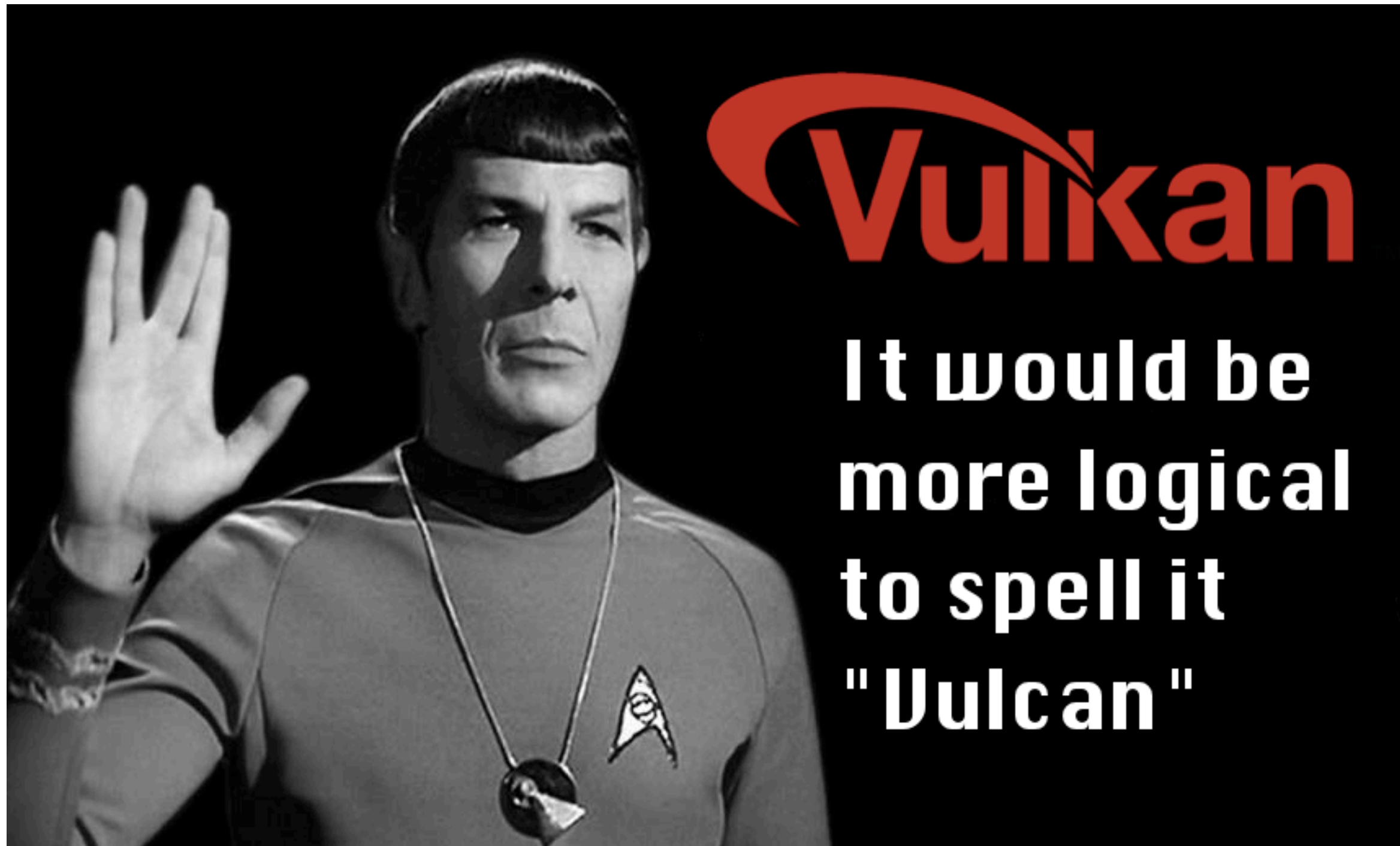
a.k.a. gINext

Did the future just arrive?

”Next-generation OpenGL”?



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What? When? Where?

