



Information Coding / Computer Graphics, ISY, LiTH

# Lecture 10

**Object representation:  
Quadrics  
Splines  
Bézier patches**

**(Chapter 8.5-)**



# 3D object representation

In order of importance:

- Polyhedra
  - Bi-cubic parametric patches
- Procedural representation, fractals
  - Constructive solid geometry
- Implicit representation by quadrics

plus...



# 3D object representation

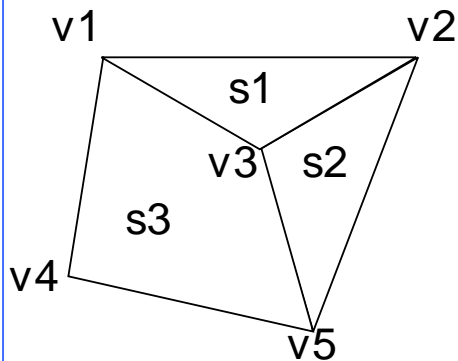
## Advanced representations:

- Density volumes
- Point-based representations
  - Level sets



# Polyhedra representations

**Dominant in real-time graphics**  
**Less suited for off-line rendering**



## Vertex table

$v1 = x1, y1, z1$

$v2 = x2, y2, z2$

$v3 = x3, y3, z3$

$v4 = x4, y4, z4$

$v5 = x5, y5, z5$

## Surface table

$s1 = v1, v2, v3$

$s2 = v2, v5, v3$

$s3 = v1, v3, v5, v4$



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## **Making our own models**

**Many powerful commercial tools (Maya, 3D Studio Max etc)**

**Free tools (nice for project work):**

**Blender  
Wings3D**



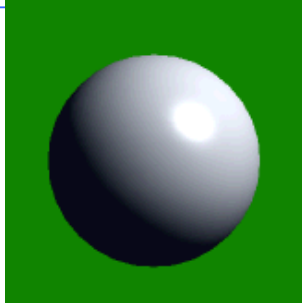
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## Implicit representations: Quadric surfaces

Surfaces represented by second-degree  
polynomials

**Sphere Ellipsoid Torus Cone**





# Sphere

Equation:

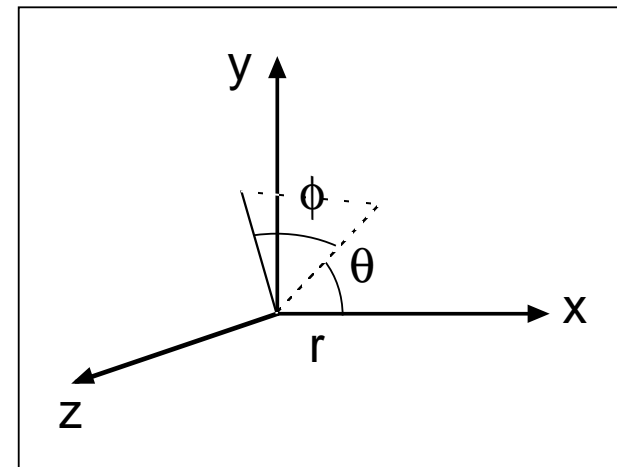
$$x^2 + y^2 + z^2 = r^2$$

Parametric:

$$x = r \cos \phi \cos \theta$$

$$y = r \cos \phi \sin \theta$$

$$z = r \sin \phi$$



$$-\pi/2 \leq \phi \leq \pi/2$$

$$-\pi \leq \theta \leq \pi$$



## Ellipsoid

Equation:

$$x^2/r_x^2 + y^2/r_y^2 + z^2/r_z^2 = 1$$

Parametric:

$$x = r_x \cos \phi \cos \theta$$

$$y = r_y \cos \phi \sin \theta$$

$$z = r_z \sin \phi$$

$$\begin{aligned} -\pi/2 &\leq \phi \leq \pi/2 \\ -\pi &\leq \theta \leq \pi \end{aligned}$$





# Torus

Rotate a circle around an axis

Equation:

$$(r - \sqrt{x^2/r_x^2 + y^2/r_y^2})^2 + z^2/r_z^2 = 1$$

Parametric:

$$x = r_x (r + \cos \phi) \cos \theta$$

$$y = r_y (r + \cos \phi) \sin \theta$$

$$z = r_z \sin \phi$$

$$-\pi \leq \phi \leq \pi$$

$$-\pi \leq \theta \leq \pi$$



## Quadric surfaces

**Limited possibilities. Slightly more freedom can be achieved with “superquadrics”**

**Many quadric surfaces are hard to rotate freely**

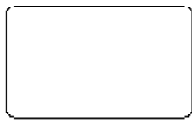
**Rendering packages replace them with meshes (polygons or curved surfaces)**

**Are quadrics outdated?**



# Superquadrics:

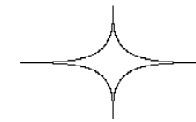
## Example: Superellipse



**s = 0.1**

$$\begin{aligned}x &= r_x \cos^s \theta \\ y &= r_y \sin^s \theta\end{aligned}$$

$$\left(\frac{x}{r_x}\right)^{2/s} + \left(\frac{y}{r_y}\right)^{2/s} = 1$$



**s = 5.0**



**s = 0.5**



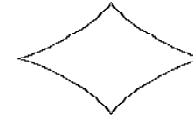
**s = 1.0**



**s = 1.5**



**s = 2.0**



**s = 2.5**



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# Quadric surfaces in OpenGL

**Calls that approximate quadric surfaces by polygons**

**glutWireSphere/glutSolidSphere**

**glutWireCone/glutSolidCone**

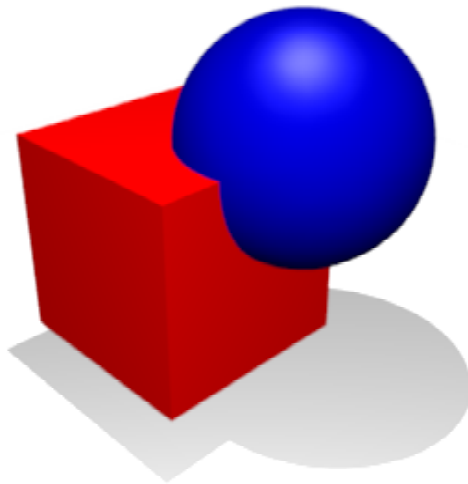
**glutWireTorus/glutSolidTorus**

(Not for GL3+)

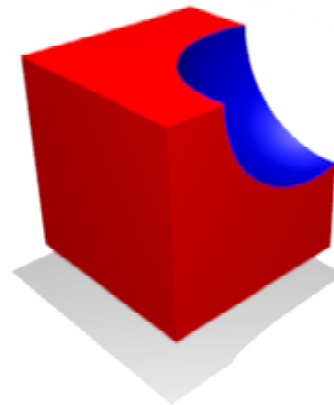


# Constructive Solid Geometry

Define shapes by Boolean operations on other shapes



**Union  
(a or b)**



**Difference (a  
and not b)**



**Intersection  
(a and b)**

Images from  
Wikipedia



# Constructive Solid Geometry

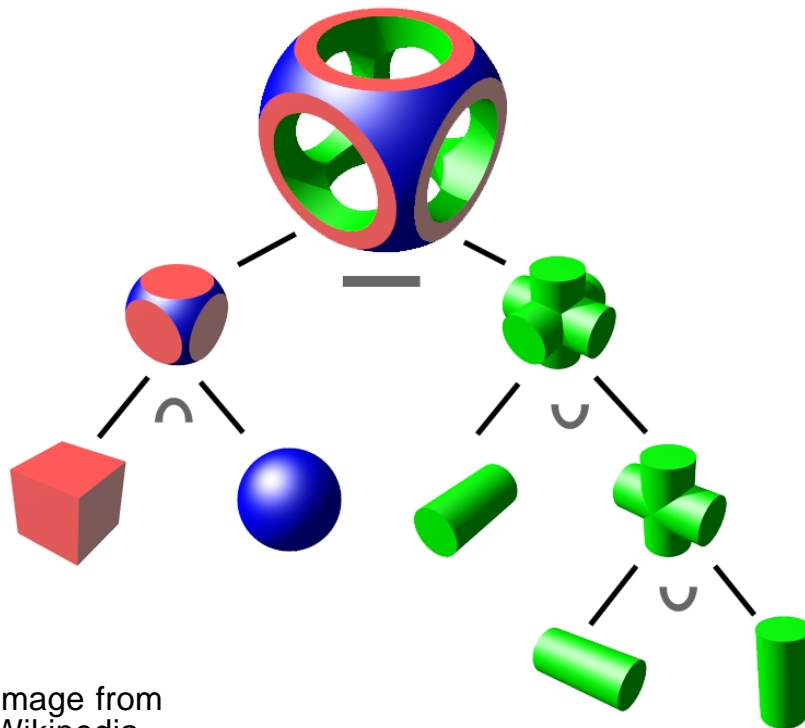


Image from  
Wikipedia

**Good shapes in -  
somewhat useful.**

**Limited shapes in -  
limited results.**