**New API, development started in 2014,
released 16th february this year.**

**Open specification - don't expect it to hit all
platforms immediately!**

**Big players try their own solutions. Apple has
"Metal" instead. MS works though DirectX.**



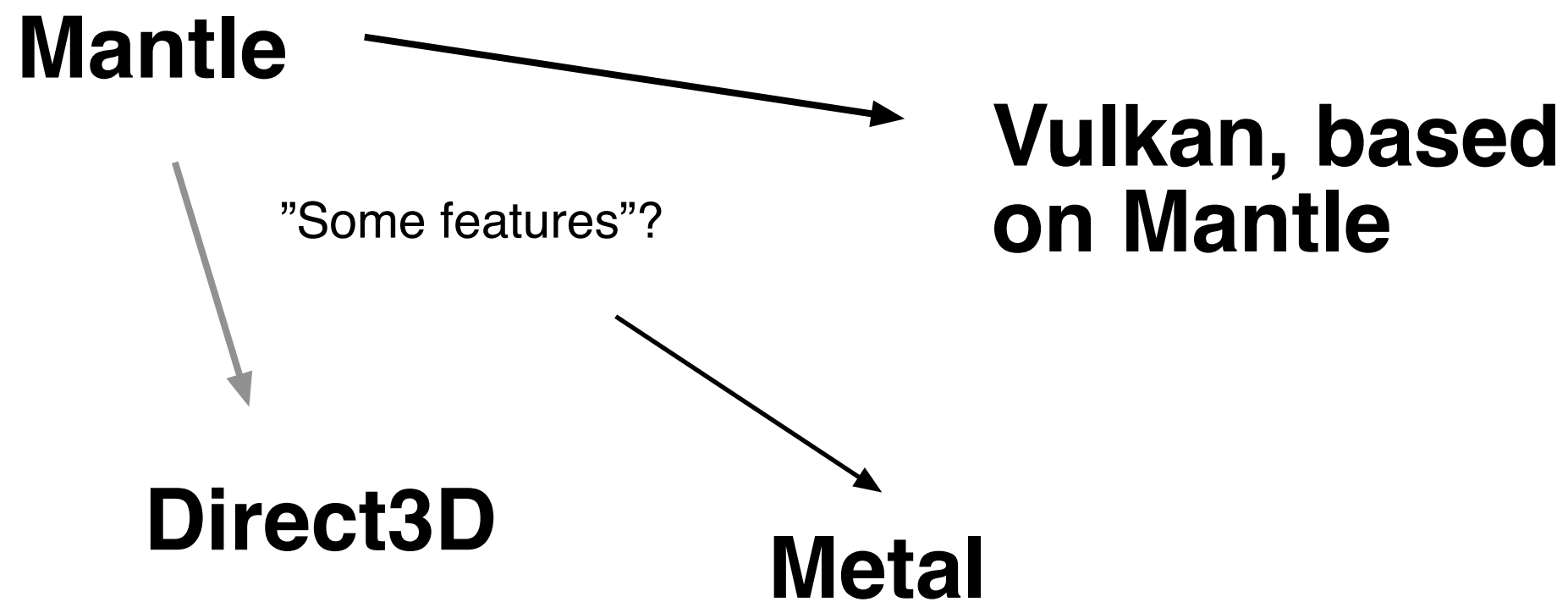
Background - AMD Mantle

Low-level API for more direct control of the GPU.





AMD Mantle: Dead but successful!





So what is the point to us?

Promises:

- **Lower driver overhead**
- **More multi-thread friendly than OpenGL**
- **Shaders can be compiled to intermediary binary format (SPIR-V)**
- **Open front-end for shader compilers?**



Show me some code!

This is how you draw a triangle:



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```
#ifndef _MSC_VER
#define _ISO_C11_SOURCE /* for aligned_alloc() */
#endif

#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <stdbool.h>
#include <assert.h>

#ifdef _WIN32
#pragma comment(linker, "/subsystem:windows")
#define APP_NAME_STR_LEN 80
#endif // _WIN32

#include <vulkan/vulkan.h>

#define DEMO_TEXTURE_COUNT 1
#define VERTEX_BUFFER_BIND_ID 0
#define APP_SHORT_NAME "tri"
#define APP_LONG_NAME "The Vulkan Triangle Demo Program"

#define ARRAY_SIZE(a) (sizeof(a) / sizeof(a[0]))

#if defined(NDEBUG) && defined(__GNUC__)
#define U_ASSERT_ONLY __attribute__((unused))
#else
#define U_ASSERT_ONLY
#endif

#ifdef _WIN32
#define ERR_EXIT(err_msg, err_class)
do {
    MessageBox(NULL, err_msg, err_class, MB_OK);
    exit(1);
} while (0)
#else // _WIN32
#define ERR_EXIT(err_msg, err_class)
do {
    printf(err_msg);
    fflush(stdout);
    exit(1);
} while (0)
#endif // _WIN32

#define GET_INSTANCE_PROC_ADDR(inst, entrypoint)
{
    demo->fp##entrypoint =
    (PFN_vk##entrypoint)vkGetInstanceProcAddr(inst, "vk" #entrypoint);
    if (demo->fp##entrypoint == NULL) {
        ERR_EXIT("vkGetInstanceProcAddr failed to find vk" #entrypoint,
                "vkGetInstanceProcAddr Failure");
    }
}

#define GET_DEVICE_PROC_ADDR(dev, entrypoint)
{
    demo->fp##entrypoint =
    (PFN_vk##entrypoint)vkGetDeviceProcAddr(dev, "vk" #entrypoint);
    if (demo->fp##entrypoint == NULL) {
        ERR_EXIT("vkGetDeviceProcAddr failed to find vk" #entrypoint,
                "vkGetDeviceProcAddr Failure");
    }
}

struct texture_object {
    VkSampler sampler;

    VkImage image;
    VkImageLayout imageLayout;

    VkDeviceMemory mem;
    VkImageView view;
    int32_t tex_width, tex_height;
};

VKAPI_ATTR VkBool32 VKAPI_CALL
dbgFunc(VkFlags msgFlags, VkDebugReportObjectTypeEXT objType,
        uint64_t srcObject, size_t location, int32_t msgCode,
        const char *pLayerPrefix, const char *pMsg, void *pUserData) {
    char *message = (char *)malloc(strlen(pMsg) + 100);

    assert(message);

    if (msgFlags & VK_DEBUG_REPORT_ERROR_BIT_EXT) {
        sprintf(message, "ERROR: [%s] Code %d : %s", pLayerPrefix, msgCode,
                pMsg);
    } else if (msgFlags & VK_DEBUG_REPORT_WARNING_BIT_EXT) {
        sprintf(message, "WARNING: [%s] Code %d : %s", pLayerPrefix, msgCode,
                pMsg);
    } else {
        return false;
    }
}

#ifdef _WIN32
MessageBox(NULL, message, "Alert", MB_OK);
#else
printf("%s\n", message);
fflush(stdout);
#endif
free(message);

/*
 * false indicates that layer should not bail-out of an
 * API call that had validation failures. This may mean that the
 * app dies inside the driver due to invalid parameter(s).
 * That's what would happen without validation layers, so we'll
 * keep that behavior here.
 */
return false;
}

typedef struct _SwapchainBuffers {
    VkImage image;
    VkCommandBuffer cmd;
    VkImageView view;
} SwapchainBuffers;

struct demo {
#ifdef _WIN32
#define APP_NAME_STR_LEN 80
HINSTANCE connection; // hInstance - Windows Instance
char name[APP_NAME_STR_LEN]; // Name to put on the window/icon
HWND window; // hWnd - window handle
#else // _WIN32
xcb_connection_t *connection;
xcb_screen_t *screen;
xcb_window_t window;
xcb_intern_atom_reply_t *atom_wm_delete_window;
#endif // _WIN32
VkSurfaceKHR surface;
bool prepared;
bool use_staging_buffer;

VkInstance inst;
VkPhysicalDevice gpu;
VkDevice device;
VkQueue queue;
VkPhysicalDeviceProperties gpu_props;
VkQueueFamilyProperties *queue_props;
uint32_t graphics_queue_node_index;

uint32_t enabled_extension_count;
uint32_t enabled_layer_count;
char *extension_names[64];
char *device_validation_layers[64];

int width, height;
VkFormat format;
VkColorSpaceKHR color_space;

PFN_vkGetPhysicalDeviceSurfaceSupportKHR
fpGetPhysicalDeviceSurfaceSupportKHR;
PFN_vkGetPhysicalDeviceSurfaceCapabilitiesKHR
fpGetPhysicalDeviceSurfaceCapabilitiesKHR;
PFN_vkGetPhysicalDeviceSurfaceFormatsKHR
fpGetPhysicalDeviceSurfaceFormatsKHR;
PFN_vkGetPhysicalDeviceSurfacePresentModesKHR
fpGetPhysicalDeviceSurfacePresentModesKHR;
PFN_vkCreateSwapchainKHR fpCreateSwapchainKHR;
PFN_vkDestroySwapchainKHR fpDestroySwapchainKHR;
PFN_vkGetSwapchainImagesKHR fpGetSwapchainImagesKHR;
PFN_vkAcquireNextImageKHR fpAcquireNextImageKHR;
PFN_vkQueuePresentKHR fpQueuePresentKHR;
uint32_t swapchainImageCount;
VkSwapchainKHR swapchain;
SwapchainBuffers *buffers;

VkCommandPool cmd_pool;

struct {
    VkFormat format;

    VkImage image;
    VkDeviceMemory mem;
    VkImageView view;
} depth;

struct texture_object textures[DEMO_TEXTURE_COUNT];

struct {
    VkBuffer buf;
    VkDeviceMemory mem;

    VkPipelineVertexInputStateCreateInfo vi;
    VkVertexInputBindingDescription vi_bindings[1];
    VkVertexInputAttributeDescription vi_attr[2];
} vertices;

VkCommandBuffer setup_cmd; // Command Buffer for initialization commands
VkCommandBuffer draw_cmd; // Command Buffer for drawing commands
VkPipelineLayout pipeline_layout;
VkDescriptorSetLayout desc_layout;
VkPipelineCache pipelineCache;
VkRenderPass render_pass;
VkPipeline pipeline;

VkShaderModule vert_shader_module;
VkShaderModule frag_shader_module;

VkDescriptorPool desc_pool;
VkDescriptorSet desc_set;

VkFramebuffer *framebuffers;

VkPhysicalDeviceMemoryProperties memory_properties;

bool validate;
PFN_vkCreateDebugReportCallbackEXT CreateDebugReportCallback;
PFN_vkDestroyDebugReportCallbackEXT DestroyDebugReportCallback;
VkDebugReportCallbackEXT msg_callback;
PFN_vkDebugReportMessageEXT DebugReportMessage;

float depthStencil;
float depthIncrement;

bool quit;
uint32_t current_buffer;
uint32_t queue_count;
};

// Forward declaration:
static void demo_resize(struct demo *demo);

static bool memory_type_from_properties(struct demo *demo, uint32_t typeBits,
                                       VkFlags requirements_mask,
                                       uint32_t *typeIndex) {
    // Search memtypes to find first index with those properties
    for (uint32_t i = 0; i < 32; i++) {
        if ((typeBits & 1) == 1) {
            // Type is available, does it match user properties?
            if ((demo->memory_properties.memoryTypes[i].propertyFlags &
                requirements_mask) == requirements_mask) {
                *typeIndex = i;
                return true;
            }
        }
        typeBits >>= 1;
    }
    // No memory types matched, return failure
    return false;
}

static void demo_flush_init_cmd(struct demo *demo) {
    VkResult U_ASSERT_ONLY err;

    if (demo->setup_cmd == VK_NULL_HANDLE)
        return;

    err = vkEndCommandBuffer(demo->setup_cmd);
    assert(!err);

    const VkCommandBuffer cmd_bufs[] = {demo->setup_cmd};
    VkFence nullFence = {VK_NULL_HANDLE};
    VkSubmitInfo submit_info = {sType = VK_STRUCTURE_TYPE_SUBMIT_INFO,
                                .pNext = NULL,
                                .waitSemaphoreCount = 0,
                                .pWaitSemaphores = NULL,
                                .pWaitDstStageMask = NULL,
                                .commandBufferCount = 1,
                                .pCommandBuffers = cmd_bufs,
                                .signalSemaphoreCount = 0,
                                .pSignalSemaphores = NULL};

    err = vkQueueSubmit(demo->queue, 1, &submit_info, nullFence);
    assert(!err);

    err = vkQueueWaitIdle(demo->queue);
    assert(!err);

    vkFreeCommandBuffers(demo->device, demo->cmd_pool, 1, cmd_bufs);
    demo->setup_cmd = VK_NULL_HANDLE;
}

static void demo_set_image_layout(struct demo *demo, VkImage image,
                                  VkImageAspectFlags aspectMask,
                                  VkImageLayout old_image_layout,
                                  VkImageLayout new_image_layout,
                                  VkAccessFlagBits srcAccessMask) {
    VkResult U_ASSERT_ONLY err;
}

```

These are the first
≈300 lines of a file
with 2448 lines...
should I continue?



What kind of mind-boggling bullsh*t is this?

Same feeling going from OpenGL 2 to 3...

- **Low-level**
- **Detailed control over buffers, processes, queues, devices...**

This comes for a cost!



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The main advantage is a multi-thread friendly design!

Also more detailed hardware control.

Future challenge: To abstract this to suitable simpler layers in order to make it managable.



Earlier efforts like this

- **3dfx Glide (?)**
- **Apple RAVE**
- **...but isn't this what DirectX and OpenGL was about from the start...?**

So what is this? An up-to-date effort for today's hardware.



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Important: This does NOT mean that OpenGL will be discontinued in the foreseeable future! Vulkan is a lower-level complement, not a replacement!

**Much will happen the coming year!
Computer graphics is still moving fast...**



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